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**Energy oriented Center of Excellence
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**D1.3 M28
Application Support Outcome**

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1. Overview

Deliverable D1.3 reports on all activities concerning application support, including applications the consortium decided to give support to prior to the start of the project, but also applications which partners requested work on during the course of the project. The document therefore represents a follow-up to D1.1 on the 6 triggered applications reported therein, but is extended by a further 5 applications that were also subjected to the same scrutiny. In many cases significant improvements were achieved after the initial performance analysis.

Table 1: Contribution of Deliverable D1.3 to impacts 1.1, 1.2, 1.3 and 3.1

Code	Lead institute	Performance gain (%)	CPUh saved in 2017 (MCPUh)	EoCoE tools usage
Alya	BSC	10	0.4	4
Eirene	FZJ	-	-	
Esias	FZJ	23	15	
Gysela	CEA	65	40	2
MDFT		1200	ε	
Metalwalls	CEA	350	5	
PVnegf		-	-	
Parflow	FZJ	<10	N/A	
Shemat	RWTH Aachen	7	ε	
SolarNowcast		540	ε	
Telemac		18	ε	
Total	-	-	60.4	6

Table 1 is an update of the table in D1.1 on triggered application support with updated performance gain and the CPU time saved in 2017, where an estimated total of 60 MCPUh could be saved by the groups using these applications. So impact 1.1 whose goal was to save 50 MCPUh/year was reached once again. ESIAS and Gysela are the main contributors here as they use significant CPU time quotas each year. Even moderate performance improvements on these codes compared to some others have a strong impact on the better usage of underlying computing infrastructures. The very large performance gain of MDFT and Solar Nowcast were possible because these two applications were serial or with an inefficient OpenMP implementation. Support activities on these two codes enabled them to leverage the full computing power of a single node. Similarly to SHEMAT and Telemac, MDFT and Solar Nowcast did not save a lot of Core-hours because they do not run on very large CPU time allocations. However, these performance increase had a big impact on the daily routine of the scientists and the type of problems they were able to treat. Alya benefitted from a small acceleration thanks to the optimisation of the matrix assembly part of the code. As the main bottleneck is related to linear algebra, the Alya team is in strong contact with the linear algebra team of the transversal basis and could test four different packages in the code. Finally Metalwalls has been accelerated by a factor x3.5 with only single core and single node optimisations. This means the code runs faster on the same amount of computing resources, thus enabling more numerical experiments with similar computing time.

2. Alya

The Alya System is the BSC simulation code for multi-physics problems. It addresses problems of incompressible and compressible flows, non-linear solid mechanics, species transport equations, excitable media, thermal flows, N-body collisions ...

The application submitted to EoCoE is a coupling of 2 modules: NASTIN, a FE solver for incompressible Navier Stokes and TURBUL, a FE solver for turbulence equations. It applies to wind simulation for wind farms.

It is pure MPI. Each module contains a matrix assembly part, that is perfectly distributed, and a solver part that requires communications at each iteration.

2.1 Performance metrics

Code team:

- Herbert Owen (BSC), WP2
- Guillaume Houzeaux (BSC), WP2
- Yacine Ould Rouis (MdlS), WP1

Benchmark characteristics:

Domain size	1 Million elements
Number of timesteps	30
Compile options	-O2 -xHost -DNDIMEPAR
Resources	1 node on JURECA (24 cores)
IO details	default sequential IOs, parallel hdf5 output is tested in a second step
Type of run	the size of benchmark aims to be faithful to the regular use of the program, in terms of number of elements per node

2.2 Application support

Code optimization for the matrix construction

Activity type	WP1 support
Contributors	Y. Ould-Rouis (WP1), H. Owen (WP2), G. Houzeaux (WP2)

The application support on Alya focuses exclusively on the matrix construction parts of the two modules involved in the application submitted to EoCoE: NASTIN and TURBUL. The work has been conducted based on the conclusions of the performance evaluation, with a strong collaboration and communication with the Alya team.

In the following, I describe point-by-point the different actions and steps that brought improvements to the code's performance.

1. Detection of loop level pathologies using VTune.
2. Loops reordering: in order to take profit of data locality in the cache by contiguous accesses.

Table 2: Performance metrics for Alya on the JURECA HPC system.

	Metric name	original	after App Support
Global	Total Time (s)	385.4	346.3
	Time IO (s)	0.5	0.4
	Time MPI (s)	99.7	90.1
	Memory vs Compute Bound	1.3	1.3
IO	IO Volume (MB)	2449.9	2449.9
	Calls (nb)	97655	97573
	Throughput (MB/s)	5069.0	6423.6
	Individual IO Access (kB)	4.9	4.9
MPI	P2P Calls (nb)	154493	151985
	P2P Calls (s)	4.1	4.3
	Collective Calls (nb)	100071	98609
	Collective Calls (s)	0.7	0.8
	Synchro / Wait MPI (s)	94.2	84.9
	Ratio Synchro / Wait MPI	94.5	94.2
	Message Size (kB)	15.4	15.4
	Load Imbalance MPI	20.6	19.9
Mem	Memory Footprint (B)	584 mB	584 mB
	Cache Usage Intensity	N.A.	N.A.
	RAM Avg Throughput (GB/s)	N.A.	N.A.
Core	IPC	N.A.	N.A.
	Runtime without vectorisation (s)	383.2	362.9
	Vectorisation efficiency	1.0	1.0
	Runtime without FMA (s)	392.7	353.5
	FMA efficiency	1.0	1.0

3. Refactoring of potential redundant calculations.
4. Helping vectorization: by data restructuring and getting rid of dependencies inside inner loops.
For example: in *nsi_elmmat*, building elauu matrix as 9 distinct arrays that are assembled together at the end allowed an 11% improvement of this routine, in addition to the 15% obtained with the 2 previous steps.
5. Memory padding (or data structure alignment). tested only on some local array variables.
6. Eliminating while/conditional loops.
7. Element to sparse matrix pre-mapping: This step was motivated by the observation that *csruse* subroutine contains a very costly while loop (2.7% of total CPU time), c.f. Figure 1. This subroutine is used in turbul matrix assembly, to copy the coefficients calculated by element into a larger sparse matrix, and the while loop finds for each coefficient of indices (inode, jnode) in a local element's matrix the right index 'izsol' in the CSR matrix. Same is done other way around, and in other parts/modules.
The idea is to calculate this relation once in a pre-processing step.

Table 3: Detailed time performance on JURECA - original performances.

mode	CPU_time	Start_ops	NSI_total	NSI_mat	NSI_sol	TUR_total	TUR_mat	TUR_sol
ref	384.66	37.9	203.57	67.24	132.27	125.46	87.87	32.21
darshan	385.34	37.48	204.16	67.19	132.68	125.79	87.6	32.25
scatter	311.28	36.15	148.91	65.71	79.04	111.22	84.81	20.33
compact	396.5	35.89	207.43	68.42	134.05	130.53	88.75	36.35
memory	384.95	38.17	202.98	67.12	131.99	125.96	88.35	32.22
scalasca	477.1	49.96	213.28	76.08	133.24	187.04	149.02	32.97
no-fma	392.03	38.44	207.12	70.93	132.15	127.32	89.76	32.35
no-vec	381.93	38.94	199.97	60.92	134.94	125.83	85.25	34.95

Table 4: Detailed time performance on JURECA - after matrix assemblies optimization.

mode	CPU_time	Start_ops	NSI_total	NSI_mat	NSI_sol	TUR_total	TUR_mat	TUR_sol
ref	345.65	37.79	180.85	43.85	130.4	108.29	68.04	31.61
darshan	346.04	37.16	181.72	44.04	130.37	109.66	67.95	31.6
scatter	279.39	35.97	131.09	43.37	79.23	96.62	66.27	20.32
compact	351.33	36.14	184.36	44.46	131.54	113.0	68.8	34.72
memory	348.77	38.4	182.63	44.04	130.92	108.88	67.65	31.9
scalasca	424.13	49.35	190.1	51.91	131.02	155.94	114.58	32.15
no-fma	352.59	37.86	185.82	47.89	130.43	110.44	69.1	31.66
no-vec	361.56	40.01	193.52	56.74	128.78	110.75	68.84	31.99

- advantages: avoid a costly redundant while loop.
- neutral: it won't solve the problem of indirections when writing in the sparse matrix.
- negative: an estimated memory cost of $8*8*integer_size$ for each element. With long integers (8 bytes), this means 50MBytes for each 100 000 elements. This is reasonable when compared to the total memory footprint.

Results

The core level optimization has been successful in securing 10 to 13% gain in total, depending on the hardware. The Figure 2 shows the evolution of the performance for the successive versions of Alya. The stage 0 shows the original times. Stages 1 to 6 show the results of steps 2 to 6 described above, applied to the NASTIN matrix assembly. Stages 7 to 11 are the results of steps 2 to 6 applied to the TURBUL module combined with other efforts.

The final results on JURECA are as follows:

- NASTIN matrix assembly: 35% improvement.
- TURBUL matrix assembly: 22% improvement.
- Total: 10% global improvement.

The methodology and the interesting results of this work generated new interests in the Alya team, that triggered new optimization efforts on the other modules composing Alya.

In early 2018, we updated the Alya performance evaluation JUBE script to the latest state

Sour... Line	Source	CPU Time: Total				CPU Time: Self				Effective Time by Utilization			
		Effective...	Spin Ti...	O...	O...	Idle	Poor	Ok	Ideal	Over	Co.	Oth..	Oth..
81	amatr(idof2,izsol) = amatr(idof2,izsol) + elmat(ievat,jevat)												
82													
83	end do												
84	end do												
85													
86	else if(iprob==2) then												
87													
88	if(ndofn==1) then	0.0%	0.0%	0.0%	0.0%	0.008s					0s	0s	0s
89	!												
90	! General case: 1 unknown												
91	!												
92													
93													
94	do inode = 1,pnode	0.0%	0.0%	0.0%	0.0%	0.008s					0s	0s	0s
95	ipoin = inode(inode)	0.0%	0.0%	0.0%	0.0%	0.012s					0s	0s	0s
96	do jnode = 1,pnode	0.3%	0.0%	0.0%	0.0%	1.148s					0s	0s	0s
97	jpoint = inode(jnode)	0.0%	0.0%	0.0%	0.0%	0.024s					0s	0s	0s
98	izsol = r_sol(jpoint)	0.1%	0.0%	0.0%	0.0%	0.256s					0s	0s	0s
99	jcolu = c_sol(izsol)	0.1%	0.0%	0.0%	0.0%	0.592s					0s	0s	0s
100	do while(jcolu /= jpoint .and. izsol < r_sol(jpoint+1)-1)	2.7%	0.0%	0.0%	0.0%	11.988s					0s	0s	0s
101	izsol = izsol + 1	0.2%	0.0%	0.0%	0.0%	0.960s					0s	0s	0s
102	jcolu = c_sol(izsol)	0.7%	0.0%	0.0%	0.0%	2.924s					0s	0s	0s
103	end do												
104	if(jcolu == jpoint) then												
105													
106	!SOMP ATOMIC												
107	amatr(1,izsol) = amatr(1,izsol) + elmat(inode,jnode)	1.2%	0.0%	0.0%	0.0%	5.274s					0s	0s	0s
108													
109	end if												
110	end do	0.1%	0.0%	0.0%	0.0%	0.362s					0s	0s	0s
111	end do	0.1%	0.0%	0.0%	0.0%	0.304s					0s	0s	0s
112	else if(ndofn==2) then												
113	!												

Figure 1: Part of *csraxe* subroutine instruction level profiling, unveiling a costly loop.

of art. The runs with the latest Alya version available, and with Intel 2018, on JURECA, show an improvement of 3% in the execution time (10 seconds) compared to the previous latest results. While the general picture stays roughly the same, the MPI time shows an improvement of 30%.

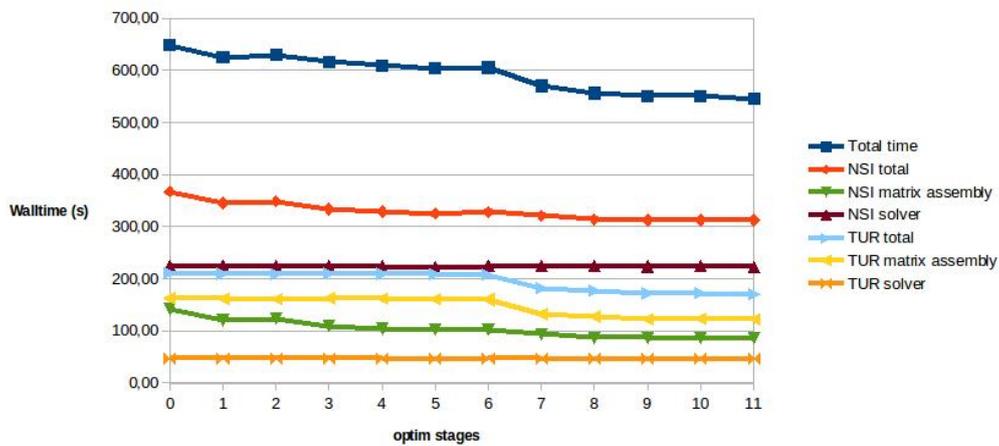


Figure 2: ALYA NSI+TUR perf evolution - 1 Melem, 30 timesteps, 1 node (16 processes) on MareNostrum.

Integration of the Maphys solver in Alya

Activity type	Consultancy or WP1 support
Contributors	E. Agullo (WP1), L. Giraud (WP1), G. Houzeaux (WP2), M. Kuhn (WP1), G. Marait (WP1), L. Poirel (WP1)

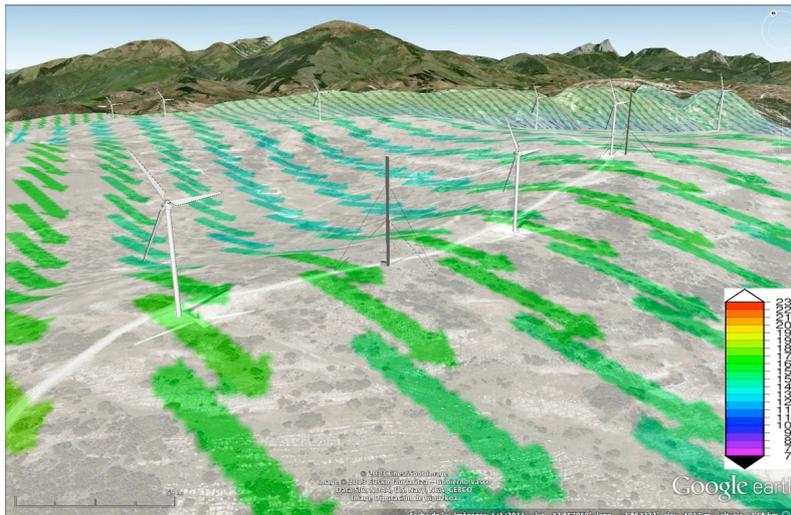


Figure 3: The windfarm test case.

This section deals with the usage of **Maphys** [5] into Alya high performance computing simulation code. Our goal with this study was to evaluate and improve the performances of **Maphys** coarse grid correction mechanism into an applicative context.

For that purpose, we confronted Alya's internal solvers and **Maphys** solver for linear algebra on test cases implemented into Alya, with a particular focus on test cases leading to find the solution of symmetric positive definite systems. In this case, coarse grid correction or deflation mechanisms can be used into both Alya's internal solvers and **Maphys**.

Two test cases have been chosen for this study:

- the simulation of a wind farm,
- and the simulation of the airflow through the nose during a sniff.

To better understand the results presented in this section, please refer to the available description of **Maphys** in Deliverable 1.7 of the EoCoE project.

Simulation of a windfarm. The simulation of a windfarm, Figure 3, has first been chosen as a candidate for a detailed analysis of **Maphys** solver in the frame of Alya simulation code. This simulation involves the Navier-Stokes equations together with a k-ε turbulence model.

The mesh consists of a circled and flat domain with boundary layer elements. Only HEX08 elements are used for its discretisation. The basic mesh contains 3.7M elements, 3.8M nodes. The number of elements can be increased through mesh division into Alya to reach a better accuracy. An example of domain decomposition on 255 subdomains is given by Figure 4, where one can observe that the domain decomposition is almost 2-dimensional.

The equation concerned by **Maphys** into this test case is the pressure equation. Its discretisation leads to find the solution of an SPD linear system. In this case, it is possible to consider the use of Alya's deflated CG and of **Maphys** coarse grid.

For more details on the simulation of a windfarm into Alya, please refer to [1].

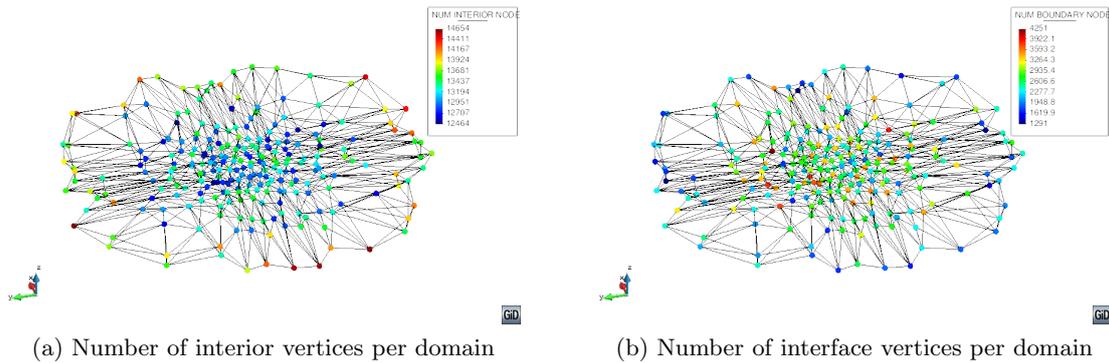


Figure 4: Windfarm test case: pseudo-2D domain decomposition into 255 subdomains.

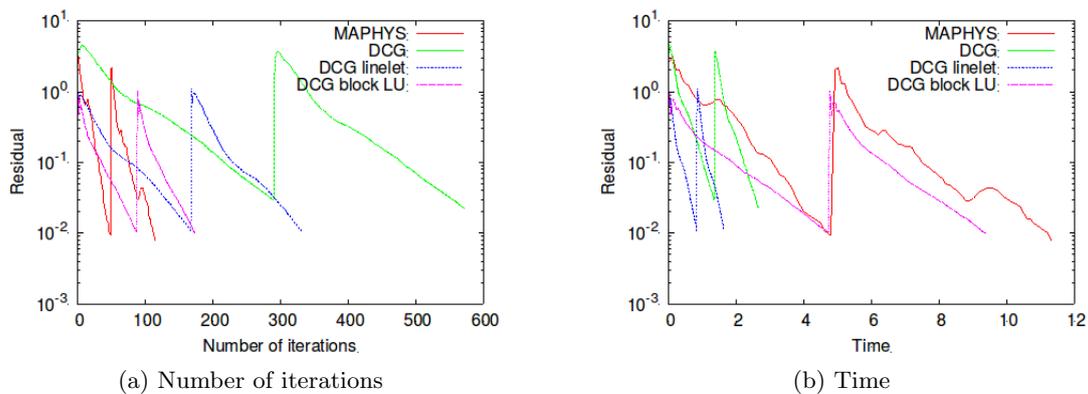


Figure 5: Windfarm test case: convergence history on 511 subdomains. **Maphys** without factorization time.

Figure 5 shows a convergence history on this windfarm test case, simulated on 512 computational cores. The figure plots the residual as a function of the number of iterations on the left and the time to solution on the right. For the **Maphys** solver (in red), the basic (without coarse grid) configuration has been considered, with a local dense preconditioning technique. For Alya, the deflated CG algorithm has been employed, jointly with three preconditioning techniques (in green, blue and purple). As can be seen on the left figure, the number of iterations is lower for **Maphys** than for any of Alya’s deflated CG version. However, on the right figure, the time to solution for **Maphys** is approximately 5 times larger than the best Alya’s deflated CG configuration.

These last results motivate the need of a performant and scalable coarse grid correction study into **Maphys**. This study has been performed on a more suitable test case for coarse grid or deflation technique study, allowing to better illustrate the benefit of using the coarse grid mechanism or deflation technique. This other test case involves a pseudo-1D domain decomposition instead of the windfarm test case’s pseudo-2D one, and is the topic of the next paragraph. Indeed, for a 1D decomposition the coarse grid correction plays a critical role on the numerical behaviour since the condition number grows linearly with the number of domains, while the growth is $\mathcal{O}((\# domains)^{\frac{1}{2}})$ ($\mathcal{O}((\#i domains)^{\frac{1}{3}})$) for 2D-decomposition (resp. 3D-decomposition). Because we do not have yet access to very large computer with large number of cores we prefer to consider 1D-decomposition where

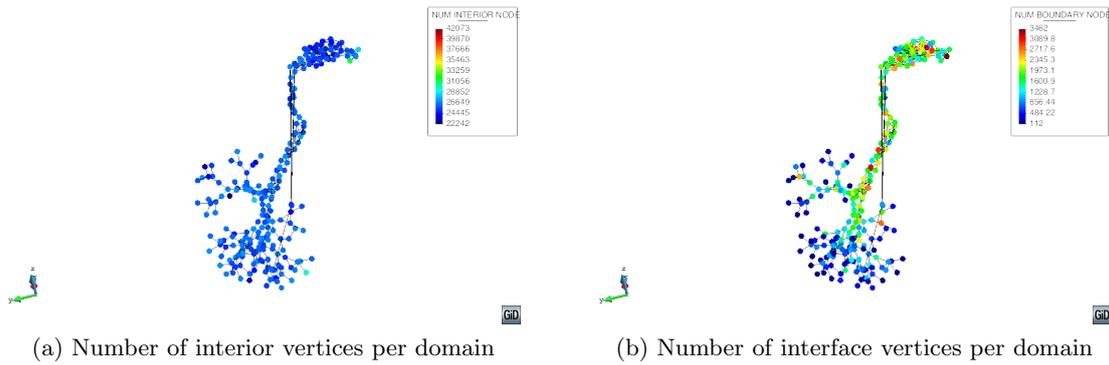


Figure 6: Respiratory test case: pseudo-1D domain decomposition into 255 subdomains.

the critical numerical behaviour will be easy to observe already for a moderated number of cores.

Simulation of the airflow through the nose: the Respiratory test case.

The simulation of the airflow through the nose has been chosen to perform an evaluation of different coarse grid implementations into *Maphys*. This test case simulates the airflow through the nose and large airways by solving the incompressible Navier-Stokes equations.

Three types of elements are in use for the mesh discretisation: TET04, PYR05 and PEN06, for a total of 17.7M elements and 6.9M nodes. The mesh is characterised by a very elongated geometry with small passages in the nasal cavity, leading to a pseudo-1D elongated domain decomposition when parallelising through partitioning the mesh, see Figure 6. This property makes this test case a very good candidate to evaluate the coarse grid of *Maphys* in an applicative context.

On the algebraic solver side, the discretisation of the problem leads to a coupled algebraic system to be solved at each time step. This algebraic system is split to solve independently the momentum and the continuity equations. Due to the splitting strategy, it is necessary to solve the momentum and the continuity equations twice per time step. As the problem is non-linear, the matrix changes between each time step.

The continuity equation is considered for the solver comparison study. This equation leads to the assembly of a SPD linear system. Due to the elongated geometry, low frequencies are hardly damped with a classical one level domain decomposition approach. Hence, coarse grid or deflation mechanisms are investigated to solve the continuity equation.

For more details about this test case, please refer to [2].

All the simulations presented into this section have been performed on the GENCI's OCCIGEN cluster, hosted by the CINES. The part of the cluster in use is composed of 2 Dodeca-core Haswell Intel Xeon E5-2690 v3 @ 2.6 GHz nodes with 64 and 128 Go RAM per node. The code was compiled with Intel compiler version 17.0.0, and linked with the multithreaded Intel MKL version 2017.0.0 and Intel MPI version 2017.0.0. All the runs are made such that the nodes of the cluster are fully occupied (hence the number of cores is always a multiple of 24). Notice that on the OCCIGEN cluster, memory swapping is disabled by default. The simulation campaigns were realised with the help of JUBE Benchmarking Environment, allowing to explore parameters and analyse results comfort-

ably.

The parallel benchmarks have been performed in mono-threaded configuration, on 264, 528, 1056 and 2112 MPI processes, leading respectively to 265, 527, 1055 and 2111 subdomains in the domain decompositions (as Alya has a master process). The iterative solvers' stopping criterion is set to 10^{-6} , to be reached in a maximum of 2000 iterations. For each experiment, 10 time steps are performed, each time step requiring two substeps.

Results are displayed on Figure 7. This figure consists of four quadrants, showing the solver total time (Fig. 7a), the global preconditioner application time for **Maphys** (Fig. 7b), the speedups (Fig. 7c) and the efficiencies (Fig. 7d) of the solvers depending on their preconditioning strategies.

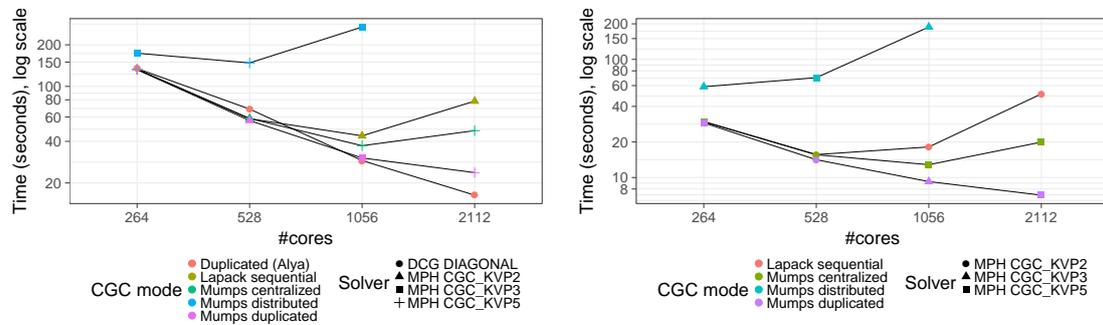
On the Alya's internal solver side, a Deflated Conjugate Gradient method is employed, together with a diagonal preconditioner, **DCG DIAGONAL** on the figures, with a duplicated coarse space of fixed order 10000. The corresponding Coarse Grid Correction mode (CGC mode) for Alya is unique, denoted by **Duplicated (Alya)** on Figure 7.

On the **Maphys** side, several two level preconditioning techniques with coarse grid correction are considered for the iterative solution to the Schur system: **MPH CGC_KVPn** on the figures, with **n** the number of eigenvalue/eigenvector pairs computed for the coarse grid per subdomain. The order of the coarse problem to be solved is then $n \times \#cores$. The four formerly coarse grid correction implementations are displayed on Figure 7. For each CGC mode, only the number of eigenvalue/eigenvector pairs **n** leading to the lowest total computation time is displayed. For the **Mumps centralized**, 12 MPI processes were in use to solve the coarse problem. For the **Mumps duplicated** mode, the coarse problem has been replicated on disjoint groups of 12 MPI processes. As the matrix changes between each time step, **Maphys** has to perform several times its factorization step in order to factorize the local interior problems and to compute the local Schur complements. The preconditioner (local and coarse) are set up to remain fixed through the time steps. If necessary, it could be set up to be recomputed at a predetermined fixed frequency.

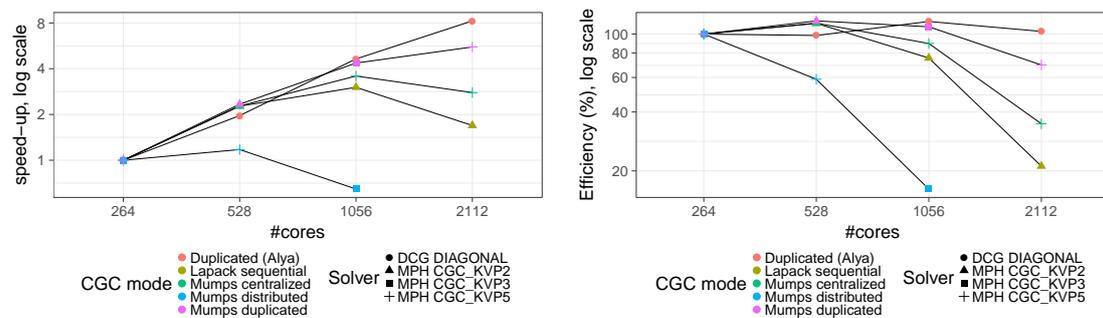
By focusing on the first **Mumps distributed** implementation of the coarse grid, one can observe on Figure 7a (in blue), that **Maphys** coarse grid correction performs poorly in front of Alya's internal deflated CG solver. Into this CGC mode, **Maphys** was not able to scale beyond 528 cores, and did not give a solution for 2112 cores (Out Of Memory (OOM) event on the compute nodes). When having a look at the performances of **Mumps distributed** CGC mode concerning the global preconditioner application on Figure 7b (still in blue), one can identify the required computation time for this part of the iterative process of **Maphys** increases with the number of processes, representing then an increasing ratio of the total computation time. The main reason of these results is that the coarse problem is solved with **Mumps** sparse direct solver with its distributed entry on too many MPI processes, leading to a too fine granularity hence implying poor performances.

In order to improve performances, two other CGC modes have been implemented, namely **Lapack sequential** and **Mumps centralized**. These CGC modes are displayed in greeny-yellow and in green on Figure 7. These two implementation strategies allow to compete with Alya internal solver up to 1056 cores, giving better results on both 264 and 528 cores, see Figure 7a. Notice the results for the **Mumps centralized** version become better than the **Lapack sequential** version when increasing the number of cores. This is due to the order of the coarse problem that increases with the number of domains in use which makes it worth to exploit the sparsity pattern of the coarse matrix. However, these strategies

do not scale beyond 1056 cores. This is mainly due to the global MPI communications required at the beginning and at the end of the global preconditioner application, whose computation time again increases with the number of processes, representing then an increasing ratio of the total computation time, see Figure 7b in greeny-yellow and in green.



(a) Solver total time to solve the continuity problem (b) Maphys only: global preconditioner application time



(c) Solver speedup in solving the continuity equation (d) Solver efficiencies in solving the continuity equation

Figure 7: Evaluation of Maphys scaling with different coarse grid implementations on the respiratory test case.

To go beyond the former limitation, a last CGC mode has been implemented: **Mumps duplicated**. This coarse grid parallel implementation is closer to Alya’s deflation implementation strategy, and allows to save one global MPI communication in the global preconditioner application process of Maphys’ iterative solve part as a comparison to the three former parallel algorithms. On Figure 7b, in purple, one can observe this last global communication bypass allows the global preconditioner application to scale up to the 2112 cores in use for these parallel experiments with this implementation strategy. However, for the solver total time on Figure 7, there is still a gap of approximately 10 seconds between this last version and Alya’s internal solver. This gap is mainly due to the non-ideal scaling of Maphys’ solve phase despite the new strategy and because of the factorization phase which also scale less successfully between 1056 and 2112 than before to reach this amount of computing resources.

To sum up, the developments in the frame of this comparative study enabled to significantly improve the efficiency and the scalability potential of Maphys (see Figures 7c and 7d) with the use of its coarse grid correction mechanism in the case of SPD linear systems. Indeed, on 1056 cores, the first coarse grid parallel implementation, i.e. **Mumps centralized**

CGC mode, led to 13 % efficiency relatively to 264 cores against 109 % with the most performant CGC mode `Mumps duplicated`. The `Mumps duplicated` CGC mode also enabled to obtain results on 2112 cores with 69% efficiency against 34 % (respectively 21 %) for the less performant `Mumps centralized` (resp. `Lapack sequential`) CGC modes.

PSBLAS and MLD2P4 for Alya

Activity type	WP1 support
Contributors	Ambra Abdullahi Hassan (University of Rome “Tor Vergata”, Italy), Pasqua D’Ambra (CNR, Italy), Daniela di Serafino (University of Campania “L. Vanvitelli”, Italy), Salvatore Filippone (Cranfield University, UK), Herbert Owen (BSC, Spain) for WP2

The improved versions of PSBLAS and MLD2P4 developed during the EoCoE project (see Deliverable D1.7) have been applied to a data set from Alya. The goal of this work was to provide a sound basis for the selection of solvers and preconditioners for future integration and tuning into the application code.

Data Set

The set of linear systems comes from computational fluid dynamics simulations for wind farm design and management, carried out at BSC, within WP2 (*Meteorology for Energy*), by using the HPC multi-physics simulation code Alya [6]. The systems arise from the numerical solution of Reynolds-Averaged Navier-Stokes equations coupled with a modified $k - \varepsilon$ model. The space discretization is obtained by using stabilized finite elements, while the time integration is performed by combining a backward Euler scheme with a fractional step method, which splits the computation of the velocity and pressure fields and thus requires the solution of two linear systems at each time step. Four test cases were made available by BSC, each including a pressure and a velocity system. The dimensions of the pressure systems range from 305472 to 2224476, and the corresponding number of nonzeros from 8060182 to 58897774. The dimensions and the number of nonzero entries of the velocity system range from 916416 to 6673428 and from 72541638 to 530079966, respectively. The data partitioning used by Alya on 8, 16, 32 and 64 processors was also provided for one of the test cases, having pressure and velocity systems of dimensions 1123344 and 3370032, respectively. We focused mainly on the pressure systems, whose sparsity pattern is shown in Figure 8.

In order to assess the behaviour of different MLD2P4 preconditioners on the selected test case and choose the best ones for the applications of interest, an evaluation in terms of execution time, strong and weak scalability, and linear solver iterations was carried out.

Results on the Data Set

We applied to the linear systems from Alya the PSBLAS Conjugate Gradient (CG) solver with algebraic multilevel preconditioners implemented in MLD2P4, using several choices of smoothers and coarsest-level solvers. We also used the one-level block-Jacobi preconditioner, applying ILU(0) to the blocks. The zero vector was chosen as starting guess; the reduction of the 2-norm of the residual by a factor of 10^{-6} was used as stopping criterion. The experiments were run on a linux cluster, named yoda, operated by the Naples Branch of the CNR Institute for High-Performance Computing and Networking.

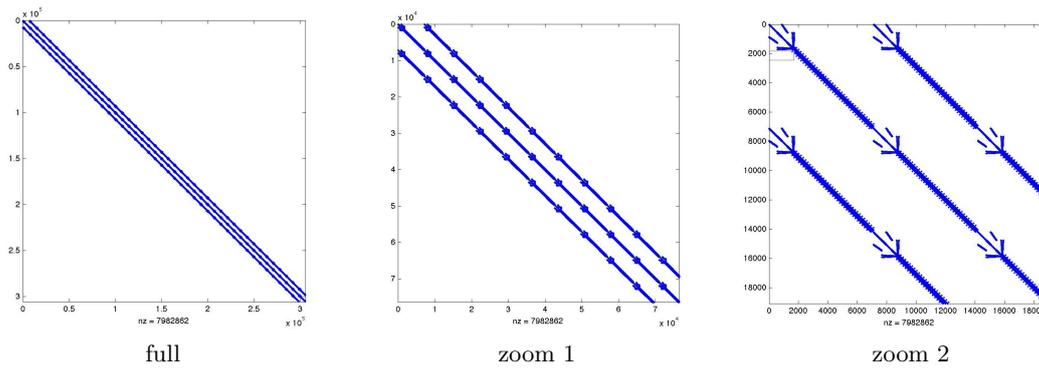


Figure 8: Pressure matrices from wind farm simulations: sparsity pattern (full matrix and details).

The results obtained with the multilevel preconditioners implemented in MLD2P4 are not satisfactory. These preconditioners result very sensitive to the matrix distribution, and the performance quickly deteriorates as the number of parallel processes increases, often leading to stagnation of CG. Furthermore, a strong load imbalance arises when the data partitioning from Alya is used. A crucial role is played by the aggregation threshold used by the smoothed aggregation algorithm at each level, but determining this threshold is not an easy task. Conversely, the block-Jacobi preconditioner has a reasonable performance, although the number of iterations increases significantly with the number of cores. As an example of this behaviour, in Table 5 we report the number of CG iterations, the times (in seconds) for building the preconditioners and applying the preconditioned CG, and total time obtained with the block-Jacobi preconditioner on the pressure matrix with dimension 1123344, using the Alya data partitioning. Further experiments showed that

Table 5: Pressure matrix from wind farm simulation (dim. 1123344): number of iterations and execution time (in seconds) on yoda.

BLOCK-JACOBI				
procs	iters	tprec	tsolve	ttot
8	285	0.2	6.4	6.6
16	323	0.1	4.4	4.5
32	354	0.1	2.9	3.0
64	430	0.0	1.8	1.8

the multilevel preconditioners implemented in MLD2P4 are not effective with the velocity systems too. In particular, the smoothed aggregation algorithm implemented in MLD2P4 is not effective with linear systems coming from discretization grids where each node is associated with multiple variables, as is the case with the velocity systems.

The results obtained on the pressure and velocity matrices motivated our interest toward new coarsening algorithms, aimed at improving the convergence behaviour and the parallel performance of the smoothed-aggregation based multilevel preconditioners implemented in MLD2P4. This is part of a longer-term research directed toward a more general revision

of the package, which may include the design and the developments of new methods. First results in this direction appear very promising and are reported in Deliverable D1.11 (Applied research activities outcome).

AGMG for Alya

Activity type	WP1 support
Contributors	Herbert Owen (BSC, WP2), Yvan Notay (ULB, WP1)

As concluded in earlier performance reports, Alya can possibly be improved by using external, well optimized, software packages for the solver part of the code, instead of the so far implemented in house method. Because of the nature of the linear systems to solve, the AGgregation-based algebraic MultiGrid (AGMG)¹ is a potential candidate, although the specific discretisation methods used in Alya entail that the matrix properties are relatively far from those AGMG has been designed for.

Comparison between Alya's own solvers and AGMG:

For CFD problems 2 different approaches can be used RANS and LES. The numerical treatment and the kind of meshes used significantly affect the behaviour of AGMG:

- **RANS:** RANS is cheaper and more robust than LES. All the turbulence scales are modelled. It is the approach typically used by most of the industry. The meshes used are highly anisotropic and both the velocity and pressure are solved implicitly. AGMG does not work well for this kind of problems. The anisotropic meshes discretised with finite elements are not well suited for AGMG. For this kind of problems Alya's [6] own solvers (GMRES, CG or deflated CG) typically provide much smaller solution times.
- **LES:** When LES is used the small scales are modelled but the large scales are resolved. It is significantly more expensive than RANS but it can provide much more accurate results for problems with important separation as those that occur in flow over complex terrain. With the constant increase in computational resources pioneering companies are moving towards LES. For incompressible LES problems the velocity is treated explicitly and the pressure implicitly. LES meshes are much less anisotropic than RANS meshes. AGMG has proved to be very successful for these kind of problems. In Table 6 we present results for the solution of pressure for a complex geometry flow. The mesh is isotropic and has 8 M nodes. The number of cores used vary from 72 to 288. Thus, the average number of nodes per sub-domain varies from 111 k nodes to 27 k nodes respectively. In Alya a deflated conjugate gradient solver is used [4]. The number of groups is set to 1000.

Table 6: CPU time per time step. Note that AGMG setup is only done once, c.f. text.

number of cores	Alya solution[s]	AGMG solution[s]	AGMG setup [s]
72	1.67	0.33	0.37
144	0.86	0.16	0.19
288	0.46	0.12	0.12

¹<http://www.agmg.eu>

AGMG needs 2 steps to be performed; first setup and then solution. For the LES problems being solved the setup can be performed only once at the beginning of the simulation and it can be reused for thousands of time steps since the pressure matrix remains constant. Thus, this time can be neglected in the comparison. In the cases with 72 and 144 cores AGMG is more than 5 times faster than Alya's own solver, a deflated CG with 1000 groups. For 288 cores AGMG does not scale well and its advantage with respect to Alya is reduced. It is a well known fact that multi-grid solvers do not have a good scalability with small number of unknowns per core. The case we have presented is particularly well suited for AGMG but we have found several other cases where AGMG is at least twice faster than Alya.

Weak scalability with AGMG:

A key advantage of multi-grid solvers with respect to standard iterative linear solvers such a CG is that they should allow the number of iterations to remain constant as the number of unknowns increases. This means that they have algorithmic scalability which makes them the best choice for Exascale problems. Since AGMG's weak scaling has only been tested on structured meshed we decided that it would be good to make some numerical experiments with the unstructured meshes used by Alya.

In order to do so, a tool in Alya that allows to subdivide the elements into elements with half the size is used [3]. In a 3D problem each time the divisor is applied the number of nodes of the problem is multiplied by 8. In the original mesh (no divisor) we run with 36 and 72 CPU cores. Each time we apply the divisor the number of cores is multiplied by 8 so that the average number of nodes remains constant at 222knodes/core and 111 knodes/core respectively (see Table 7) . An ideal weak scaling would imply that the CPU time remains constant. We have applied the divisor once and twice leading to a meshes of 64 M nodes and 512 M nodes respectively.

Table 7: Number of cores used and size of meshes tested.

knode/core	222	111
no divisor- 8 M node	36	72
1divisor – 64 M nodes	288	576
2divisor – 512 M nodes	2304	4608

In Table 8 we present the average CPU time per time step for each of the cases. We can see that with 1 divisor the weak scaling is good but it degrades significantly when 2 divisors are used. The degradation is much higher in the case with 111 k nodes/core. Actually AGMG takes more time with 4608 cores than with 2304. We have observed that the performance of AGMG depends strongly on the partitioning method used. In the current results Metis has been used, which typically provides smaller AGMG CPU times that the alternative Space Filling Curve approach also available in Alya.

Table 8: Average CPU time [s] per time step.

knode/core	222	111
no divisor- 8 M node	0.65	0.32
1divisor – 64 M nodes	0.67	0.36
2divisor – 512 M nodes	1.13	1.36

One possible cause of the degradation observed between 1 and 2 divisors is that the resulting partition that Alya obtains when 2 divisors are applied is not very good. We are currently working on improving the partition when the divisor is used. When this is solved, further tests shall be performed.

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3. Eirene

Short description

EIRENE is a classical Monte Carlo transport code that simulates neutral particle (and to a certain extent also charged particle) linear transport, mostly in nuclear fusion applications. It is often coupled iteratively to many integrated fusion plasma transport code systems (e.g. in all EU edge transport code systems), both in 2D and in 3D magnetic configurations. Non-linear particle (and photon) transport problems are also dealt with by iteration. EIRENE is written in Fortran (~170.000 lines of code) and parallelised using MPI.

Code team:

- Petra Börner (FZJ) (WP5)
- Tamás Fehér (MPG) (WP5)
- Thomas Breuer (FZJ) (WP1)

Benchmark characteristics:

One example of coupling EIRENE to other codes is used in the SOLPS-ITER code package. Here EIRENE is linked together with the B2 code and is called by B2 in each iteration. The following test cases are inspired by a SOLPS-ITER test case, but they use the stand-alone version of EIRENE.

The physical parameters for the test case correspond to the so-called ASDEX Upgrade Plasma with 5 bulk ion species and 59 reactions. The particle number and iteration number is set in a way to have one minute execution time using one node of JURECA. In both test cases six strata are used.

Test case 1, fixed number of particles: In this test the number of particles is fixed in each stratum. A total 630k particles are calculated in every iteration. There are 30 iterations. The six strata have different numbers of particles, and the CPU time to simulate a stratum also depends on the physical parameters inside the stratum.

Test case 2, fixed execution time: This test specifies that in each iteration 5 seconds of wall-clock time is allocated to following the particles. Each MPI task is assigned to one of the strata and then calculates as many particles as possible in 5 seconds. Twelve iterations are used to reach 1 minute of execution time. The actual execution time is longer because of post processing and communication.

Since the execution time is fixed for test case 2, time is not a good measure of performance. Instead, we should consider the number of particles that are calculated. Some of the metrics in the performance tables will hence use the unit kP/s (thousand particles per second).

Application support

Activity type	WP1 support during performance workshop, Consultancy
Contributors	T. Fehér (WP5, MPG, Germany), T. Breuer (WP1, JSC, Germany), D. Brömmel (WP1, JSC, Germany)

The main support action so far was support during the second benchmarking workshop

in Saclay. The results from this workshop have been reported before and are partly mentioned below. This also triggered improvements to EIRENE that were performed via the EUROfusion High Level Support Team (HLST) in Garching, explained later in this section.

A new support activity for EIRENE has been started at the end of 2017. The main developers expressed interest in running large parameter studies that would require a much more scalable code and a new, more scalable architecture to run on for which they were previously targeting JUQUEEN. Since JUQUEEN will be decommissioned, the focus shifted to the JURECA booster system consisting of 1640 compute nodes each with one Intel Xeon Phi Knights Landing (KNL).

Initial tests have been performed investigating the performance of EIRENE on KNL vs. standard Intel CPUs as well as the scalability on the JURECA booster. Along with this, a master student started working on EIRENE in January 2018, focussing on hybrid parallelisation and possibly vectorisation. This work will be carried out in collaboration with support from EoCoE WP1.

EoCoE benchmark tables

Tables 9 and 10 show the summary of the benchmarks that have been run during the project so far. The two tables each present one of the test cases. The individual columns represent results from the performance evaluation workshop and later measurements to evaluate EIRENE on the booster (KNL) architecture.

Findings from the workshop: Test case 2 has 5.8 seconds of MPI communication time. According to the Scalasca trace analysis, around half of this time is spent in distributing the input data. Some part of the input data does not change between the iterations, and it would be possible to reduce the communication costs of distributing the input data.

The other half of the communication time is summing up the data within the stratum and over all strata. There is a large number of collective communication calls with an average message size of 25 kB. This is due to looping through the columns of large arrays, and doing reductions column-wise. It would be trivial to replace this with a single reduction over 2D arrays.

Even though an Allinea Performance Report suggests that the code is memory bound, the 'Memory vs Compute Bound' metric does not show significant improvements using higher memory bandwidth.

If the vectorization is turned off, then the code performance remains the same, this is in agreement with the Allinea Report. Without FMA operations the code seems to be slightly faster. The difference is very small and is likely only a measurement fluctuation.

Repeated measurements: With the renewed support activity, the metrics have been updated again from previous runs, c.f. the second column in tables 9 and 10. Since the metrics have been changed during the lifetime of the project, the JUBE scripts had to be adapted. This also means not all metrics have a 1:1 correspondence and direct comparisons are made difficult (e.g. the extraction of MPI metrics has changed, some measurements have been removed and others added.). The total runtime nevertheless allows for testing whether compiler improvements or updates to the software stack on JURECA had an

Table 9: Performance metrics for test case 1 on the JURECA cluster and booster system. The first column is the original measurement after the workshop, the last two columns are re-runs to start investigating the KNL performance and latest software stage. Metrics that have been added (removed) during the project are marked with n.m. (o.m.).

	Metric name	05'2016	01'2018	
		Cluster	Cluster	Booster
Global	Total Time (s)	64.4	68	241
	Time IO (s)	0.2	0.24	5.87
	Time MPI (s)	36.0	28.58	134.30
	Memory vs Compute Bound	1.1	1.82	1.01
	Load Imbalance (%)	n.m.	11.01	8.74
IO	IO Volume (MB)	498.3	498.33	502.11
	Calls (nb)	650279	652903	775805
	Throughput (MB/s)	2142.3	2043.87	85.51
	Individual IO Access (kB)	0.9	0.73	0.77
MPI	P2P Calls (nb)	37	37	14
	P2P Calls (s)	0.0	0.42	0.60
	P2P Calls Message Size (kB)	n.m.	3080	1332
	Collective Calls (nb)	191543	191543	131165
	Collective Calls (s)	2.2	13.00	45.13
	Coll. Calls Message Size (kB)	n.m.	22	25
	Synchro / Wait MPI (s)	10.8	11.15	37.67
	Ratio Synchro / Wait MPI (%)	29.9	40.56	28.09
	Message Size (kB)	24.7	o.m.	o.m.
	Load Imbalance MPI	13.4	o.m.	o.m.
Mem	Memory Footprint	151552 kB	166936kB	196584kB
	Cache Usage Intensity	N.A.	0.84	0.63
	RAM Avg Throughput (GB/s)	N.A.	o.m.	o.m.
Core	IPC	N.A.	2.30	1.44
	Runtime without vectorisation (s)	65.8	73	248
	Vectorisation speedup factor	1.0	1.07	1.03
	Runtime without FMA (s)	63.8	73	239
	FMA speedup factor	1.0	1.07	0.99

effect on EIRENE's performance: this seems not to be the case. The small variations in runtime are more likely attributed to variability of different jobs on JURECA. The test cases are likely too short to hide this variability. Two options are possible: change the test cases (with the drawback of losing continuity in measurements) or extend the JUBE scripts to account for statistics. The latter is a rather involved step and has not been taken by EoCoE.

Investigating the JURECA booster: Tables 9 and 10 also contain a first execution of the code on KNL. Those runs have not been tuned to the architecture, so a performance drop (e.g. for the kP/s metric) is expected at first. We currently observe a slowdown of a ≈ 4 for both test cases when using 24 MPI ranks on the JURECA cluster and 64 MPI ranks on the JURECA booster, both roughly corresponding to a single node (68 physical cores on a

Table 10: Performance metrics for test case 2 on the JURECA cluster and booster system. For test case 2, the figure of merit is the number of particles calculated per second, given as kP/s (thousand particles/sec). The first column is the original measurement after the workshop, the last two columns are re-runs to start investigating the KNL performance and latest software stage. Metrics that have been added (removed) during the project are marked with n.m. (o.m.).

	Metric name	05'2016	01'2018	
		Cluster	Cluster	Booster
Global	Total Time (s) / Throughput (kP/s)	69.0 / 666	67 / 702	98 / 166
	Time IO (s)	0.1	45.00	6.14
	Time MPI (s)	5.8	7.46	21.09
	Memory vs Compute Bound	1.0	1.81	1.00
	Load Imbalance (%)	n.m.	4.74	12.88
IO	IO Volume (MB)	202.7	202.72	204.29
	Calls (nb)	260403	261404	311524
	Throughput (MB/s)	1842.7	4.50	33.28
	Individual IO Access (kB)	0.9	0.74	0.78
MPI	P2P Calls (nb)	15	15	5
	P2P Calls (s)	0.0	0.18	0.24
	P2P Calls Message Size (kB)	n.m.	4264	2843
	Collective Calls (nb)	76590	76568	52621
	Collective Calls (s)	0.9	7.03	18.76
	Coll. Calls Message Size (kB)	n.m.	21	25
	Synchro / Wait MPI (s)	4.4	6.25	15.70
	Ratio Synchro / Wait MPI (%)	76.5	76.23	74.34
	Message Size (kB)	24.6	o.m.	o.m.
Mem	Load Imbalance MPI	4.5	o.m.	o.m.
	Memory Footprint	154624 kB	339544kB	202232kB
	Cache Usage Intensity	N.A.	0.85	0.66
Core	RAM Avg Throughput (GB/s)	N.A.	o.m.	o.m.
	IPC	N.A.	2.39	1.40
	Runtime without vectorisation (s)	68.0	67	93
	Vectorisation speedup factor	0.99	1.00	0.95
	Runtime without FMA (s)	68.8	75	95
	FMA speedup factor	1.00	1.12	0.97

booster node). Note that the 'Memory vs Compute Bound' metric is estimated as on the cluster nodes (i.e. the same number of MPI ranks is distributed over two nodes instead of one, using every other code, in theory freeing memory bandwidth and enlarging L2 cache available to the ranks). One obvious difference is the achieved I/O bandwidth on the cluster and booster part. This is attributed to the early production phase of the booster. But investigating I/O performance revealed inefficient I/O within EIRENE where data is written multiple times (the difference in measure I/O volume and actual data on disk is $\mathcal{O}(10 - 30)$). While this has no dramatic effect on overall runtime it certainly leaves room for improvement.

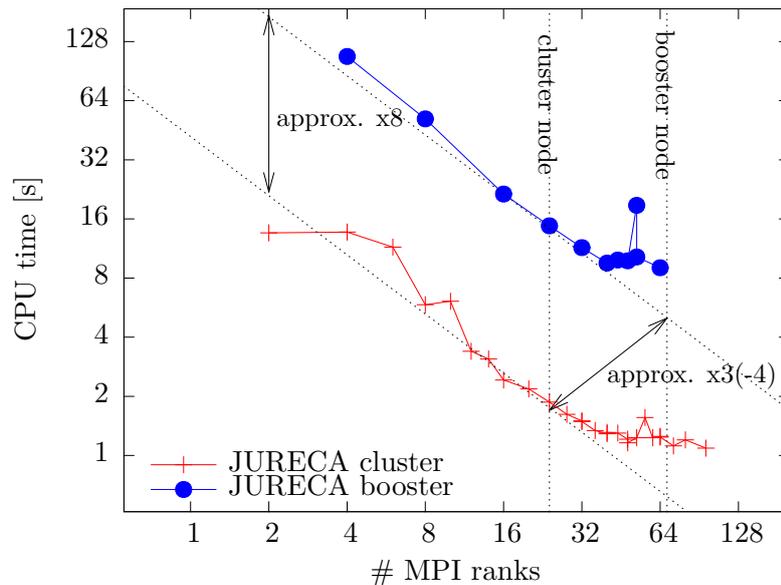


Figure 9: Scalability of EIRENE on the JURECA cluster and booster parts. Shown is the CPU time per step, also indicating the initial (untuned) slowdown between a single core (node) on either part shown.

Please note that the metrics, without statistics, are not to be taken too serious for EIRENE since the observed variations between repeated runs is on the order of the 'observed effects'. In case of I/O, bandwidths between 4 MB/s and 2 GB/s can be seen in the tables. Hence both test cases need to be extended in their runtime.

Since scalability was of special interest, a test case similar to test case 1 was used to test the scaling of EIRENE on the cluster and booster parts, shown in Figure 9. With the used number of strata and overall particle number per rank it was not possible to go beyond the number of MPI ranks shown. We did try and relate performance per core and node of the cluster and booster parts, showing an untuned (i.e. no optimisations for KNL or changes to the source code) slowdown of approximately a factor of 8 and 3–4, respectively. During the new support action we hope to close the gap between the two.

External support

The EUROfusion High Level Support Team (HLST) at Garching was present at the workshop in Saclay and continued supporting the development of Eirene. They have concentrated on the load-balancing issues present in some setups for running EIRENE (with a fixed particle number, similar to test case 1). Here, we quote their main results and refer to their write-up [2, 1] for more details, in particular for the implementation steps.

EIRENE distributes work (in form of strata and particles therein) over the available processing elements (PEs). Strata with a larger particle number will be assigned to more PEs and this balancing will be optimised over time steps according to the work done.

The HLST team discovered and fixed a bug that led to bad load-balancing in case where the number of PEs was comparable to the number of strata.

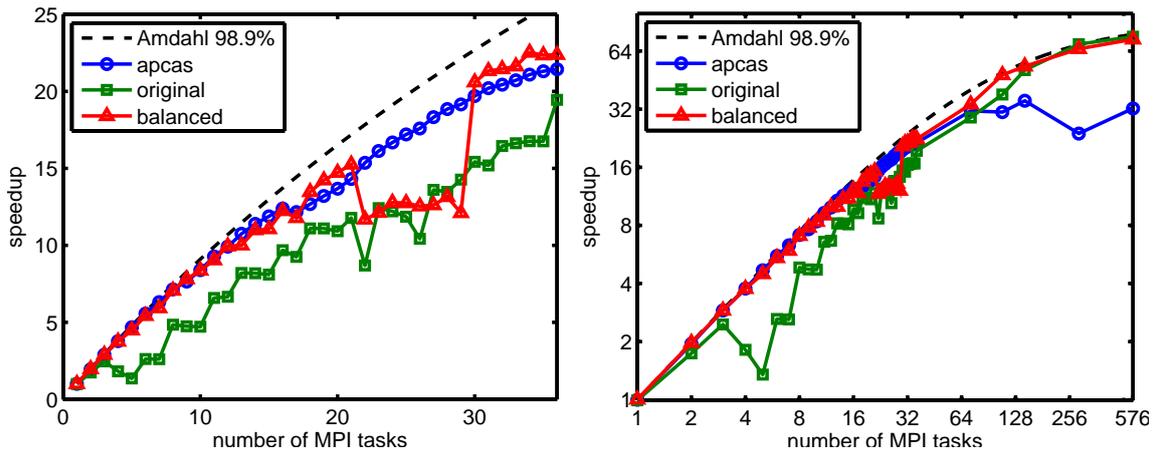


Figure 10: Speed-up of the MCARLO subroutine for different load-balancing strategies for the AUG test case, taken from [1]

Apart from the bugfix, the team also introduced new load-balancing strategies:

- **APCAS:** ALL PEs Calculate All Strata. Here work is distributed evenly among PEs. This also introduces blocking reduction operations. Since all PEs process parts of all strata, overall more communication is necessary which may deteriorate performance with a larger number of PEs.
- **Balanced:** Here non-blocking reductions are used while summing results within strata, thus work does not have to be divided evenly between PEs. Instead work can be divided freely based on measurements of the processing time and overheads. In this case also, some PEs may work on multiple strata.

The performance impact has been studied on MARCONI where each node has 2x18 cores. Test cases called 'AUG3' and 'ITER2' used a fixed particle and iterations number. Thus keeping the problem size constant, the number of MPI tasks was varied and the execution time measured. The HLST noted several performance drops with certain numbers of tasks for some of the load-balancing strategies and suggested this may be related to the MPI library. Figure 10 shows this is the case for the 'AUG3' test case and the 'balanced' load-balancing, while Figure 11 has such an effect for 'APCAS' and the ITER case.

Any achieved improvements will depend on the exact setup of the runs performed with EIRENE. However, ITER users report a routine usage of these improvements for their scientific production of SOLPS-ITER without quantifying the overall impact in runtime.

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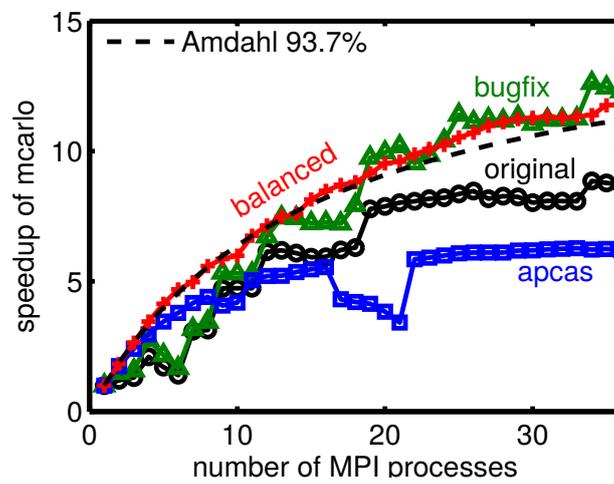


Figure 11: Speed-up of the MCARLO subroutine for different load-balancing strategies for the ITER test case, taken from [1]

4. Esias

4.1 Overview

ESIAS stands for Ensemble for Stochastic Integration of Atmospheric Simulations.

It is a coupled ensemble implementation of Weather Research and Forecasting Model (WRF) and European Air Pollution and Dispersion Inverse Model (EURAD-IM) for short to medium range probabilistic forecasts and emission parameter estimation using Monte Carlo and Variational Data assimilation techniques.

WRF is a state-of-the-art mesoscale numerical weather prediction system which is used extensively for research and operational real-time forecasting at numerous public research organizations and the private sector throughout the world and is open to the public. It offers various sophisticated physics and dynamics options.

EURAD-IM is a fully adjoint chemistry transport model on the regional scale for chemical species and aerosols which is used for both, operational air quality forecasts and research applications. A main feature is the joint initial value and emission factor optimization using four dimensional variational data assimilation.

4.2 Performance metrics

The benchmark setup contains a random simulation period of 6 hours with 240x240x24 grid points as a typical size. For benchmarking, solely 2 ensemble members run in parallel (instead of the order 1000 for production runs, would be too computational intensive for benchmarking). No particle filtering is performed due to the small ensemble size. 1024 processors on JUQUEEN are used. Parallel NetCDF is used. In Table 11 the direct comparison between the initial code state on JUQUEEN for this particular benchmarking case together with a second run done after the improving the node level performance is shown.

For a second setup the same benchmark case was chosen, but the number of ensemble members was increased together with the number of used processors to validate the weak scaling behavior. For this run 256 processors per ensemble member were selected and three individual runs for 2, 4 and 16 members were performed on JUQUEEN. Table 12 shows the extracted metrics.

4.3 Support

Activity type	Consultancy
Contributors	Sebastian Lührs (WP1, JSC, Germany), Jonas Berndt (WP2, IEK8, Germany)

The main support activity for ESIAS within the framework of EoCoE took place in the context of WP2 with additional guidance by WP1 especially in context of the usage of the performance evaluation tools.

The main outcome of this particular support activity is presented within the separate deliverable D2.2 "Ultra large meteorological ensemble" [1] as well in the performance evaluation deliverable D1.17 "Application Performance Evaluation" [2].

The overall computing performance could be improved with the help of adapted compiler options. Here mainly the WRF part of ESIAS was adapted to the JUQUEEN system

Table 11: Performance metrics for Esias on the JUQUEEN HPC system.

	Metric name	metrics_O2.json	metrics_O3.json
Global	Total Time (s)	259.46	199.71
	Time IO (s)	28.53	27.42
	Time MPI (s)	150.01	132.33
	Memory vs Compute Bound	N.A.	N.A.
	Load Imbalance (%)	31.03	31.36
IO	IO Volume (MB)	3570.93	3570.93
	Calls (nb)	63594	63594
	Throughput (MB/s)	125.16	130.24
	Individual IO Access (kB)	118.42	118.45
MPI	P2P Calls (nb)	135267	135267
	P2P Calls (s)	70.25	57.07
	P2P Calls Message Size (kB)	15	15
	Collective Calls (nb)	6170	6170
	Collective Calls (s)	21.93	18.35
	Coll. Calls Message Size (kB)	14	14
	Synchro / Wait MPI (s)	85.89	68.73
	Ratio Synchro / Wait MPI (%)	48.05	42.20

capabilities. This allows a overall runtime improvement in the sense of a a factor 1.5 to 2. A comparison of the performance metrics for the non optimized ESIAS execution and the optimized version is shown in Table 11.

In addition within WP2 the internal stochastic pattern computation was parallelised. This was needed to finally reach a acceptable execution time on JUQUEEN due to its specific architecture with its low per core performance. The routine itself could be improved by a factor of 5 up to 10 in the sense of computing time.

The overhead of the ensemble approach was evaluated as well. For a small number of ensemble members the scaling behavior was analyzed with the help of the performance metrics, as shown in Table 12. Larger number of ensemble members were also tested in the context of D2.2. Overall there is a growing datasize for additional ensemble members, which is compensated by the growing I/O bandwidth when using more computing elements of JUQUEEN. On the other site the overall MPI time increased, while the total time kept quite stable. This behaviour is mainly influenced due to the metric calculation and the selected benchmark case, which was just copied multiple times. While the number of computing elements increased, there is one process defining the critical path of the application. This path stays mostly unchanged even if there are new members involved. Due to the metric average calculation the overall MPI delay increases, as more members have to wait for the critical path.

References

- [1] Hendrik Elbern, ed. *D2.2 Ultra large meteorological example*. URL: http://www.eocoe.eu/sites/default/files/results_files/d2.2-m18-676629_ultralarge_meteorological_ensemble.pdf.

Table 12: Performance metrics for increasing number of Esias ensemble members on the JUQUEEN HPC system.

	Metric name	2 member	4 member	16 member
Global	Total Time (s)	268	270	279
	Time IO (s)	20.70	21.23	22.13
	Time MPI (s)	111.92	119.21	174.22
	Memory vs Compute Bound	N.A.	N.A.	N.A.
	Load Imbalance (%)	24.39	26.23	36.40
IO	IO Volume (MB)	3244.71	6489.41	25957.65
	Calls (nb)	38506	77002	307978
	Throughput (MB/s)	156.73	305.61	1172.94
	Individual IO Access (kB)	147.82	147.83	147.85
MPI	P2P Calls (nb)	133050	133050	133050
	P2P Calls (s)	57.52	58.88	99.64
	P2P Calls Message Size (kB)	19	19	19
	Collective Calls (nb)	6170	6170	6170
	Collective Calls (s)	10.91	10.77	16.67
	Coll. Calls Message Size (kB)	16	30	117
	Synchro / Wait MPI (s)	62.80	68.95	118.29
	Ratio Synchro / Wait MPI (%)	47.13	48.91	60.20

- [2] Matthieu Haefele, ed. *D1.17 Application Performance Evaluation*. URL: http://www.eocoe.eu/sites/default/files/results_files/d1.17.pdf.

5. Gysela

Activity type	Consultancy or WP1 support
Contributors	Brian Wylie (WP1, Germany), Judit Gimenez (WP1, Spain), Guillaume Latu (WP5, France), Julien Bigot (WP1, France), Corentin Roussel (WP1, France), Benedikt Steinbusch (WP1, Germany), Chantal Passeron (WP5, France), Wolfgang Frings (WP1, Germany), Sebastian Lührs (WP1, Germany)

Direct benefits of SMT

To evaluate SMT, we choose a domain size of $N_r \times N_\theta \times N_\varphi \times N_{v_{\parallel}} \times N_\mu = 512 \times 256 \times 128 \times 60 \times 32$ in this section. Due to GYSELA internal implementation choices, we are constrained to choose, inside each MPI process, a number of threads as a power of two. Let us remark, that the application performance increases by avoiding very small power of two (*i.e.* 1, 2). Haswell node that we target are made of 24 cores. That is the reason why we choose to set 8 threads per MPI process for the runs shown hereafter. This configuration will allow us to compare easily an execution with or without SMT activated.

In the following, the deployment with 3 MPI processes per node (one compute node, 24 threads, 1 thread per core) is checked against a deployment with 6 MPI processes per node (one compute node, 48 threads, 2 threads per core, SMT used). Strong scaling experiments are conducted with or without SMT, timing measurements are shown in Table 13. Let us assume that processes inside each node is numbered with an index n going from 0 to 2 without SMT, and $n = 0$ to 5 whenever SMT is activated. For process n , threads are pinned to cores in this way: logical cores id from $8n$ up to $8n + 7$.

Table 13: Time measurements for a strong scaling experiment with SMT activated or deactivated, and gains due to SMT.

Number of nodes/cores	Exec. time (1 th/core)	Exec. time (2 th/core)	Benefit of SMT
22/ 512	1369s	1035s	-24%
43/1024	706s	528s	-25%
86/2048	365s	287s	-21%
172/4096	198s	143s	-28%

The different lines show successive doubling of the number of cores used. The first column gives the CPU resources involved. The second and third columns highlight the execution time of mini runs comprising 8 time steps (excluding initialization and output writings): using 1 thread per core (without SMT), or using 2 threads per core (with SMT support). The last column points out the reduction of the run time due to SMT comparing the two previous columns. As a result, the simultaneous multi-threading with 2 threads per core gives a benefit of 21% up to 28% over the standard execution time (deployment with one thread per core). While an improvement is expected with SMT, as already reported for other applications this speedup is quite high for a HPC application.

Within Paraver, we observe that for each intensive computation kernel the number of instructions per cycle (IPC) cumulated over the 2 threads on one core with SMT is always higher than the IPC obtained with one thread per core without SMT. For these kernels,

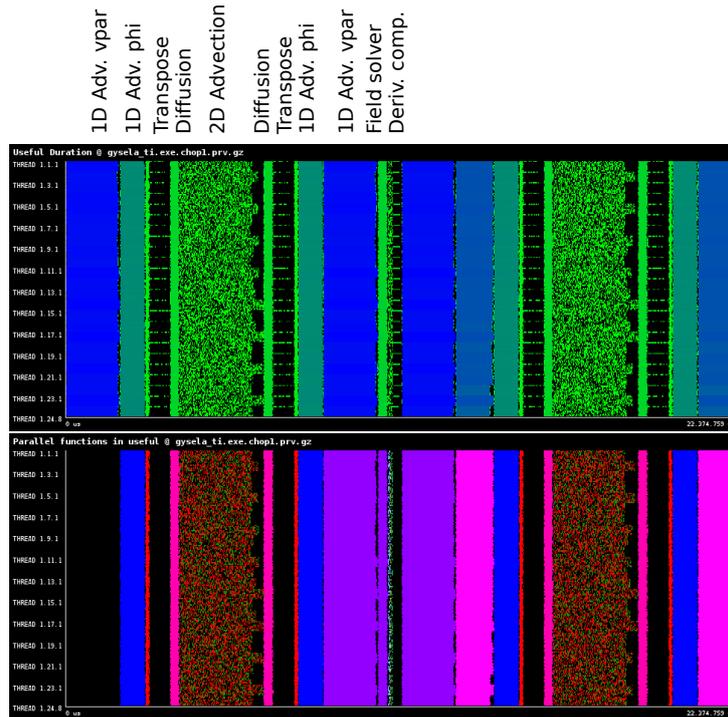


Figure 12: Snippet of a run with 2 threads per core (SMT), Top: Paraver useful duration plot, Bottom: Parallel functions plot.

the cumulated IPC is comprised between 1.4 and 4 for two threads per core with SMT, whereas it is in the range of 0.9 up to 2.8 with one thread per core without SMT. These IPC numbers should be compared to the number of micro-operations achievable per cycle, 4 on Haswell. Thus, we use a quite large fraction of available micro-operation slots. Two factors explain the boost in performance with SMT. First, SMT hides some cycles wastes due to data dependencies and long latency operation (*e.g* memory accesses). Second, SMT enables to better fill available execution units. It provides a remedy against the fact that, within a cycle, some issue slots are often unused.

Optimizations to increase SMT gain

The Paraver tool gives us the opportunity to have a view of OpenMP and MPI behaviors at a very fine scale. The visual rendering informs rapidly the user of an unusual layout and therefore hints to look on some regions with unexpected patterns. On the Fig. 12 is plotted a snippet of the timeline of a small run with SMT (2 threads per core, 24 MPI processes, 8 threads per MPI process, meaning 4 nodes hosting 48 threads within each node). We can extract the following information:

1. The 2D advection kernel (first computationally intensive part of the code) is surprisingly full of small black holes.
2. There are several synchronizations during this timeline between MPI processes that are noticeable. As several moderate load imbalances are also visible, a performance penalty can be induced by these synchronizations. See for example 2D advection and Transpose steps (Useful duration plots), there is much black color

at the end of these steps. This is due to final MPI barriers. Nevertheless the impact is relatively low in this reduced test case because the tool reported a parallel efficiency of 97% over the entire application indicating that only 3% of the iteration time is spend on the MPI and OpenMP parallel runtimes. The impact is stronger on larger cases, because load imbalance is larger.

3. The transpose steps show a lot of black regions (threads remaining idle). At the end of the phase, all the ranks are synchronized by the MPI_Barrier. Checking the hardware counters indicate the problem is related with a different IPC where the fast processes are getting twice the IPC of the delayed ones. This behavior illustrates well that SMT introduces heterogeneity of the hardware that should be handled by the application even if the load is well balanced between threads.
4. At the end of 2D advection step, a serrated form is noticeable. All the processes that straddle two different sockets are slowed down a little bit.

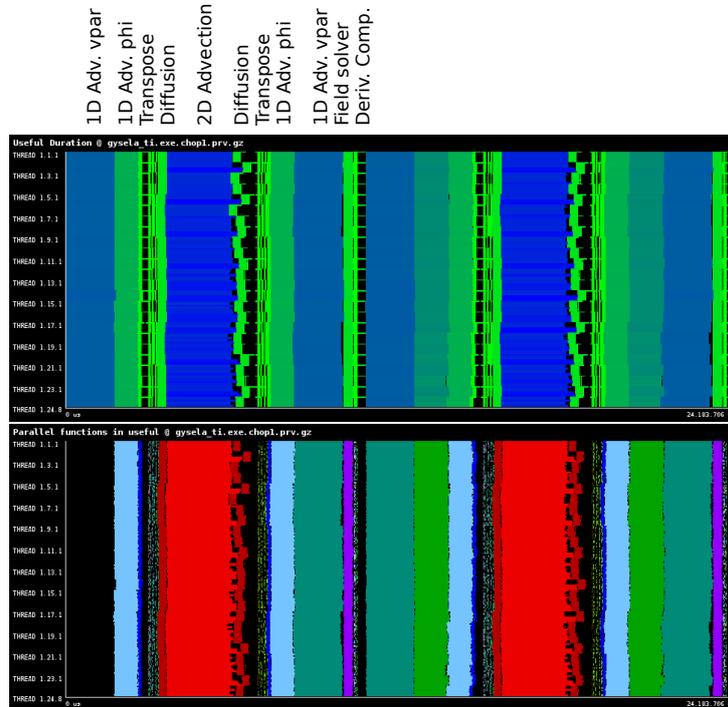


Figure 13: Snippet of a run with 2 threads per core (SMT), after optimizations are done, Top: Paraver useful duration plot, Bottom: Parallel functions plot.

These inputs from the Paraver visualization helped us to determine some code transformations to make better use of unoccupied computational resources. The key point was to point out the cause of the problem, the improvements were not so difficult to put into place. The upgrade are described in the following list. The Table 14 and Fig. 13 exhibits associated measurements.

1. The 2D advection kernel is composed of OpenMP regions. There is mainly an alternation of two distinct OpenMP kernels. The first one fills the input buffers to prepare the computation of 2D spline coefficients for a set of N poloidal planes (corresponding to different $\varphi, v_{||}$ couples). The second kernel computes the spline coefficients for the same N poloidal planes and performs the advection itself that encompasses an interpolation operator. Yet, there is no reason for having two sep-

arate OpenMP regions encapsulated in two different routines, apart from historical ones. Thus, we decided to merge these OpenMP regions in a single large one. This modification avoids the overheads due to entering and leaving the OpenMP regions multiple times. Also the implicit synchronization at the beginning and end of each parallel region are removed. Thus, avoiding synchronization leads to a better load balance by counteracting the imbalance originating mainly from the SMT effects.

2. Some years ago, with homogeneous computing units and resources, the workload in GYSELA was very balanced between MPI processes and inside them, between threads. Thus, even if some global MPI barriers were present within several routines, they induced negligible extra costs because every task was executed synchronously with the others. In latest hardware, there is heterogeneity coming from cache hierarchy, SMT, NUMA effects or even Turbo boost. The penalty due to MPI barriers is now a key issue, and thread idle time is visible on the plot. We removed several useless MPI barriers. As a result, we see for example in Fig. 13 that, now, diffusion is sandwiched between the transpose step and the 2D advection, without global synchronization.
3. The transpose step is compounded of three sub-steps: copy of data into send buffers, MPI non-blocking send/receive calls with a final wait on pending communications, copy of receive buffers into target distribution function. On the Fig. 12, it is worth noticing that only the first thread of each MPI process is working, *i.e.* only the master thread is performing a useful work. To improve this, we added OpenMP directives to parallelise all the buffers' copies. This modification increases the extracted memory bandwidth and the thread occupancy. On the Fig. 13, the bottom plot shows that the transpose step is now partly parallelised with OpenMP.

Thanks to these upgrades, there is much less black (idle time) in Fig. 13 compared to Fig. 12. Still, MPI communications induce idle time for some threads in the transpose step and in the field solver. This can not be avoided within the current assumptions done in GYSELA. Table 14 also illustrates the achieved gain in term of elapsed time. If one compares to Table 13, the timings are reduced with one or two threads per core. Comparing one against two threads per core, the SMT gain is still greater than 20% (almost the same statement as before optimization). Now, if we cumulate the gain resulting from SMT and from the optimizations, we end up with a net benefit on execution time of 32% up to 38% depending on the number of nodes.

Table 14: Time measurements and gains achieved after optimizations that remove some synchronizations and some OpenMP overheads.

Number of nodes/cores	Exec. time (1 th/core)	Exec. time (2 th/core)	Benefit of SMT	Benefit vs. Table 1
22/ 512	1266s	931s	-26%	-32%
43/1024	631s	474s	-25%	-33%
86/2048	320s	239s	-25%	-34%
172/4096	164s	124s	-25%	-38%

Much of this work has been published in a paper <https://doi.org/10.1145/2929908.2929912> entitled *Benefits of SMT and of Parallel Transpose Algorithm for the Large-Scale*

GYSELA Application.

In addition to these upgrades, we have modified the code to remove the constraint of having a power of two concerning the number of threads within a MPI process. This has been a bit of work to modify some algorithms, but the reward is that we can now avoid MPI processes that straddle two different sockets. Typically we now put 2 MPI processes per socket and 2 threads per core for production runs. Avoiding the straddling allows us for an extra saving of 5% on the total execution time.

To conclude, the use of SMT has decrease run times by 24%, whereas additional optimization done in the framework of this application support brought an additional 16% of reduction. Then, this optimization work consitutes a strong benefit for the user of Gysela application. Modifications has been included in the production code in January of 2016. The amount of core-hours consumed in 2016 on machines that have Hyper-threading/SMT activated was 40 millions for Gysela code. One can estimate that this application support has saved at least 6.4 millions of core-hours in 2016 and direct SMT use has saved 9.6 millions of core-hours.

Auto-tuning

Portability of performance with static auto-tuning. Within a single HPC application, multiple aims concerning the source code should be targeted at once: performance, portability (including portability of performance), maintainability and readability. These are very difficult to handle simultaneously. A solution is to overhaul some computation intensive parts of the code in introducing well defined kernels. BOAST (Bringing Optimization Through Automatic Source-to-Source Transformations, developed by INRIA project-team CORSE, part of WP1) is a metaprogramming framework to produce portable and efficient computing kernels. It offers an embedded domain specific language (using ruby language) to describe the kernels and their possible optimization. It also supplies a complete runtime to compile, run, benchmark, and check the validity of the generated kernels. BOAST has been applied to some of the most computation intensive kernels of Gysela: 1D and 2D advection kernels. It permitted to gain speedup from $1.9\times$ up to $5.7\times$ (depending on the machine) on the 2D advection kernel which is a computation intensive of the code. Furthermore, BOAST is able to generate AVX-512 instructions on INTEL Xeon Phi KNL in order to get high performance on this architecture. A specific point to take into account with this approach is to handle the integration of Ruby code within the production/legacy code. This optimization work saves in average 8% of computation time over the total execution time, integration into production code will be carried out soon. This activity was part of the CEMRACS school where WP1 and WP5 people have met (<http://smai.emath.fr/cemracs/cemracs16>). A proceeding paper has been submitted that describes this auto-tuning approach for the GYSELA application.

Portability of performance with dynamic auto-tuning. Another option for performance portability is to use auto-tuning at runtime. Compared with static auto-tuning, this dynamic approach incurs more overhead at runtime but it is able to leverage information that only becomes available at execution. The result of these different compromises is that the dynamic approach makes sense at a coarser grain than the static approach and that is therefore interesting to combine both. In the case of Gysela, we have implemented this approach based on the StarPU runtime developed in Inria project-team STORM (related to WP1 contribution). The whole 2D advection of which the kernel optimized with

BOAST is a part has been ported to use the native StarPU API for parallelisation instead of OpenMP. This new approach makes it possible to express parallelism at a grain that would be complex to express in the previously used OpenMP fork-join model and thus improve cache usage. StarPU should also improve performance portability by letting execution choices be made in the StarPU scheduling plug-in rather than in the application code. The scheduling plug-in can take into account informations about the available hardware and can even be changed for different executions. Some preliminary evaluations on the Poincare cluster have demonstrated a 15% speedup on a realistically sized case compared to the version using OpenMP fork-join. This optimization can not be included in production code for the moment. This work has also been described in the proceeding paper of the CEMRACS school.

Extending Input/Output capabilities for checkpoint

On large configurations, one significant cost is caused by writing and reading checkpoint/restart files. To access new physics as kinetic electrons, computational domain is increased a lot and it requires much more resources and I/O capabilities. A specific support has been asked to EoCoE to improve GYSELA on this matter. The main goals are to reduce these Input/Output expenses and add new capabilities in order to: have access to several libraries to handle different checkpoint file format to perform comparisons, improve the maintenance of the code dedicated to the coupling with I/O libraries, add a new feature to GYSELA in order to be able to restart from files generated with another domain decomposition and/or grid size.

This activity has began in Q4 2016 and will end in Q3 2017. The following tasks have been done so far: 1) Incorporate calls to SIONlib to write/read restart files in Gysela, 2) Allow for Gysela restarting with a different MPI domain decomposition that was used for checkpointing (with HDF5), it implies that the code should handle the reading of 5D distribution function whatever the number of files used for storing the distribution function, 3) PDI is a Parallel Data Interface that decouples parallel code from I/O libraries, integration of PDI within GYSELA has started together with the development of SIONlib and HDF5 plugins.

6. MDFT

The molecular density functional theory and its associated code MDFT are a disruptive way of tackling the problem of the embedding medium at the molecular scale. It computes *fast* the solvation structure (where are solvent molecules) and solvation free energy (how much does it cost to embed) of any object in water.

The code is originally serial.

6.1 Performance metrics

Code team:

- Yacine Ould Rouis & Matthieu Haefele (MdlS) for WP1
- Cedric Gageat & M. Levesque (MdlS) for WP3

The representative benchmark: “benchmark_mid”:

Domain size	128*128*128*84
Solute size	1960 sites
Resources	1 node
IO details	All the output are written at the end (1 GB)
Comments	typical targeted production run, initially takes few tens of minutes, and uses 10 GB memory. It was chosen as a reference case for the performance evaluation

Table 15: Performance metrics for MDFT on the JURECA HPC system - Compiler: gfortran - case: benchmark_mid.

	Metric name	Initial (01'2017)	After app support (03'2017)			
		w/o OpenMP	w/o OpenMP	threads		
				4	8	24
Global	Total Time (s)	1529	843	287	190	120
	Time IO (s)	2.42	1.61	1.63	1.97	1.91
	Time MPI (s)	-	-	-	-	-
	Memory vs Compute Bound	-	-	-	-	-
	Load Imbalance (%)	-	-	15.07	17.70	44.21
IO	IO Volume (MB)	1094.79	1070.23			
	Calls (nb)	278102	271851			
	Throughput (MB/s)	452.24	665.92	655.83	543.99	560.67
	Individual IO Access (kB)	4.03	4.03			
Node	Time OpenMP (s)	-	-	262.51	157.03	80.99
	Ratio OpenMP (%)	-	-	89.7	81.6	67.4
	Synchro / Wait OpenMP (s)	-	-	10.33	12.77	18.45
	Ratio Synchro / Wait OpenMP (%)	-	-	3.97	8.31	23.15
Mem	Memory Footprint (GB)	N.A.	10.28	10.25	10.25	11.01
	Cache Usage Intensity	0.50	0.50	0.45	0.48	0.59
Core	IPC	2.15	2.08	1.99	1.72	1.35
	Runtime without vectorisation (s)	1530	844	288	194	121
	Vectorisation efficiency	1.00	1.00			

6.2 Application support

The application support on MDFT focuses on the introduction of OpenMP multithreading, and a general improvement of the code's quality and its core-level performance. The work has been conducted based on the conclusions of the performance evaluation. Its success is due to the strong implication and the close collaboration of the MDFT team.

In the following, I describe point-by-point the different actions and steps taken in this work, and expose the results at the end.

Activity type	WP1 support
Contributors	Y. Ould-Rouis (WP1), M. Levesque (WP3), C. Gageat (WP3)

Main obstacles

- Defining a relevant benchmark: It is a major step in every project, to design a test case close to the production use in respect to memory and bandwidth usage, the type of calculations, the IO volumes and frequency, and the calculations reproducibility. In this case, we first had to determine a big case that does not exceed the available memory. We also had to replace the L-BFGS minimizer with a fix number of simulations, in order to reproduce the same number of iterations independently from rounding errors (*next point) introduced by different compiling options, or changes in the code. We later redefined the input, adding a non trivial molecule in order to reveal the real behavior of the lennard Jones forces calculation.
- Rounding precision: If the simple precision was validated as suitable for small grids, the tests we conducted on benchmark_mid, and especially when changing compiler, or changing the order of a reduction operation (sum), revealed very big disparities. It was then decided to return to double precision for such big cases.
- The introduction of openmp caused some bugs (catastrophic errors) related to the use of some "block" statements (introduced in Fortran 2008).

Work description

1. **energy_cproj_mrso** handles a four dimensional array, $\text{delta_rho}(\text{angles}, x, y, z)$, through five main parts. Each step computes calculations, accessing this array in a different order. Each of these parts was distributed separately:
The first and fifth parts call, for each space cartesian coordinate (x, y, z), the subroutines *angl2proj* and *proj2angl* on the (already contiguous) angles array. These functions had to be adapted to an omp distribution on the space coordinates (z), by making them reentrant (thread safe): the global variables used in these functions in order to save allocation time in, up to now, exclusively serial executions, had to be replaced with inner variables, respecting the stack memory size (allocation on the heap when needed), and calls to *fftw_execute* routines had to be replaced by thread safe forms of these routines². The cost of these necessary modifications was +4.2% on *angl2proj* time and +15% on *proj2angl* time, mainly due to the allocs and frees. The memory overhead was negligible.

²http://www.fftw.org/fftw3_doc/Thread-safety.html

The second and fourth parts of *energy_cproj_mrso* compute, for each angle, three dimensional dfts using fftw. This operation requires, for each angle, a copy of the values of *delta_rho* for all space coordinates into a contiguous 3 dimensional array, and a copy back to the initial array after the dft calculation. In our case, this array represents 128^3 double precision values, and has to be stored on the heap. The *fftw_execute* routines were already in their thread safe form.

Finally, the third and costliest part of *energy_cproj_mrso* was distributed without notable difficulties, as the calculations made on every orientation and cartesian coordinate were totally independant.

This OpenMP distribution results in a speedup of *energy_cproj_mrso* of roughly 6 times on 8 threads, and 11 times on 24 threads.

2. The first profiling results with a big Lysozyme solute molecule (1960 sites) showed an unexpected amount of time spent calculating the Lennard Jones forces (in **calcul_lennardjones**). In the light of these measurements, the code holders identified a big optimization potential consisting in the implementation of the water model case separately from the general case. This particular case, that represents the big majority of the target use, only takes into consideration the interaction between the oxygen atoms. The result is more than 70% improvement on this routine, which makes the total run 36% faster.
This step also solved an overhead problem caused by the log function calls when introducing OpenMP on JURECA: *ieee754_log_avx* alone slowed down *calcul_lennardjones* from 750 to 1200 seconds in the passage from no openmp to 1 openmp thread. This overhead has totally disappeared. An eye has to be kept on this issue for the general solute (non water) case.
3. About the introduction of OpenMP in **calcul_lennardjones**, the first choice was to distribute the loop on the number of sites. This allowed a good load balance, but caused calculation errors in a case where the number of sites was inferior to the number of threads. This issue still needs to be investigated, and meanwhile, it was replaced by a less advantageous distribution on an inner loop (on the z coordinates). The difference, due to the inbalance and a repetitive threads initialization (for every molecule site) is estimated to 5% on the whole run time (this translates, on 24 threads, in x4 more time spent in the OpenMP barriers of this loop). After this step, *calcul_lennardjones* has a speedup of 4.2 on 8 threads, and 8.5 on 24 threads compared to a serial run.
4. A serial optimization has been identified in the calculation of rotation matrices between spherical harmonics. This routine is called in the third part of *energy_cproj_mrso*, for every angular and cartesian coordinate. It contains a part of invariant small arrays initialization and calculation that become expensive with the redundance after hundreds of millions of calls. The factorization of these small calculations at the beginning of the simulation allowed a gain of 55% on **rotation_matrix_between_spherical_harmonics_lu**, resulting in 9% improvement of *energy_cproj_mrso*
5. After the distribution of the largest parts of the code, the Amdahl limit could be lowered by the distribution of smaller hotspots, like **Energy_ideal_and_external** and **chargedensityandmolecularpolarizationofasolventmoleculetorigin**, identified using Scalasca and Vampir trace visualization.

6. As the code is still in development phase, the code holders decided not to resort to “agressive” optimizations that would make some parts of the code harder to read or modify, for little improvement. Therefore, few parts with improvement potential were left serial, for the moment.
7. The profiles and traces at this stage also uncovered useless post-processing operations. Quoting Maximilien:

“At first I did not understand why you were calling *histogram_3d* so many times. I would have expected less than 10 calls. In fact, for a solute containing more than few sites, it makes no sense to call *output_rdf* and thus *histogram_3d*.”

These operations, that represent 70 seconds, about 7% of the serial time at this stage, could be totally removed for solutes above a defined amount of sites.

Table 16: MDFT Improvements and scalability for each modified routine from VTune profiling, benchmark_mid, JURECA, gfortran. inclusive time expressed.

subroutine	Original serial (s)	Improved (March 2017)			
		serial (s)	serial improvement	parallel improvement: Speedup	
				8 threads	24 threads
calcul_lennardjones	756	204	-73%	4.5	8.5
energy_cproj_mrso	586	535	-8.7%	5.5	11
rotation_matrix....lu	100	45	-55%	6.5	17
angl2proj	95	99	+4.2%	5.5	8
histogram_3d	71	0	-100%		
proj2angl	63	73	+15%	6	11.5
energy_ideal_and_external	36	36		10	27.5
chargedensityandmolecular...	46	47		4	5.5
libc_malloc,int_free	15	21	+40%	2.7	3
All OpenMP regions		805		5	10
Total run	1530	850	-44%	4.5	7.5

Results

- The optimisation work results in 44% improvement in the serial code execution time, bringing it from 1530 to 850 seconds.
- The introduction of OpenMP multithreading allows a better exploitation of the calculation resources, with x3 speedup on 4 cores. The parallel efficiency drops to x4.5 speedup on 8 cores, and roughly x8 on 24 cores. The Table 16 details the improvements and scalability for each hotspot.
- With a load inbalance rising to 44% on 24 threads (Table 15), and 40 seconds still serial (30% of the execution time on 24 threads), there is still room for improvement. Few regions in the code were identified as good candidates for OpenMP, but the quantity of complexity introduced in the code compared to the potential gains was not accepted in a code that is still in development and maturation phase.
- More efforts can also be put in the quality of the distribution in the different regions of the code. We talked in this chapter (Work description, point 3) about the limitations met in *calcul_lennardjones*, where a closer look at the bug could unlock a better distribution, therefore a better scalability.
- In *energy_cproj_mrso*, we can see, Figure 16, the load unbalance due to the division

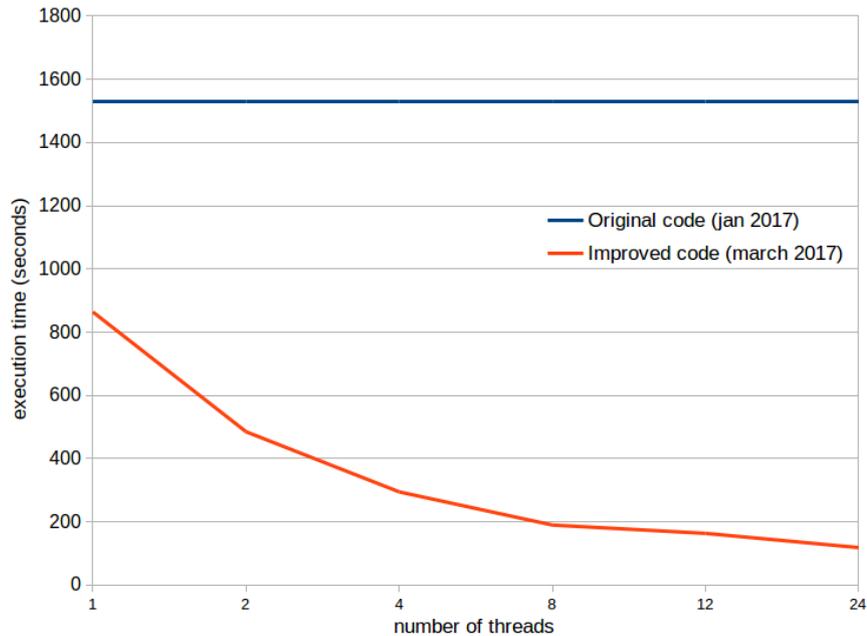


Figure 14: MDFT scalability on one JURECA node, from 1 to 24 threads, before and after application support - case: benchmark_mid.

remainder of the iterations number (here 128) on the number of cores (here 24). This can be reduced by introducing different levels of distribution on the different imbricated loops. The serial time in between successive calls totalizes 10 seconds, and can be distributed.

- We see no significant rise in memory usage (less than 10%). However, the multithreading and necessary adaptations introduced 40% increase in the allocation and deallocation time. It could be the object of advanced optimization, using preallocations for every thread.
- Following the serial optimization, the IPC rate dropped from 2.15 to 2.08 ipc. There was no improvement in terms of SIMD.
- The cache usage intensity, or in other words, the L3 cache hit rate, is still at 50%. It rises to 59% when using 2 sockets. The memory vs compute bound test gives a very small advantage to the scatter mode showing a memory-bound behavior.



Figure 15: Vampir trace of MDFT after optimization (March), on 24 threads, JURECA. Case: benchmark_mid, compiler: gfortran.

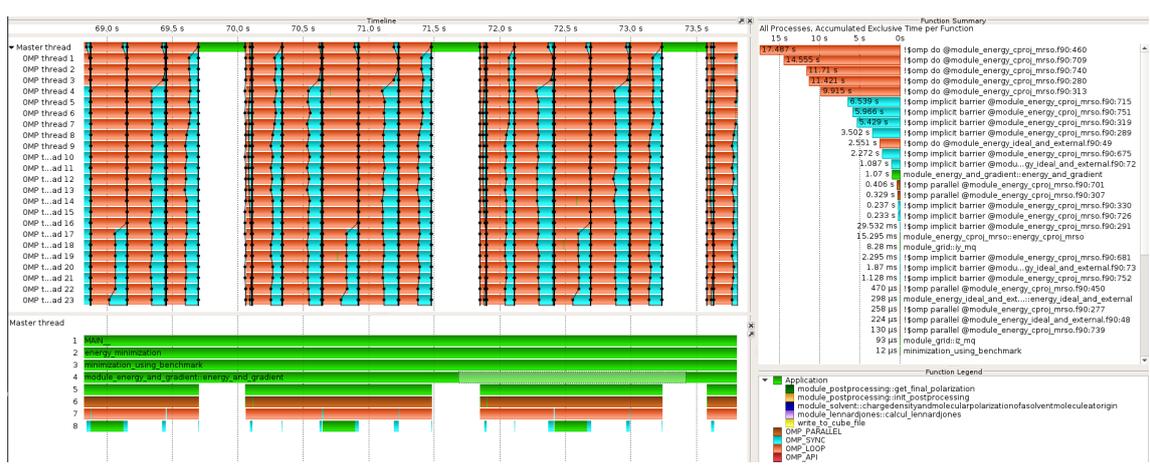


Figure 16: Zoom on successive calls to energy_cproj_mrso (and its 5 OpenMP regions), on jureca node, 24 threads. On the right, some measurements on the sample shown.

7. Metalwalls

Activity type	Consultancy and Support
Contributors	Haefele M., Marin Lafleche A

MetalWalls is a molecular dynamics simulation code dedicated to the study of electro-chemical systems. Its main originality comes from the capability to simulate electrodes held at constant potential. Currently, it is used to model nanoporous electrodes, known as super-capacitors, to better understand their behavior and improve their potential applications in the field of energy storage, energy production and desalination.

From a computer science point of view, the application follows a two steps algorithm: i) to compute the charges density within the electrodes according to the atom locations, an iterative process that requires to reach a convergence, ii) to compute the position of each atom according to the charge density. More than 90% of the total runtime is spent in the charge density computation, so this is definitely a target for the code optimization process.

In term of parallelisation, the application is pure MPI and no data is distributed across the ranks. This means that each rank has all the whole data. Only the computations are distributed such that each rank computes the interaction between a set of pairs of atoms. An MPI Allreduce sums up all these contributions and sends the result back to all MPI ranks.

7.1 Metrics

Code team:

- Matthieu Haefele (MdlS) and Abel Marin-Lafleche (MdlS) for WP1
- Mathieu Salanne (MdlS) for WP3

Case1 characteristics:

Domain size	3776 ions (walls + melt)
Resources	1 node on JURECA (24 cores)
IO details	Checkpoint written every 10 steps instead of 1000 \Rightarrow much larger than production
Type of run	both a development and small production run

Table 17: Performance metrics for Metalwalls on the JURECA HPC system.

	Metric name	03/01/2016	27/01/2017	15/12/2017
Global	Total Time (s)	43.2	10.0	8.0
	Time IO (s)	0.3	N.A	N.A
	Time MPI (s)	12.4	7.2	0.8
	Memory vs Compute Bound	1.1	0.9	1.5
IO	IO Volume (MB)	35.8	N.A	N.A
	Calls (nb)	384000	N.A.	N.A.
	Throughput (MB/s)	105.0	N.A.	N.A.
	Individual IO Access (kB)	0.1	N.A.	N.A.
MPI	P2P Calls (nb)	0	0	0
	P2P Calls (s)	0.0	0.0	0.0
	Collective Calls (nb)	2721	1408	707
	Collective Calls (s)	0.1	7.0	0.7
	Synchro / Wait MPI (s)	11.7	6.9	0.6
	Ratio Synchro / Wait MPI	94.8	93.8	38.7
	Message Size (kB)	908.4	925.7	462.9
	Load Imbalance MPI	24.8	17.8	20.8
Node	Ratio OpenMP	0.0	0.0	89.0
	Load Imbalance OpenMP	0.0	0.0	0.1
	Ratio Synchro / Wait OpenMP	0.0	0.0	2.1
Mem	Memory Footprint (MB)	66	134.3	165.6
	Cache Usage Intensity	N.A.	0.9	0.86
	RAM Avg Throughput (GB/s)	N.A.	N.A.	N.A.
Core	IPC	N.A.	0.60	0.57
	Runtime without vectorisation (s)	46.5	55.0	40
	Vectorisation efficiency	1.1	5.5	5.0
	Runtime without FMA (s)	44.6	11.0	9
	FMA efficiency	1.0	1.1	1.12

```

do i = ibeg_w , iend_w
  vsumzk0=0.0d0
  do j = nummove+1,num
    if (i==j) then
      vsumzk0=vsumzk0+q(j)*sqrpieta
    else
      zij=z(i)-z(j)
      zijsq=zij*zij
      rerf = erf(eta*zij)
      vsumzk0=vsumzk0+q(j)*((sqrpieta*exp(-etasq*zijsq))+&
        (pi*zij*rerf))
    end if
  enddo
  cgpot(i)=cgpot(i)-vsumzk0
enddo

```

Figure 17: Kernel not vectorized by the compiler

7.2 Memory footprint reduction

At several places in the code, the information if the interaction between two specific atoms has to be taken into account is needed. As this information depends only on the type of system simulated, in the original version, it was computed once during the code initialisation and stored. But the amount of memory required to store this information grows with N^2 , N being the number of atoms in the simulation.

The optimisation that has been implemented suppresses completely the need for this N^2 memory by recomputing this information each time it is required from existing information of size N . Now the memory footprint of the application scales linearly with the number of atoms and enables to treat larger systems. From the restitution time point of view, this optimisation had only a moderate impact as the time spent in this part of the code was not that important. Unfortunately, we could not measure the impact of this single optimisation as it has been done in conjunction with the code vectorisation.

7.3 Vectorisation

As mentioned in the performance report, the vectorization of the code could be the source of potential improvements. A careful examination of the compiler log could identify the internal loops that the compiler could not vectorise.

For instance, Fig 17 shows a kernel not vectorised by the compiler. The *if* statement introduces an issue: the iteration $j = i$ executes different code than $j = i - 1$ and $j = i + 1$. The compiler can simply not transform this code into a Single Instruction Multiple Data (SIMD) version. As a consequence, the whole j loop is not vectorised. By examining the code in the *if* and *else* branches, one can notice that the purpose of this construct is to save the evaluations of an error function, an exponential function and some multiplications. This optimisation has been likely implemented at a time where scalar processors did not have vector units. Nowadays, this construct prevents the compiler from introducing vector instructions. By removing the *if* part and keeping only the *else* part, a speedup of 2.5 could be obtained on this single kernel.

Other code modifications enabled the compiler vectorization and now, thanks to Intel Advisor, we could check that all the kernels in the high computing intensity part of Metalwalls

are vectorised by the compiler.

7.4 Cache blocking

During the porting of Metalwalls on Intel Xeon Phi KNL architecture, we observed larger run times than expected for some routines and especially the *cgwallrecipE* routine. After an examination with the memory analyser of VTune, it turned out that these routines were almost compute bound on Xeon architectures and became memory bound on KNL. A careful examination of the source code revealed that several large arrays were accessed within the same kernel. These large arrays were still fitting in the L3 cache of Xeon processors but, as there is no L3 cache on KNL, these arrays could not fit into L2 cache. As a consequence, the kernel triggered a large amount of memory transfer and, despite the considerably large memory bandwidth of KNL's MCDRAM, the execution time of this kernel on KNL was larger by a factor of 8.

A cache blocking mechanism has been implemented on this kernel. Instead of performing computations on the total size of the arrays, computations are performed only on a subset such that the sum of all these subsets fit into the cache. The implementation was not completely trivial as a reduction of some of these arrays was performed inside the kernel and used directly in the kernel. The kernel had to be split in two and an intermediate data structure that accumulates the partial reductions had to be introduced. The overhead in memory of this data structure is negligible and we could recover very good performance on this specific routine.

7.5 Hybrid MPI/OpenMP parallelisation

An hybrid MPI/OpenMP version of Metalwalls has been implemented by added OpenMP directives to the existing code base. Figures 18 and 19 shows the basic additions to the code base in order to add OpenMP support.

The performance of the hybrid version was evaluated on two different machines: "JURECA", based on Intel "Haswell" 12-core E5-2680 V3 processors and "Frioul", based on Intel "Knight Landing" 68-cores 7250@1.40GHz processors. On each machine, the test case "Blue Energy" was run for 10 time steps on 2 nodes. Table 18 reports the time to solution for this test case on these two architectures. For the MPI only version, 1 MPI rank was assigned to each physical core on the nodes: 24 ranks per node on JURECA and 68 ranks per node on Frioul. For the hybrid version, the reported time correspond to the best configuration of rank per node and threads per rank assignment. On JURECA, this corresponds 8 tasks per node and 3 threads per tasks, on Frioul this corresponds to 17 tasks per node and 8 threads per tasks, where the SMT 2 mode is activated. The hybrid MPI/OpenMP version improve the time to solution by 6% on a Haswell architecture and by 20% on a KNL architecture compared to the MPI only version. On top of that, as can be seen on Figure 20, the hybrid version enables a better scalability since less MPI rank per nodes are used.

7.6 GPU offloading with OpenACC

A PATC workshop on "Performance portability for GPU application using high-level programming approaches" kickstarted the introduction of OpenACC directives in Metalwalls. The performance of MetalWalls on GPUs was evaluated on Ouessant, an IBM OpenPower prototype which is based on IBM Power8+ processors and NVidia P100 GPUs (Pascal). A speedup of 1.76 was observed when offloading the code to 1 NVidia P100 GPU versus

```

1 !$omp parallel
2 !$omp do reduction(+:Potential) schedule(dynamic) &
3 !$omp private(j, potj, qj, i, rij, rijNormSquare, rijNorm, erfcFactor, potj)
4 do j = 2, numParticles
5   potj = 0.0d0
6   qj = q(j)
7   do i = 1, j-1
8     rij(:) = r(:,j) - r(:,i)
9     rijNormSquare = dot_product(rij(:),rij(:))
10    if(rijNormSquare < rijNormSquareMax) then
11      rijNorm = sqrt(rijNormSquare)
12      erfcFactor = (erfc(alpha*rijNorm) - erfc(eta*rijNorm)) / rijNorm
13      potj = potj + q(i) * erfcFactor
14      Potential(i) = Potential(i) + q(j) * erfcFactor
15    end if
16  end do
17  Potential(j) = Potential(j) + potj
18 end do
19 !$omp end do
20 !$omp end parallel

```

Figure 18: Kernel RealE with OpenMP directive

```

1 !$omp parallel
2 !$omp do reduction(+:SkCos, SkSin) &
3 !$omp private(particleBlock, iStart, iEnd, kMode, kNormSquare, i, rdotk)
4 do particleBlock = 1, numParticleBlocks
5   iStart = (particleBlock-1)*blockSize + 1
6   iEnd = min(particleBlock*blockSize, numParticles)
7   do kMode = 1, numKModes
8     kNormSquare = dot_product(k(:,kMode), k(:,kMode))
9     if (kNormSquare < kNormSquareMax) then
10      do i = iStart, iEnd
11        rdotk = dot_product(r(:,i), k(:,kMode))
12        SkCos(kMode) = SkCos(kMode) + cos(rdotk)
13        SkSin(kMode) = SkSin(kMode) + sin(rdotk)
14      end do
15    end if
16  end do
17 end do
18 !$end omp do
19
20 !$omp do private(particleBlock, iStart, iEnd, kMode, kNormSquare, i, rdotk)
21 do particleBlock = 1, numParticleBlocks
22   iStart = (particleBlock-1)*blockSize + 1
23   iEnd = min(particleBlock*blockSize, numParticles)
24   do kMode = 1, numKModes
25     kNormSquare = dot_product(k(:,kMode), k(:,kMode))
26     if (kNormSquare < kNormSquareMax) then
27       do i = iStart, iEnd
28         rdotk = dot_product(r(:,i), k(:,kMode))
29         Potential(i) = Potential(i) + &
30           Sk*(cos(rdotk)*SkCos(kMode) + sin(rdotk)*SkSin(kMode))
31       end do
32     end if
33   end do
34 end do
35 !$omp end do
36 !$omp end parallel

```

Figure 19: Kernel RecipE with OpenMP directive

Table 18: Time to solution (in seconds) on different architectures

Machine	MPI	MPI/OpenMP
JURECA (BDW)	82.2	77.3
Frioul (KNL)	61.4	48.8

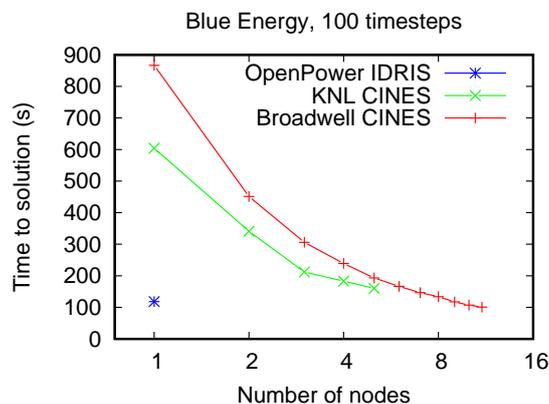


Figure 20: Time to solution for 10 iterations of the BlueEnergy test-case on different architectures

running the code on 2 nodes of JURECA (Intel "Haswell" 12-core E5-2680 V3 processor).

This performance boost was obtained in a relatively short amount of time given the lack of prior knowledge on CUDA programming from the developers of Metalwalls. Three main factors can explain this fact. First the most compute intensive parts of the code were clearly identified prior to the workshop and they break down to few kernel loops. Second, we decided to use OpenACC which is a directive-based programming model not too intrusive in the source code. Finally, we relied on the "Unified Memory" feature available on NVidia platform since CUDA 6. The latter relieves the programmer from a lot of the memory transfer and management between the host and the accelerator, which in turn can focus on loop optimization.

In Figures 21 and 22, we show the listing of the two most compute intensive kernels with OpenACC directive included. As can be seen in these figures, the impact on the code base is minimal.

7.7 Results

Metalwalls' performance has been improved by a factor 2.5. This work has been merged in the production version of the code in January 2016. 28 MCPUh have been used for Metalwalls on various Tier-0 and French Tier-1 machines during 2016, 2 MCPUh in 2017. So performing the same numerical experiments would have required 75 MCPUh without the code optimisations. This represents a saving of 45 MCPUh for the years 2016 and 2017.

Metalwalls has also been tested on Intel Xeon Phi KNL processors available at CINES³.

³<https://www.cines.fr/>

```

1 !$acc parallel
2 !$acc loop private(potj)
3 do j = 2, numParticles
4   potj = 0.0d0
5   qj = q(j)
6   !$acc loop private(rijNormSquare, rijNorm, erfcFactor) reduction(+:potj)
7   do i = 1, j-1
8     rij(:) = r(:,j) - r(:,i)
9     rijNormSquare = dot_product(rij(:), rij(:))
10    if(rijNormSquare < rijNormSquareMax) then
11      rijNorm = sqrt(rijNormSquare)
12      erfcFactor = (erfc(alpha*rijNorm) - erfc(eta*rijNorm)) / rijNorm
13      potj = potj + q(i) * erfcFactor
14      !$acc atomic update
15      Potential(i) = Potential(i) + q(j) * erfcFactor
16    end if
17  end do
18  !$acc atomic update
19  Potential(j) = Potential(j) + potj
20 end do
21 !$acc end parallel

```

Figure 21: Kernel RealE with OpenACC directive

```

1 !$acc parallel
2 !$acc loop gang
3 do kMode = 1, numKModes
4   SkCosKMode = 0.0d0
5   SkSinKMode = 0.0d0
6   kNormSquare = dot_product(k(:,kMode), k(:,kMode))
7   if(kNormSquare < kNormSquareMax) then
8     !$acc loop vector reduction(+:SkCosKMode, SkSinKMode)
9     do i = 1, numParticles
10      rdotk = dot_product(r(:,i), k(:,kMode))
11      SkCosKMode = SkCosKMode + cos(rdotk)
12      SkSinKMode = SkSinKMode + sin(rdotk)
13    end do
14    SkCos(kMode) = SkCosKMode
15    SkSin(kMode) = SkSinKMode
16  end if
17 end do
18
19 !$acc loop gang
20 do kMode = 1, numKModes
21   kNormSquare = dot_product(k(:,kMode), k(:,kMode))
22   if(kNormSquare < kNormSquareMax) then
23     !$acc loop vector
24     do i = 1, numParticles
25       rdotk = dot_product(r(:,i), k(:,kMode))
26       !$acc atomic update
27       Potential(i) = Potential(i) + &
28         Sk*(cos(rdotk) * SkCos(kMode) + sin(rdotk) * SkSin(kMode))
29     end do
30   end if
31 end do
32 !$acc end parallel

```

Figure 22: Kernel Recipe with OpenACC directive

It turns out that on 4KNL nodes, the code is faster by 40% compared to 4 Intel Haswell nodes.

The more recent developments have been merged into the production version of the code in January 2018. The hybrid MPI/OpenMP parallelization of the code will enable to run with a higher number of nodes. Indeed since less MPI ranks are assigned per nodes, scalability holds for a higher count of nodes. Additionally the addition of OpenMP directive enable the user to leverage the power of the SMT mode of more recent architectures. The work initiated to obtain a GPU version of Metalwalls is very promising. Indeed 1 NVidia P100 GPU is 1.76 times faster than 2 nodes of JURECA.

The fact that the code requires a very small amount of memory and presents high complexity algorithms helps considerably in achieving these good results.

8. PVnegf

Current implementation:

Activity type	Assessment of OpenMP implementation and performance optimization
Contributors	Thomas Breuer, Brian Wylie, Sebastian Lührs, Urs Aeberhard

Starting from a serial version of PVnegf a parallel implementation with OpenMP has been developed.

External work inspired by EoCoE:

Activity type	Hybrid MPI-OpenMP parallelisation of core modules in PVnegf
Contributors	Sebastian Achilles, Edoardo Di Napoli, Urs Aeberhard

Some core modules of PVnegf have been designed and implemented from scratch with MPI and OpenMP parallelisation. This code is successfully tested on the full JUQUEEN system.

8.1 Description of the code

Central to the prediction of material properties for solar cells is the utilization of an accurate and versatile simulation software intended to treat all of the relevant processes on equal footing and enabling an efficient exploration of the parameter space. Simulations based on NEGF provide unique physical insight, but they are also computationally demanding especially when the target are simulations of real-world heterojunctions. On the other hand, the exploration of parameter-space would require high-throughput accurate simulations. Consequently, one of the keys to successfully predict material properties is a highly efficient and optimized numerical implementation. A blueprint of such an implementation is provided by the 1D-NEGF code.

The code 1D-NEGF is the result of a master thesis focused on proof-of-concept optimizations. It was developed from scratch to get familiar with the algorithm and implement an efficient code based on the underlying framework. The PVnegf code, recently developed at the IEK-5, can simulate a variety of physical properties, due to the possibility to configure the couplings between the dynamical player of the non-ballistic model. However PVnegf offers only shared memory parallelisation, and is thus limited to a single node. In the master thesis we have developed a new simplified version of the PVnegf code, termed 1D-NEGF, with the aim of obtaining an efficient and scalable implementation for the NEGF framework. Despite the fact that the 1D-NEGF currently contains only a subset of features of the original PVnegf code, the long-term goal is to blueprint the design principles of 1D-NEGF to improve the PVnegf code.

The 1D-NEGF implementation does only contain unipolar single-band simulations containing only interaction between electrons and phonons. Therefore only simulations with reduced physics can be performed. However the insights of the parallelisation can be used also to implement and parallelise other interactions and features. The underlying data structure and data distribution stays the same, so that the parallelisation strategy of the proof-of-concept code could be blueprinted and adopted to the PVnegf code. The distributed memory parallelisation allows not only to compute results much faster by using more resources, but also to compute bigger, and so more realistic, system sizes as well as increased accuracy through the possibility to study finer grid sizes. The complexity of simulations of real-world nanostructures leads to an exascale problem.

8.2 Code Performance

The Code is portable between different architectures, since it only depends on a efficient BLAS and LAPACK library, which is available on every modern supercomputer installation. The performance and availability has been tested on quite different architectures: Intel Xeon Haswell on JURECA, Intel Xeon Phi (KNL) on JURECA booster and Blue Gene/Q on JUQUEEN. In the following these results are presented. The 1D-NEGF code is based on the use of the hybrid MPI + OpenMP parallelisation.

JURECA

In Figure 23 we show the speedup results of the 1D-NEGF code with only one outer and one inner loop (= 1 step). This test was performed on JURECA with a system size of $N_K = 32$, $N_E = 4096$, and $N_P = 100$. Up to 1024 nodes have been used. In this scaling test, we have used 1 MPI task per node and 48 threads per task.

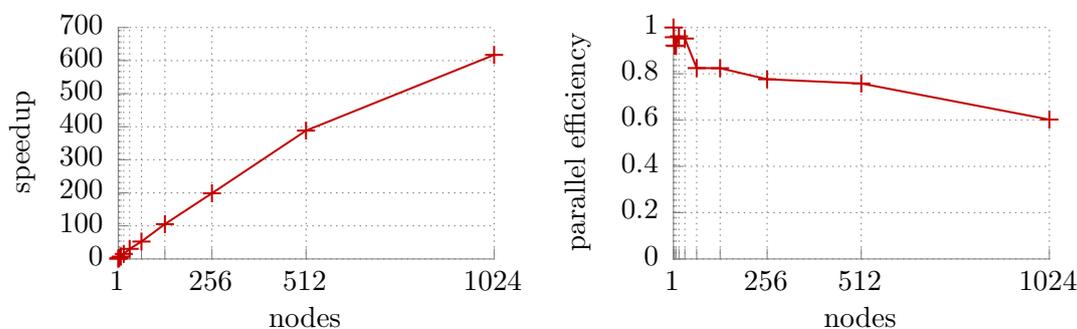


Figure 23: Scaling behaviour (left) and efficiency (right) of one outer and one inner SCF loop of 1D-NEGF on JURECA at JSC. This data was obtained with a problem size of $N_K = 32$, $N_E = 4096$, and $N_P = 100$.

JURECA booster

The program also scales on the booster. This test was performed with a system size of $N_K = 32$, $N_E = 480$, and $N_P = 100$. Up to 48 nodes have been used. In this scaling test, we have used 1 MPI task per node and 64 threads per task. The current job profile contains independent jobs. Different operation points are submitted with a bash script as individual jobs.

JUQUEEN

For large scaling results, we show in Figure 25 the speedup results of one inner loop. This test was performed on JUQUEEN with a system size of $N_K = 2048$, $N_E = 5376$, and $N_P = 100$. Up to 458752 cores with 2-way SMT have been used.

8.3 JUBE metrics

For the JUBE metrics a small input file with $N_K = 32$, $N_E = 128$ and $N_P = 100$ was used. On JURECA 16 nodes with 1 MPI rank and 24 OpenMP threads each have been

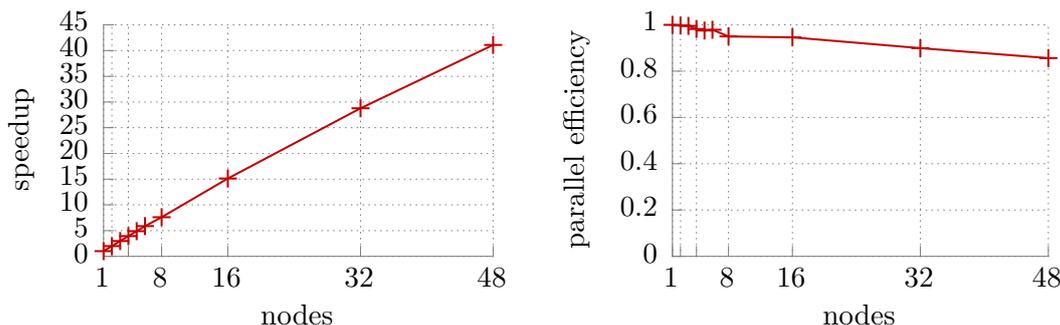


Figure 24: Scaling behaviour (left) and efficiency (right) of one outer and one inner SCF loop of 1D-NEGF on the booster at JSC. This data was obtained with a problem size of $N_K = 32$, $N_E = 480$, and $N_P = 100$.

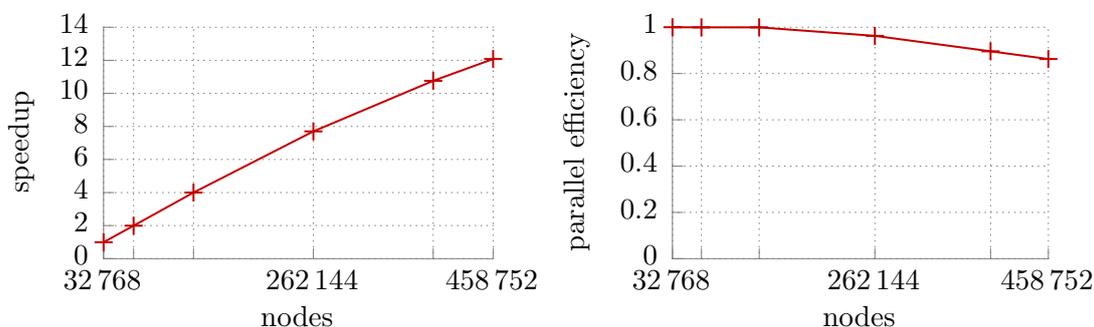


Table 19: Performance metrics for 1D-NEGF as measured on JURECA with 16 nodes running 1 MPI ranks and 24 OpenMP threads each. Note that the 'Core' section is misleading, see text for details.

	Metric name	1D-NEGF
Global	Total Time (s)	43
	Time IO (s)	0.00
	Time MPI (s)	0.29
	Memory vs Compute Bound	0.98
	Load Imbalance (%)	65.59
IO	IO Volume (MB)	0.02
	Calls (nb)	0
	Throughput (MB/s)	7.19
	Individual IO Access (kB)	0.00
MPI	P2P Calls (nb)	1200
	P2P Calls (s)	0.21
	P2P Calls Message Size (kB)	26
	Collective Calls (nb)	4
	Collective Calls (s)	0.02
	Coll. Calls Message Size (kB)	2
	Synchro / Wait MPI (s)	0.13
	Ratio Synchro / Wait MPI (%)	1.92
Node	Time OpenMP (s)	10.93
	Ratio OpenMP (%)	25.00
	Synchro / Wait OpenMP (s)	1.36
	Ratio Synchro / Wait OpenMP (%)	13.71
Mem	Memory Footprint	1459488kB
	Cache Usage Intensity	0.98
Core	IPC	0.64
	Runtime without vectorisation (s)	42
	Vectorisation speedup factor	0.98
	Runtime without FMA (s)	44
	FMA speedup factor	1.02

9. Parflow

Short description

ParFlow is a parallel physics-based integrated watershed model, which simulates fully coupled, dynamic 2D/3D hydrological, groundwater and land-surface processes suitable for large scale problems. ParFlow is used extensively in research on the water cycle in idealized and real data setups as part of process studies, forecasts, data assimilation experiments, hind-casts as well as regional climate change studies from the plot-scale to the continent, ranging from days to years. Saturated and variably saturated subsurface flow in heterogeneous porous media are simulated in three spatial dimensions using a Newton-Krylov nonlinear solver [3, 8, 17] and multigrid preconditioners, where the three-dimensional Richards equation is discretised based on cell-centered finite differences. ParFlow also features coupled surface-subsurface flow which allows for hillslope runoff and channel routing [12]. Because it is fully coupled to the Common Land Model (CLM), a land surface model, ParFlow can incorporate exchange processes at the land surface including the effects of vegetation [18, 11]. Other features include a parallel data assimilation scheme using the Parallel Data Assimilation Framework (PDAF) from [20], with an ensemble Kalman filter, allowing observations to be ingested into the model to improve forecasts [14]. An octree space partitioning algorithm is used to depict complex structures in three-dimensional space, such as topography, different hydrologic facies, and watershed boundaries. ParFlow parallel I/O is via task-local and shared files in a binary format for each time step. ParFlow is also part of fully coupled model systems such as the Terrestrial Systems Modeling Platform (TerrSysMP) [24] or PF.WRF [19], which can reproduce the water cycle from deep aquifers into the atmosphere. ParFlow is written in C and CLM is written in Fortran 90 (117000 lines of C code and 20000 lines of Fortran code) and parallelised using MPI. The solvers currently used in ParFlow are Hypre (preconditioner) and KINSOL non-linear solver (SUNDIALS).

Code team:

- Stefan Kollet (FZJ) (WP4)
- Ketan Kulkarni (FZJ) (WP4 associated)
- Slavko Brdar (FZJ) (WP4 associated)
- Klaus G3rgen (FZJ) (WP4)
- Wendy Sharples (FZJ) (WP1)

Benchmark characteristics:

A three-dimensional sinusoidal topography as shown in Figure 26 was used as the computational domain with a lateral spatial discretization of $\Delta x = \Delta y = 1\text{m}$ and a vertical grid spacing of $\Delta z = 0.5\text{m}$; the grid size, n , was set to $n_x = n_y = 50$ and $n_z = 40$ resulting in 100 000 unknowns per CPU core, with one MPI task per core. In order to simulate surface runoff from the high to the low topographic regions with subsequent water pooling and infiltration, a constant precipitation flux of 10 mm/hour was applied. This results in realistic non-linear physical processes and thus compute times. The water table was implemented as a constant head boundary condition at the bottom of the domain with an unsaturated zone above, 10m below the land surface. The heterogeneous subsurface was simulated as a spatially uncorrelated, log-transformed Gaussian random field of the sat-

urated hydraulic conductivity with a variance ranging over one order of magnitude. The soil porosity and permeability were set to 0.25 m/day. This idealized setup was used for the profiling case study as opposed to a real world set up due to the symmetry inherent in the setup. In contrast, a real world experiment has asymmetry in both the meteorological forcing and also the model topography which naturally lead to load imbalances. These asymmetries could therefore obscure whether there are actually load imbalances due to poor software design.

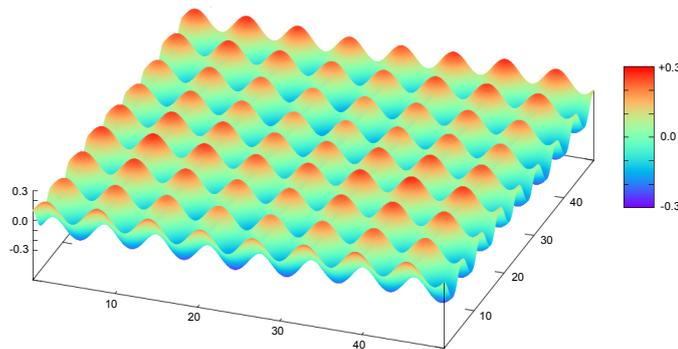


Figure 26: Model setup, showing cross-sectional domain and sinusoidal topography variation from the top of the model ($z=20$) for each processor.

Test case 1, ParFlow v320: This test uses the model described above with the current stable release. Weak scaling tests with 24 MPI ranks and 48 MPI ranks were run and the performance metrics were gathered.

Test case 2, ParFlow + p4est v320: This test uses the model described above with the current stable release integrated with p4est. p4est is integrated with ParFlow such that p4est becomes the parallel mesh manager. Weak scaling tests with 24 MPI ranks and 48 MPI ranks were run and the performance metrics were gathered.

EoCoE benchmark tables

Tables 20 and 21 show the summary of the benchmarks that have been run during the project so far. The two tables each present one of the test cases on 24 and 28 processors. The individual columns represent results from the latest stable version of ParFlow, v320 and that latest stable version integrated with p4est, using p4est as the parallel mesh manager (see Section 9).

Findings from the comparison: ParFlow integrated with p4est spends less time in communication than the stable version of ParFlow amounting to a speed up of 30%. However caution should be taken in interpreting these results as most of this reduction could be in the setup phase. Test cases with more time steps and more in depth profiling should be run in the future to confirm which routines account for the biggest speedups.

Both versions of ParFlow are compute bound, in agreement with the performance report from PoP.

If the vectorization is turned off, then the code performance is worsened, indicating that

there is a potential for serial performance improvement via vectorization. Without FMA operations the code seems to be slightly faster only in the ParFlow case and the difference could just be due to measurement fluctuations.

IO does not appear to be a bottleneck, however a more realistic test case should be used in the future to confirm this.

General comments on overall performance

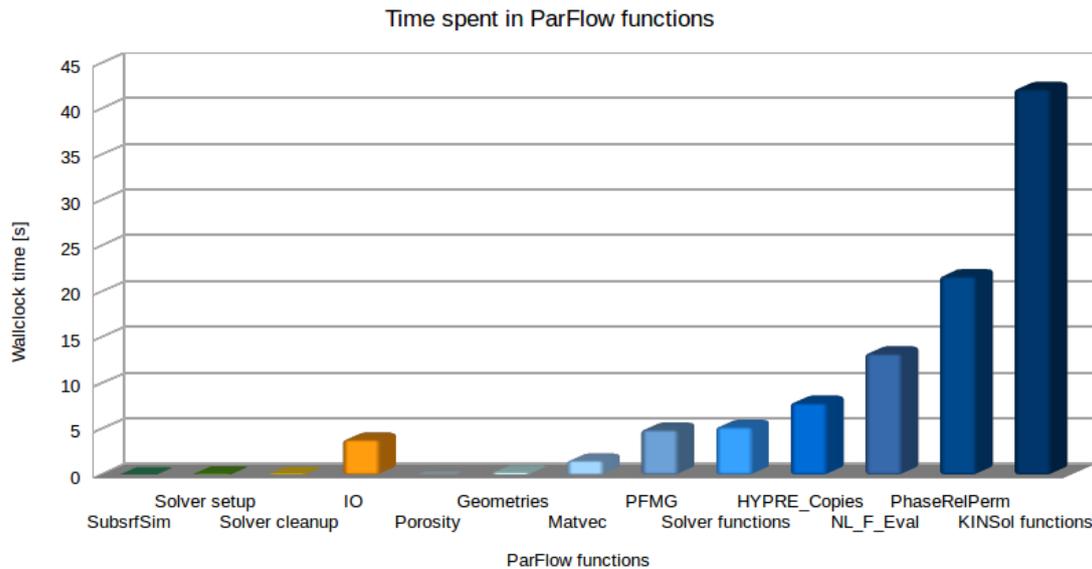


Figure 27: Time spent in ParFlow functions or routines, where the functions/routines can be divided into four categories, set up, clean up, I/O, and solve. The functions in the category "set up" are depicted in green: Subsrfsim—setting up the domain, Solver setup—initializing the solver. The functions in the category "clean up" are depicted in yellow: Solver cleanup—finalizing the solver. The functions in the category "I/O" are depicted in orange: PFB I/O—ParFlow binary I/O. The functions in the category "solve" are depicted in blue: Porosity—calculation of the porosity matrix, Geometries—calculation of the simulation domain, MatVec—matrix and vector operations, PFMG—Geometric Multigrid Preconditioner from HYPRE, Solver functions—miscellaneous functions, HYPRE_Copies—copying data within HYPRE, NL_F_Eval—setting up the physics and field variables for the next iteration, PhaseRelPerm—setting up the permeability matrix, KINSol functions—non-linear solver functions from SUNDIALS

We can see that in running test case 1 ParFlow spends large part of the execution time in the non linear solve step (see Figure 27. The performance metrics gathered show that ParFlow is compute bound and up to a certain amount of processors, ParFlow scales extremely well [13]. However from extensive profiling, it was determined that both time spent in communication and memory use become a problem at scale (see POP_AR.17.pdf). To mitigate this problem, ParFlow was integrated with the p4est, where p4est is now the parallel mesh manager. The performance metrics were gathered comparing these two versions of ParFlow to see what potential gains could be made in future simulations.

Overall, the gains made in using ParFlow + p4est are in a reduction of communication (time spent in MPI) and memory footprint. On average the time spent in communication from the performance metric tables is roughly 30%, and the reduction in time spent in communication with the ParFlow + p4est version means that potentially there could be an overall reduction of run time by up to 10%. However this could be due to the fact that setup time is a large percentage of these runs. Also in running a real case, the load imbalances are large due to inactive regions in the model and heterogeneity so this might counteract any gains. A more realistic test case needs to be run for the next support activity. The memory footprint has been reduced by at least 20% on average and this value does not increase at scale which means that ParFlow + p4est can now scale to the whole JURECA machine.

For both versions of ParFlow, the code is highly compute bound. This means that performance of ParFlow could be further improved via use of different solver libraries and configurations.

If the vectorization is turned off, then the code performance decreases, especially in the case of the ParFlow + p4est version, which indicates a potential for improving serial performance with more vectorization. Without FMA operations the code seems to be slightly faster only in the ParFlow case. However the difference is not significant.

Application support

Activity type	Consultancy (WP1 support request on-going)
Contributors	Sharples W. (Stefan Kollet, Ketan Kulkarni, Lukas Poorthuis, Ilya Zhukov, Damian Kaliszan, Michael Knobloch, Slavko Brdar, Thomas Breuer, Pasqua D'Ambra, Phillippe Leleux, Klaus Goergen, Bibi Naz)

In the following section, the application support activities are explained in chronological order.

Development of a run control framework to aid with porting and tuning, profiling and provenance tracking

In order to streamline development and support, ParFlow needed to be extensively profiled first to determine bottlenecks, scalability breakers and inefficiency. To enable efficient profiling and running of ParFlow, a run control framework (RCF) integrated with a workflow engine was developed by WP1 (Wendy Sharples) [23], as a best practice approach to automate profiling, porting, provenance tracking and simulation runs. The RCF encompasses all stages of the modeling chain:

- preprocess input,
- compilation of code (including code instrumentation with performance analysis tools),
- simulation run,
- postprocess and analysis,

to address these issues. Within this RCF, the workflow engine is used to create and manage benchmark or simulation parameter combinations and performs the documentation

and data organization for reproducibility. This approach automates the process of porting and tuning, profiling, testing, and running a geoscientific model. profiling, a run control framework was developed. In order to analyze ParFlow's runtime behavior, determine optimal runtime settings, as well as identify performance bottlenecks during model development, we used several complementary performance analysis tools. Setup, compilation wrappers, and analysis profiling steps were built into our RCF with support for the following tools: Score-P v3.1 [10] and Scalasca v2.3.1 [6, 25], where results collected with Score-P and Scalasca can be examined using the interactive analysis report explorer Cube v4.3.5 [22], Allinea Performance Reports v7.0.4 [7], Extrae v3.4.3 [2], Paraver v4.6.3 [15], Intel Advisor 2015 [21], and Darshan v3.0.0 [5]. In addition, automated metric calculation benchmark scripts whose results are shown in this report, were implemented into the RCF (Wendy Sharples with Thomas Breuer). In the future, the RCF will be updated take advantage of the new cycle feature coming up in JUBE to allow for job resubmission.

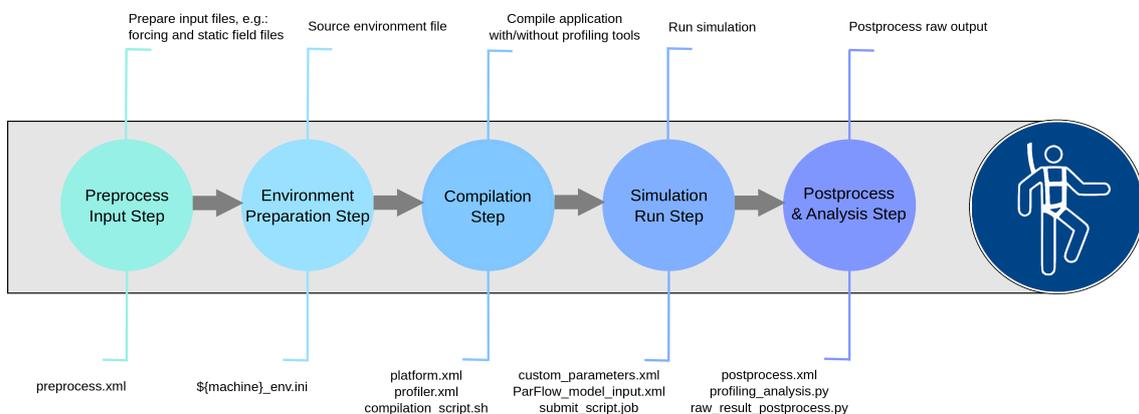


Figure 28: Schematic overview of the modeling chain as supported by our JUBE-based run harness. Each step is annotated with a brief description (top) as well as the respective RCF infrastructure (XML files and scripts, bottom).

Profiling study

Using the RCF, the specialists from the Performance Optimisation and Productivity Centre of Excellence in Computing Applications (PoP - Ilya Zhukov) performed an initial health check of ParFlow (see PoP report, POP_AR.17.pdf). The results from the profiling study show that a significant amount of time is spent in the non-linear solve step, so this was the target area for the profiling study. The profiling study showed that the main barriers to exascale were time spent in communication and memory use which informed the subsequent developments (see Section 9). This is discussed further in Section 9.

Updating ParFlow for next generation hardware

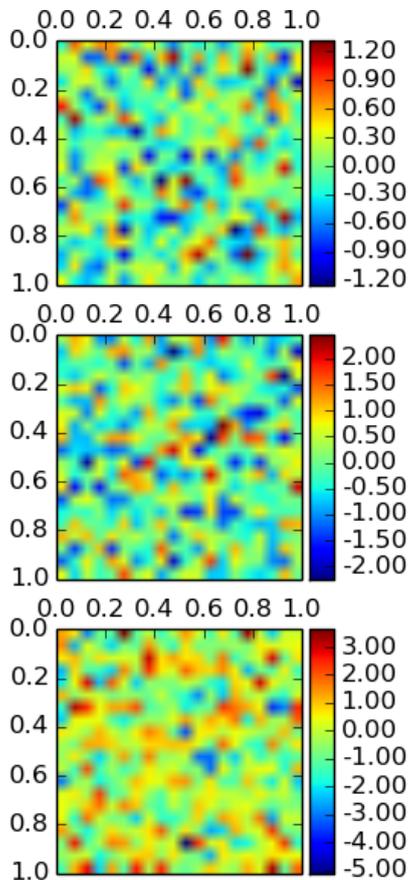
Due to the arrival of the new KNL booster for JURECA and the availability of GPUs at JSC, the application support team took a three pronged approach to getting ParFlow ready for many core, heterogeneous architecture.

(i) Development of a MiniApp:

Since ParFlow will take considerable efforts in refactoring, a MiniApp has been developed to test i) Accelerator enabled solver libraries and ii) different accelerators (KNLs, GPUs against CPUs). The MiniApp a simplified python version of ParFlow which generates a

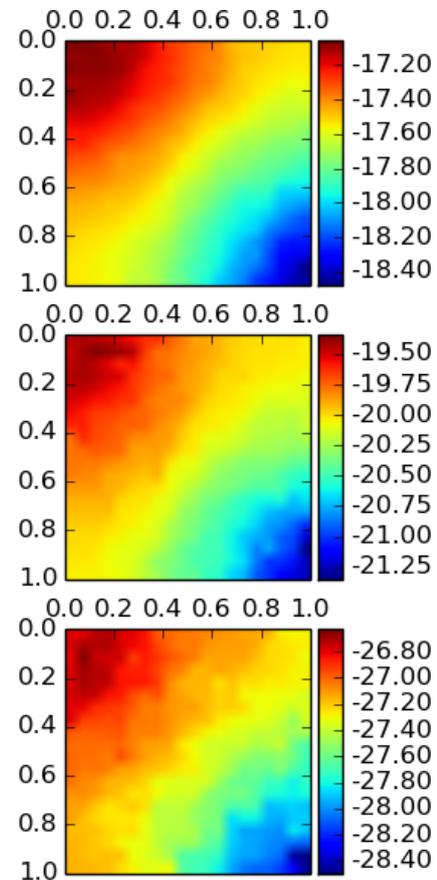
random permeability matrix and an input pressure matrix with a source and a sink and performs one linear solve. The permeability values are based on a log normal distribution where the standard deviation is set from 1 to 3. 1 meaning the least amount of heterogeneity and 3 being the most (see Figure 29, LHS showing log of the permeability). The permeability matrix is then tridiagonalized to reduce the number of arithmetic operations to become the A matrix used in $Ax = b$ solve, where the solution is shown in Figure 29 (see RHS, pressure plots) showing a solution which is not completely smooth due to the heterogeneity in A . This work is undertaken in conjunction with WP1 (Wendy Sharples, Slavko Brdar), PSNC (Damian Kaliszan), and PoP specialists (Michael Knobloch, Ilya Zhukov). Metrics such as scalability, wallclock time and serial performance is considered along with the energy delay product in assessment of each architecture's energy efficiency.

Logarithm of the Permeability Matrix



Logarithm of the Permeability Matrix

Pressure



Pressure

Figure 29: Plot of logarithm of permeability and pressure solution for a 40x40x40 problem, using the PETSc library. The standard deviation varies from 1 to 3 from top to bottom.

(ii) Investigation of state of the art linear solvers:

The A and b matrices set up by the python MiniApp were given to the linear algebra experts in WP1 at the IAC (Pasqua D'Ambra) and University of Brussels (Phillippe Leleux) where they performed a linear solve using different linear solver configurations using in-house and open source solver libraries. The results are promising but in order to be able to use these libraries further support from WP1 will be needed to create an interface in ParFlow in order to plug in and plug out different solvers and preconditioners.

More details on these results can be found in Sections 9 and 9.

(iii) Investigation of the vectorization potential of ParFlow:

ParFlow has many loops that have been implemented as macros. This means that it is difficult to determine dependencies and to determine whether these individual loops can be vectorised. Loops within two frequently used routines have been identified by the ParFlow developers as being able to be vectorized without causing inconsistencies as they have no inherent dependencies under normal running conditions. Work has started with WP1 support (Wendy Sharples, Slavko Brdar) and PoP experts (Ilya Zhukov) to redesign these loops for vectorization. This work is still ongoing. Additionally a preliminary PoP report detailing the road-map to vectorization for ParFlow and initial results from vectorization of some simple loops (which have no dependencies) is underway.

Aiding ParFlow's interoperability

To reduce time spent in preprocessing model input and post-processing binary ParFlow model output, a NetCDF reader and writer is under development, with testing of this new feature integrated into the RCF. To date, NetCDF Meteorological forcing can be read in and all output can be written in NetCDF. Future work will include integrating the NetCDF reader/writer with ParFlow tools.

External support

To reduce the memory usage and to reduce the time spent in communication, an Adaptive Mesh Refinement (AMR) library, p4est, has been implemented into ParFlow to function as the parallel mesh manager. This work was undertaken by Jose Fonseca and Carsten Burstedde at the Institute for Numerical Simulations at the University of Bonn. The approach was minimally invasive and preserves most of ParFlow's data structures, the configuration system, and the setup and solver pipeline. The current mesh manager is a barrier to scalability as it requires that all cells store information about every other cell. This is reduced to neighboring cells under p4est, which results in a decrease in memory use (storage reduction) and a decrease in time spent in communication (communication reduced to neighboring cells only), allowing ParFlow to scale over all 458,752 cores on JUQUEEN [4]. Using p4est as the parallel mesh manager has the additional potential benefit of integrating the adaptive mesh refinement functionality into ParFlow in order to address inactive regions (due to heterogeneous forcing, permeability, etc.) causing load imbalances in the real world models.

MUMPS solver for ParFlow

Activity type	WP1 support
Contributors	I. Duff (CERFACS, WP1), P. Leleux (CERFACS, WP1), D. Ruiz (IRIT, WP1), F. S. Torun (IRIT-CNRS, WP1), W. Sharples (JSC, WP4)

Overview

The target of this support activity is the optimization of the linear solver which is involved in the code ParFlow. This code is designed for the solution of large elliptic and parabolic

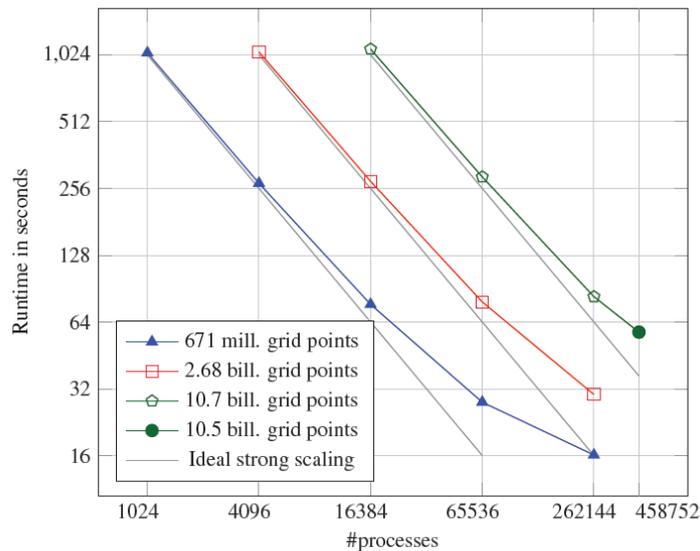


Figure 30: Scaling plot of the latest version ParFlow + p4est implementation demonstrating use of whole JUQUEEN machine. Total runtime is shown for different domain sizes shown [4].

equations on heterogeneous platforms (GPUs, KNLs, and CPUs). The linear systems are symmetric definite positive and arise from 3D finite difference discretization.

The current solution relies on a Krylov solver with a simple preconditioner (ex: Conjugate Gradient preconditioned with Block-Jacobi + Incomplete LU level 0). The largest problem solved is composed of 3.7×10^8 unknowns; the target for EoCoE2 is 3x bigger.

Method and Preliminary Results

We will not give extensive details about the use of MUMPS in this section but will focus on the use of this solver to tackle ParFlow linear systems. For more details on MUMPS principle and particularly on its latest feature: Block Low Rank Approximation (BLR), see MUMPS Section from deliverable 1.7 Software technology improvement.

Our tests were run on CERFACS cluster Nemo and CALMIP cluster EOS. Nemo consists of 1872 nodes with 128GB of memory and 2 sockets of Intel Xeon E5-2680 v3 Haswell CPUs 12-cores clocked at 2.5GHz. EOS consists of 612 nodes with 64GB of memory and 2 sockets of Intel IvyBridge processors 10-cores clocked at 2.8 GHz. In the following "P x N cores" stands for P processes with N threads each. The test case *parflow-def* used for preliminary results was the one in Table 22.

As a first approach, we tried to apply MUMPS with default parameters directly on ParFlow global system. On *parflow-def* test case, we observed that MUMPS is capable of scaling, see Figure 31). However for most applications, and ParFlow is no exception, there is no need to get a solution to machine accuracy. We can thus approximate MUMPS LU factorisation using BLR feature.

On a theoretical point of view, BLR has an asymptotic complexity of $O(n^{4/3})$ with n being the first dimension of the 3D problem. Geometric multigrid will always be a better choice on purely elliptic problems, however on different problems (ex: Helmholtz or structural mechanics) the gains compared to using an iterative scheme could be greater. For more

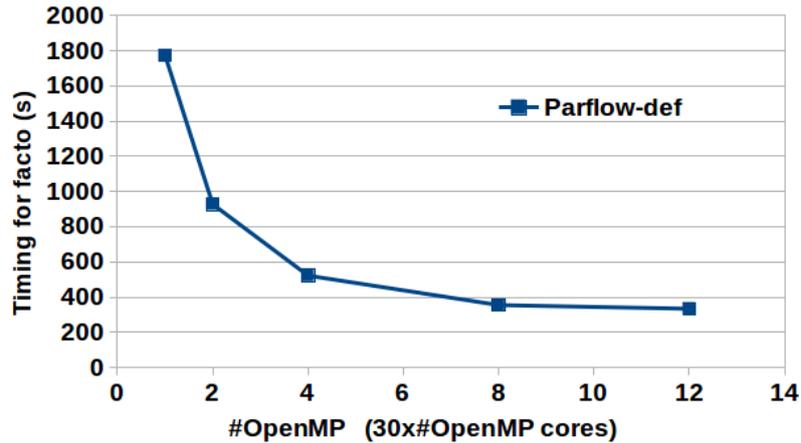


Figure 31: MUMPS factorisation phase depending on #OpenMP for ParFlow matrix *parflow-def* run on Nemo.

results, see [16].

BLR applied to ParFlow data gives particularly good results as a slight compression ($\epsilon=1 \times 10^{-16}$) is enough to already decrease flops by a factor 5 and timing by a factor 2 with no loss of accuracy on the test-case (see Figure 32). Still, with 5 minutes for a complete solve with BLR on the global system, MUMPS timings stay high compared to iterative schemes on particular problems (see Table 23). Also memory can be prohibitive: with 30x12 cores MUMPS needs 13.5GB memory on most consuming process and 12GB on average.

As a new approach to solving the linear systems in ParFlow, we decided to make use of MUMPS+BLR as a preconditioner for a simple iterative scheme.

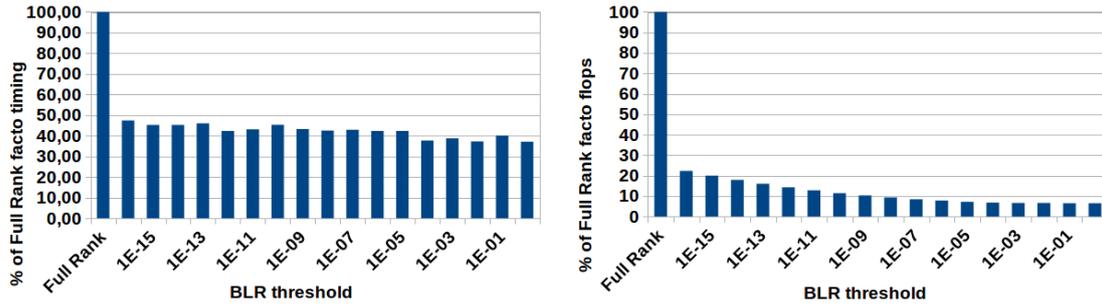
Results

In the following, we focus on an iteration of ParFlow simulation (*ex10.c*) with parameters:

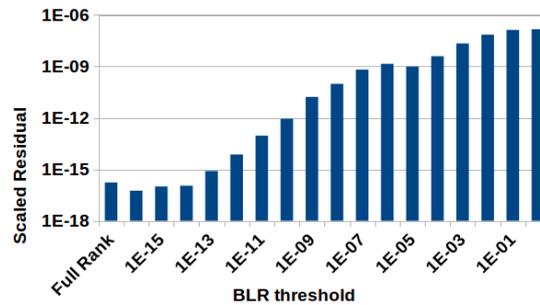
- #MPI=100,
- $H=1.0$; $N_x=N_y=160$; $N_z=120$; $num=3.0$; $atol=1 \times 10^{-15}$; $rtol=1 \times 10^{-6}$; $divtol=1 \times 10^{+5}$,
- Length of domain: $H=1.0$,
- #Cells in x,y,z: $N_x=N_y=160$ and $N_z=120$,
- Std deviation in the log-normal random number generation: $num=3$,
- Absolute/relative/diversion tolerance: $atol=1 \times 10^{-15}$, $rtol=1 \times 10^{-6}$ and $divtol=1 \times 10^{+5}$,

The method can be tested directly through PETSc using command-line options. We tried several configurations:

1. Conjugate Gradient (CG) preconditioned with Block-Jacobi (BJ) and incomplete LU level 0 (ILU0): `-ksp_type cg -pc_type bjacobi -sub_pc_type ilu`,
2. CG preconditioned with BJ and incomplete Cholesky (ICC): `-ksp_type cg -pc_type`



(a) Factorisation timing and flops



(b) Accuracy of solution

Figure 32: MUMPS used with Block Low Rank Approximation on ParFlow matrix *parflow-def* with 30x12 cores on Nemo.

bjacobi -sub_pc_type icc,

3. CG preconditioned with MUMPS(+BLR) on complete system: *-ksp_type cg -pc_type cholesky -pc_factor_mat_solver_package mumps*
4. CG preconditioned with MUMPS(+BLR) as solver for BJ subsystems:
 - *-ksp_type cg -pc_type bjacobi -pc_bjacobi_blocks 100/X -sub_pc_type cholesky -sub_pc_factor_mat_solver_package mumps,*
 - We have tried several size of BJ subdomains (see Table 24) and selected the trade-off with X MPI in MUMPS per BJ block (the default is 1 block per MPI).

To activate BLR, we only need to add the option *-mat_mumps_icntl_35 1 -mat_mumps_cntl_7 1 x 10⁻¹⁶* where 1×10^{-16} is the epsilon value.

The results are gathered in Table 25.

PSBLAS and MLD2P4 for ParFlow

Activity type	WP1 support
Contributors	Ambra Abdullahi Hassan (University of Rome “Tor Vergata”, Italy), Pasqua D’Ambra (CNR, Italy), Daniela di Serafino (University of Campania “L. Vanvitelli”, Italy), Salvatore Filippone (Cranfield University, UK), Wendy Sharples (JSC, Germany) for WP4

The improved versions of PSBLAS and MLD2P4 developed during the EoCoE project (see Deliverable D1.7) have been applied to a data set from ParFlow. The goal of this work was to provide a sound basis for the selection of solvers and preconditioners for future integration and tuning into the application code.

Data Set

The set of linear systems comes from the numerical simulation of the filtration of 3D incompressible single-phase flows through anisotropic porous media, carried out at the Jülich Supercomputing Centre (JSC) within WP4 (*Water for Energy*). The linear systems arise from the discretization of an elliptic equation with no-flow boundary conditions, modelling the pressure field, which is obtained by combining the continuity equation with Darcy’s law [1]. The discretization is performed by a cell-centered finite volume scheme (two-point flux approximation) on a Cartesian grid. The anisotropic permeability tensor in the elliptic equation is randomly computed from a lognormal distribution with mean 1 and three standard deviation values, 1, 2 and 3, corresponding to three types of systems with symmetric positive definite matrices and a classical seven-diagonal sparsity pattern, denoted by MAT1, MAT2 and MAT3. These systems can be regarded as simplified samples of systems arising in ParFlow.

First experiments were performed with matrices of dimension 10^6 and a 6940000 nonzero entries, generated by using a Matlab mini-app provided by JSC. In order to perform a weak scalability analysis, a Fortran code reproducing the mini-app was developed within WP1 to obtain larger sample matrices of the same type.

In order to assess the behaviour of different MLD2P4 preconditioners on the selected test case and choose the best ones for the application of interest, an evaluation in terms of execution time, strong and weak scalability, and linear solver iterations was carried out.

Results on the Data Set

A first set of experiments, aimed at identifying the best preconditioners available from MLD2P4 for the selected linear systems, was performed on a linux cluster, named yoda, operated by the Naples Branch of the CNR Institute for High-Performance Computing and Networking. Its compute nodes consist of 2 Intel Sandy Bridge E5-2670 8-core processors and 192 GB of RAM, connected via Infiniband. The tests were carried out on the matrices of dimension 10^6 , using 1, 2, 4, 8, 16, 32, and 64 cores, running as many parallel processes.

Figure 33 shows the execution times (in seconds) and the speedups obtained by applying the Conjugate Gradient (CG) solver available in PSBLAS with four multilevel preconditioners and a one-level block-Jacobi preconditioner from MLD2P4 (the times include the preconditioner setup). The corresponding numbers of preconditioned CG iterations are reported in Table 26. The multilevel preconditioners performed a V-cycle, using different

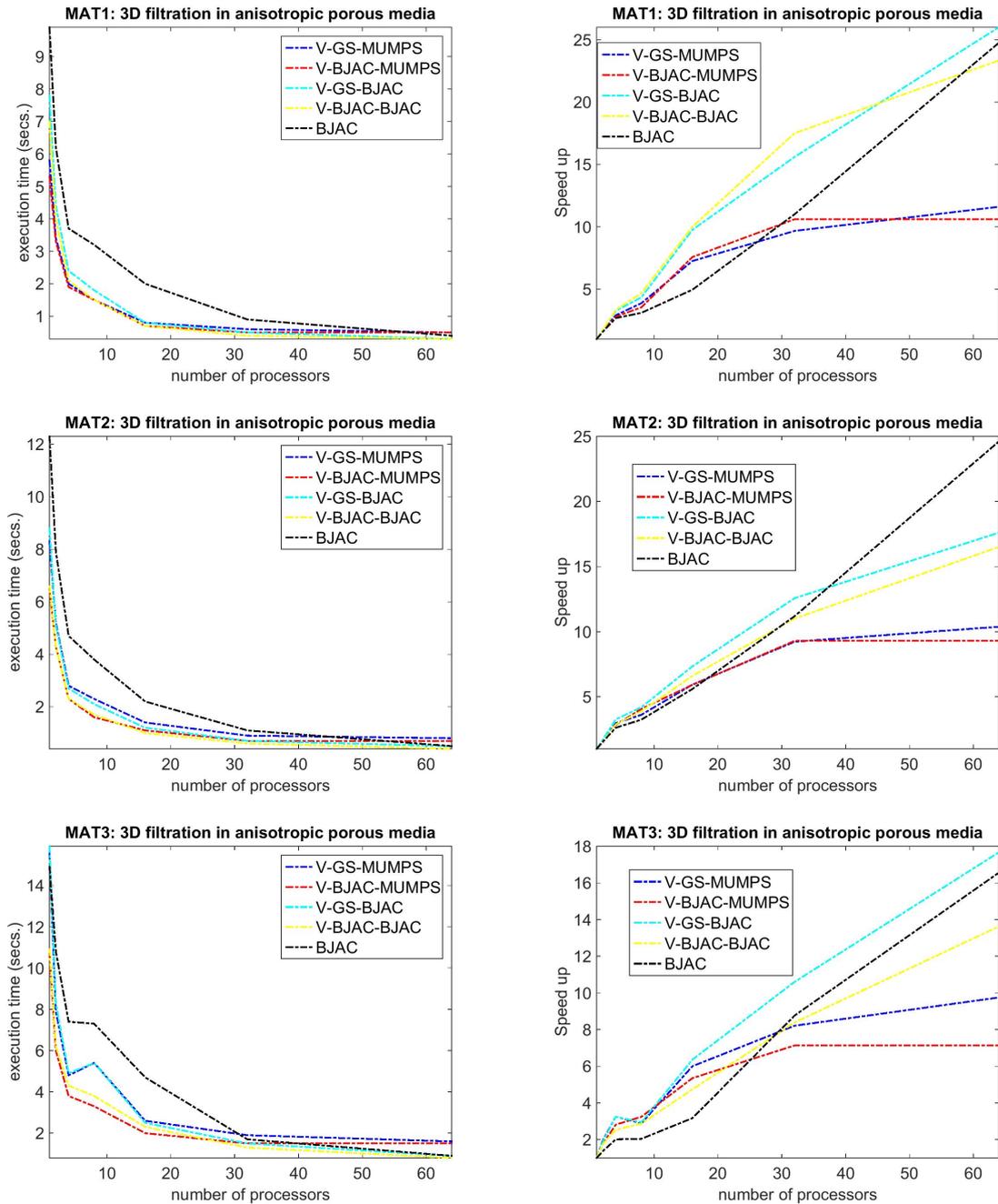


Figure 33: Linear systems from groundwater modelling: execution time and speedup on yoda. Top: MAT1, middle: MAT2, bottom: MAT3.

smoothers and coarsest-level solvers. Specifically, V-GS-MUMPS and V-BJAC-MUMPS used 1 forward/backward hybrid Gauss-Seidel sweep and 1 block-Jacobi sweep as pre/post-smoother, respectively, and applied the sparse LU factorization from MUMPS on the coarsest-level system, replicated in all the processes; V-GS-BJAC and V-BJAC-BJAC used 1 forward/backward Gauss-Seidel sweep and 1 block-Jacobi sweep as pre/post-smoother, respectively, and 10 block-Jacobi sweeps on the coarsest matrix, distributed among the processes. The ILU(0) factorization was applied to the blocks in the block-Jacobi sweeps,

in both the multilevel and the one-level preconditioners. The zero vector was used as starting guess and the preconditioned CG iterations were stopped when the 2-norm of the residual achieved a reduction by a factor of 10^{-6} . A generalized row-block distribution of the matrices, obtained by using the METIS graph partitioner [9], was chosen.

Further experiments were carried out on the IBM MareNostrum 4 supercomputer, operated by BSC. We tested the preconditioners mentioned above, with the only difference that the sparse LU factorization from UMFPACK was applied when the coarsest matrix was replicated in all the processes. The execution times and speedups obtained on MAT3 are shown in Figure 34.

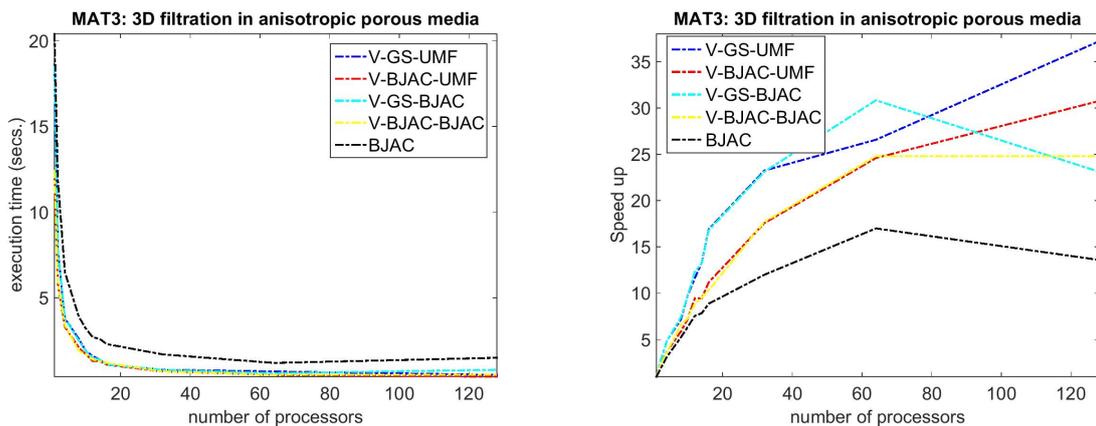


Figure 34: Linear system MAT3 from groundwater modelling: execution time and speedup on MareNostrum.

For these linear systems, all the multilevel preconditioners are generally superior than the one-level preconditioner. However, when the number of cores increases, the performance of the multilevel preconditioners using the exact coarsest-level solver deteriorates, while the multilevel preconditioners applying the distributed iterative solver to the coarsest system still appear efficient. When the overall size of the matrix is kept constant, the execution time of the block-Jacobi preconditioner becomes comparable with that of the multilevel preconditioners using the distributed iterative coarsest-level solver, although the former requires a much larger number of iterations. For all the preconditioners, the execution time increases and the speedup decreases as the anisotropy of the problem grows; this agrees with the larger number of CG iterations that are required, and with the well-known memory-bound nature of this computation. Nevertheless, the preconditioners implemented in MLD2P4 show reliability and robustness with respect to anisotropy.

On the basis of the previous experiments, the V-cycle preconditioners using the smoothed aggregation, forward/backward hybrid Gauss-Seidel (FBGS) or the block-Jacobi (BJAC) smoother, and 10 BJAC sweeps as coarsest-level solver were selected as the best preconditioners to be used with the CG solver on the selected matrices. A weak scaling analysis was performed with these preconditioners on the CRESCO cluster operated by ENEA (40 nodes, each consisting of 2 sockets with 8 Intel Xeon E5-2630 v3 processors, 2.4 GHz and

64 GB RAM, connected by Infiniband). Like in the previous tests, a generalized row-block distribution of the matrix was obtained via METIS; 15500 matrix rows per core were considered, achieving a system dimension of about 16 million on 1024 cores.

The scalability of the preconditioner build phase and of the solve phase is reported in Figure 35 for MAT1 and MAT2. Taking into account the well-known memory-bound na-

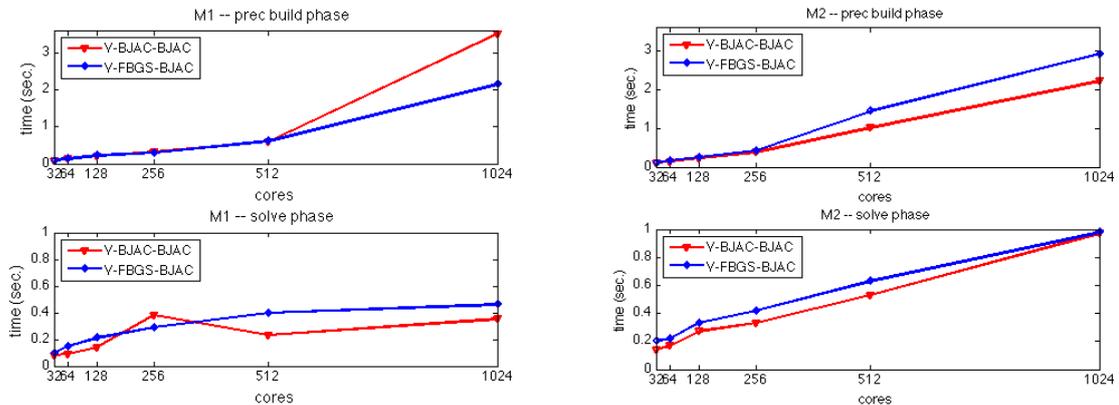


Figure 35: Linear systems MAT1 and MAT2 from groundwater modelling: weak scaling on CRESCO.

ture of the computation, a satisfactory weak scaling is achieved in the solve phase. The preconditioner build phase is less scalable, but in many applications the preconditioner can be reused, thus reducing the impact of this phase on the overall performance.

In conclusion, PSBLAS and MLD2P4 appear good candidates for the exploitation in parallel simulations of flows in heterogeneous porous media such as Parflow. Furthermore, the possibility of combining various smoothers and coarsest-level solvers provides some flexibility for achieving a good tradeoff between efficiency and robustness, depending on the problem and the parallel computer.

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Table 20: Performance metrics for test case 1 on the JURECA cluster for ParFlow and ParFlow + p4est on 24 processors. The first column is the measurement from ParFlow v320, the last column is the measurement from ParFlow + p4est. Metrics that have been added (removed) during the project are marked with n.m. (o.m.).

	Metric name	01'2018 Parflow.v320	01'2018 ParFlow.v320 + p4est
Global	Total Time (s)	5	2
	Time IO (s)	0.1	0.1
	Time MPI (s)	0.6	0.4
	Memory vs Compute Bound	0.8	0.7
	Load Imbalance (%)	12.0	9.6
IO	IO Volume (MB)	183.1	183.1
	Calls (nb)	0	0
	Throughput (MB/s)	1570.4	1551.2
	Individual IO Access (kB)	0.0	0.0
MPI	P2P Calls (nb)	11808	11537
	P2P Calls (s)	0.2	0.2
	P2P Calls Message Size (kB)	4.0	4.1
	Collective Calls (nb)	1008	1022
	Collective Calls (s)	0.2	0.2
	Coll. Calls Message Size (kB)	0.4	0.4
	Synchro / Wait MPI (s)	0.3	0.2
	Ratio Synchro / Wait MPI (%)	56.3	57.5
	Message Size (kB)	o.m.	o.m.
Load Imbalance MPI	o.m.	o.m.	
Mem	Memory Footprint	45964 kB	32168 kB
	Cache Usage Intensity	0.77	0.77
	RAM Avg Throughput (GB/s)	o.m.	o.m.
Core	IPC	1.84	1.68
	Runtime without vectorisation (s)	3	3
	Vectorisation speedup factor	0.6	1.50
	Runtime without FMA (s)	2	2
	FMA speedup factor	0.4	1.00

Table 21: Performance metrics for test case 1 on the JURECA cluster for ParFlow and ParFlow + p4est on 24 processors. The first column is the measurement from ParFlow v320, the last column is the measurement from ParFlow + p4est. Metrics that have been added (removed) during the project are marked with n.m. (o.m.).

	Metric name	01'2018 Parflow.v320	01'2018 ParFlow.v320 + p4est
Global	Total Time (s)	8	5
	Time IO (s)	0.3	0.7
	Time MPI (s)	2.4	1.4
	Memory vs Compute Bound	0.9	1.2
	Load Imbalance (%)	23.2	25.2
IO	IO Volume (MB)	366.3	366.3
	Calls (nb)	0	0
	Throughput (MB/s)	1122.4	549.3
	Individual IO Access (kB)	0.0	0.0
MPI	P2P Calls (nb)	12603	12327
	P2P Calls (s)	0.9	0.5
	P2P Calls Message Size (kB)	4.0	4.1
	Collective Calls (nb)	1028	1042
	Collective Calls (s)	0.8	1.0
	Coll. Calls Message Size (kB)	0.9	0.9
	Synchro / Wait MPI (s)	0.9	1.2
	Ratio Synchro / Wait MPI (%)	37.0	46.1
	Message Size (kB)	o.m.	o.m.
Load Imbalance MPI	o.m.	o.m.	
Mem	Memory Footprint	118176 kB	26180 kB
	Cache Usage Intensity	0.81	0.80
	RAM Avg Throughput (GB/s)	o.m.	o.m.
Core	IPC	1.87	1.81
	Runtime without vectorisation (s)	7	4
	Vectorisation speedup factor	0.88	0.80
	Runtime without FMA (s)	7	5
	FMA speedup factor	0.88	1.00

Table 22: Characteristics of a test matrix generated from ParFlow MATLAB code *FD_3D_TwoPointFluxApproximation_NoLoop_modifyYN.m* with default parameters: H=1.0; Nx=Ny=Nz=200; num=3.0; rtol=1 x 10⁻⁷; maxiter=100.

Matrix	unknowns	non-zeros per line	conditioning
<i>parflow-def</i>	8.00 × 10 ⁶	6.97	6.62 × 10 ⁸

Table 23: Comparison of MUMPS solver with a Conjugate Gradient (CG) preconditioned with Block-Jacobi (BJ) and incomplete LU level 0 (ILU0) in an iteration of ParFlow simulation (*ex10.c*) with parameters: number of MPI processes=100; H=1.0; Nx=Ny=160; Nz=120; num=3; atol=1 x 10⁻¹⁵; rtol=1 x 10⁻⁶; divtol=1 x 10⁺⁵.

Solver	MUMPS	MUMPS+BLR $\epsilon=1 \times 10^{-16}$	CG/BJ+ILU0
Timing	183.60	129.70	4.16
Residual	3.99 x 10 ⁻¹⁰	1.60 x 10 ⁻¹⁰	7.49 x 10 ⁻⁰⁶
#Iterations	1	1	1588

Table 24: Comparison of several #Blocks for Block-Jacobi, run with 100 MPI on EOS. By default, there is 1 block per MPI, so 100 blocks. Analysis/Facto/Solve timings are specific to MUMPS.

#Jacobi blocks	#MPI per blk.	Timing				Residual	#Iters.
		Total	Analysis	Facto.	Solve		
100	1	122.6	0.30	0.47	0.06	8.61 x 10 ⁻⁰⁶	1514
50	2	255.1	0.51	0.34	0.07	2.45 x 10 ⁻⁰⁵	957
25	4	205.3	1.42	1.85	0.09	3.50 x 10 ⁻⁰⁶	723
10	10	122.3	3.53	2.04	0.10	4.18 x 10 ⁻⁰⁶	538

Table 25: Comparison of several approaches to solve an iteration of ParFlow simulation (*ex10.c*) with previously defined parameters, run with 100 MPI on EOS.

Solver	Total time	Residual	#Iterations
CG/BJ+ILU0	4.16	7.49 x 10 ⁻⁰⁶	1588
CG/BJ+ICC	6.18	8.09 x 10 ⁻⁰⁶	1588
CG/MUMPS	177.10	3.88 x 10 ⁻¹⁰	1
CG/MUMPS+BLR $\epsilon=1 \times 10^{-16}$	135.20	1.38 x 10 ⁻¹⁰	1
CG/MUMPS+BLR $\epsilon=1 \times 10^{-1}$	85.18	2.20 x 10 ⁻⁰²	divergence
CG/BJ+MUMPS	118.60	8.61 x 10 ⁻⁰⁶	1514
CG/BJ+MUMPS+BLR $\epsilon=1 \times 10^{-16}$	116.80	8.61 x 10 ⁻⁰⁶	1514
CG/BJ+MUMPS+BLR $\epsilon=1 \times 10^{-1}$	112.90	8.61 x 10 ⁻⁰⁶	1514

Table 26: Linear systems from groundwater modelling: number of CG iterations.

procs	BJAC	V-GS-MUMPS	V-BJAC-MUMPS	V-GS-BJAC	V-BJAC-BJAC
MAT1					
1	288	15	13	29	26
2	331	15	14	30	27
4	341	15	14	27	25
8	331	15	15	28	25
16	343	18	15	19	17
32	356	17	15	19	17
64	351	17	15	20	18
MAT2					
1	358	32	19	33	20
2	420	38	29	38	29
4	429	34	26	34	27
8	391	33	27	35	28
16	424	35	29	37	31
32	435	34	29	36	30
64	482	38	28	40	30
MAT3					
1	469	72	43	74	44
2	607	68	46	70	47
4	618	64	54	65	56
8	625	80	64	82	60
16	680	63	60	65	62
32	716	78	71	81	72
64	700	77	72	81	72

10. Shemat

Activity type	WP1 support
Contributors	Sebastian Lührs (JSC, WP1), Rene Halver (JSC, WP1), Johanna Bruckmann (RWTH, WP4), Henrik Büsing (RWTH, WP4), Jan Niederau (RWTH, WP4)

Overview

Description of SHEMAT-Suite

SHEMAT-Suite simulates flow, heat and species transport in porous media, as well as geochemical rock reactions, for applications regarding geothermal energy. It has inverse capabilities (Monte-Carlo, EnKF, Bayes Inversion) as well as functionalities for two-phase flow to simulate CO₂ sequestration. The code is developed at RWTH (University of Aachen) and is written in Fortran, using MPI and OpenMP for parallelisation.

Implementation of HDF5 as a parallel I/O input format for SHEMAT-Suite

The target of this support activity was the optimization of the I/O behavior of SHEMAT-Suite by adding new HDF5⁴ capabilities for the input parsing process.

The existing established input format of SHEMAT-Suite allows the usage of a mix of ASCII and HDF5 (in a preliminary version) input files. The HDF5 files are referenced in the ASCII file. Large datasets can either be provided directly in the ASCII file or via the separate HDF5 file. The existing HDF5 capabilities were not used quite often and could only be used for a subset of input parameters. So far the HDF5 input files are generated by SHEMAT-Suite itself. So these files could only be used to allow re-usage of datasets in a secondary run (e.g. to restart with checkpoint data). New datasets from scratch could only be defined via the ASCII format.

The handling of the ASCII file format could be rather slow if all different input variables are written to a single input file (which is a common input case). Instead it is also possible to distribute the data over multiple files. In the case of using a single input file and a file size larger than 100 MB the input file read duration of SHEMAT-Suite could take multiple minutes.

To allow a more flexible HDF5 input format (without using SHEMAT-Suite for conversion), parallel I/O capabilities and to avoid the long input file handling of large ASCII input files, the code developers asked for application support by WP1 to implement a new HDF5 based input strategy.

Structure

To allow an easy implementation of the new input format, two new parts within SHEMAT-Suite were implemented as part of this support activity:

- A conversion script which efficiently converts the existing input format to the new

⁴<https://support.hdfgroup.org/HDF5>

input format. By using this intermediate script solution, all preprocessing steps can stay unchanged and are not affected by this implementation.

- Adding new HDF5 capabilities to SHEMAT-Suite to allow parsing of the new input files.

The output behavior of SHEMAT-Suite was not changed.

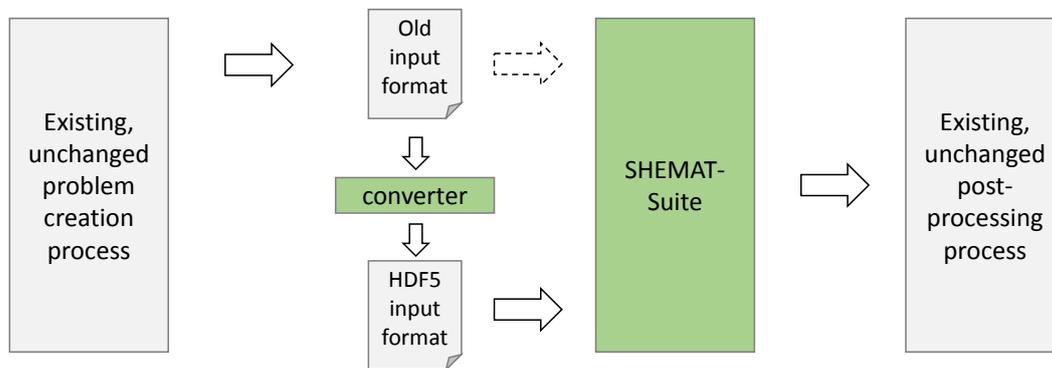


Figure 36: Updated SHEMAT-Suite I/O workflow layout. The parts which were added/changed in the activity are marked in green.

The old ASCII based input format contains several different variables to parameterize SHEMAT-Suite. In addition this format also supports different ways to represent these data (e. g. by using Fortran based repeated values like $10 * 2.3$ to reuse the same value ten times). The different variables and the different formats must be interpreted by the conversion script. The new implementation focuses on the larger variables in context of data size, smaller scalar values are currently not converted and stay unchanged in the old input file. The parsing process automatically change between the old and the new input format if a variable is found which is not converted so far. This also allows easy addition of new variables in the future, because these could be added to the old input format and do not need to be directly added into the conversion process. On the other site additional variables can be converted one after each other. Not all variables together has to be converted to still allow program execution. Until now nearly thirty variables were already moved from the old to the new format.

Implementation

The existing ASCII format uses header lines to mark the different variables in the input file.

As an example the following lines describe the general grid structure:

```
# grid
362 287 72

# delx
362*10.
```

```
# dely
287*10.
```

```
# delz
72*10.
```

These examples are rather short entries because they use the repeat feature of Fortran to avoid repeating multiple values. Other entries might contain several MB of data. Due to the existing parsing implementation of SHEMAT-Suite, the input file is searched for each individual header line starting at the beginning of the file. This process can extremely slow down the parsing process if header entries do not exist (e.g. if they are optional), because the whole file has to be scanned multiple times.

The new conversion script is written in Python using the `h5py`⁵ HDF5 Python bindings. Because it reads the original input file, the existing parsing process of SHEMAT-Suite has to be reimplemented to support as many input features as possible. To avoid the same header searching bottleneck, the file is only scanned once to mark all header lines. After this, all existing headers can easily be reached by jumping directly to the specific file position.

HDF5 does not support some of the features which were present in the old ASCII format (like the Fortran repeat syntax). Such values are now automatically converted to a general format using a fixed structure. Repeated values are now also stored directly in the file, which increases the file size, but also allows to use a file more easily within other applications.

The conversion script will produce the following HDF5 structure to store the grid layout:

```
GROUP "grid" {
  DATASET "delx" {
    DATATYPE H5T_IEEE_F64LE
    DATASPACE SIMPLE { ( 362 ) / ( 362 ) }
  }
  DATASET "dely" {
    DATATYPE H5T_IEEE_F64LE
    DATASPACE SIMPLE { ( 287 ) / ( 287 ) }
  }
  DATASET "delz" {
    DATATYPE H5T_IEEE_F64LE
    DATASPACE SIMPLE { ( 72 ) / ( 72 ) }
  }
}
```

Once a variable is extracted, it is deleted from the ASCII file to only keep the unconverted values. In addition a new entry is added to the ASCII file automatically pointing to the new HDF5 data file. The ASCII file itself still remains the main entry point for SHEMAT-Suite. Depending on the presence of the HDF5 file link entry, the new or old parsing process is triggered.

⁵<http://www.h5py.org/>

Within SHEMAT-Suite a new HDF5 parsing interface was implemented. This interface wraps the most common reader functions and some additional help routines. The new HDF5 data file is opened once in the beginning and is kept in a global reachable file handle until all input datasets are loaded. The data layout (dimension, type and structure) in the HDF5 file was selected based on the SHEMAT-Suite internal data representation to avoid any conversion process.

In addition to these improvements and the direct HDF5 conversion capabilities, the new input format also allows the usage of distributed I/O calls in future implementations of SHEMAT Suite. Instead of reading global datasets with each individual processor, the usage of distributed I/O calls can help to avoid memory scalability problems once the application will be executed on larger scales.

In order to implement the distributed I/O calls in a first step, the *mpifw* branch of SHEMAT-Suite was used, providing a MPI-parallel version of the code. Because during the implementation of parallel HDF5 I/O routines it was discovered that the MPI parallelisation was not working as intended, e.g. a asynchronous adaptive time refinement led to deadlocks in some cases or data was still collected in global arrays defeating the purpose of a distributed memory approach, it was decided to change the code-base to another MPI-based branch of the code. Therefore the implementation was continued on the *PETSTEM_DD* branch, which also provides a MPI parallel version of the code using PETSC for data distribution.

Results

To validate the benefit of the new input parsing process, the input parsing time was measured using different file sizes (of the original ASCII main input file) and different number of cores on the JURECA⁶ system. The comparison is done between the original ASCII based input file and the new converted input file. The time for the conversion process itself is included in the new timings.

Figure 37 shows a small input file, where the old and the new input format show nearly the same read duration and scaling behavior.

Figure 38 shows a second input case, using a larger ASCII input file. The ASCII parsing process is already much slower in comparison to the new format due to the header line handling which is mentioned before.

Table 27 shows an (in context of SHEMAT-Suite) large input case, storing more than 200 MB within the single main SHEMAT-Suite ASCII input file. The parsing of this file takes nearly 45 minutes in serial by using the old parsing process. This process could be significantly improved and reduced to less than a minute.

Table 27: Serial SHEMAT-Suite input parsing time on JURECA using a 229 MB main input file.

Parsing time old ASCII format	Parsing time new HDF5 input format
2647s	26s

⁶http://www.fz-juelich.de/ias/jsc/EN/Expertise/Supercomputers/JURECA/JURECA_node.html

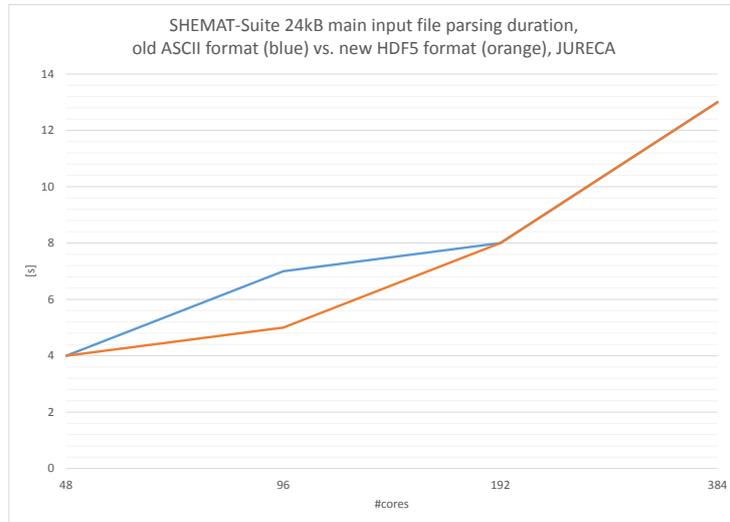


Figure 37: SHEMAT-Suite input parsing time on JURECA using different number of cores and a 24 kB main input file. The old ASCII format is marked in blue, the new HDF5 format is marked in orange.

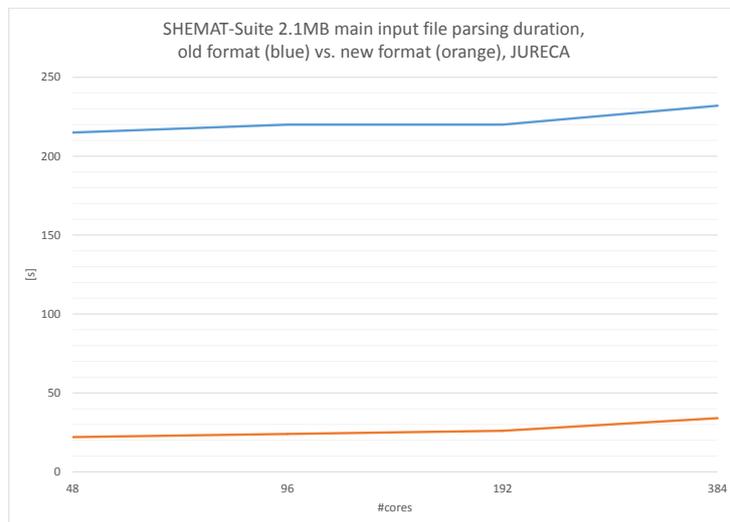


Figure 38: SHEMAT-Suite input parsing time on JURECA using different number of cores and a 2 MB main input file. The old ASCII format is marked in blue, the new HDF5 format is marked in orange.

Table 28: Test matrices for Hiepac solvers

Name	Columns	NNZ_A	NNZ_L	GFLOPS
MPhase Small	49152	438152	6222328	0.94
MPhase Big	3145728	28277768	715196138	825.27
MPMC Small	196608	1957132	19157988	5.61
MPMC Big	4320000	43160408	639275272	736.73

As shown in the figures, the new input format could speed up the parsing process. Additional variables could easily be added to the conversion process to allow future sustainability.

As a final result it should be mentioned, that these changes to the code lead to savings in the time spent for computation on different clusters situated in Aachen and Jülich. The relative amount of saved time is estimated to be around 7 % of the total time spent and sums up to about 36 500 core-h. It should be mentioned again, that these savings are the result of a pure improvement of the I/O procedure and no further performance optimizations took place in this support activity.

Hiepac solvers for SHEMAT matrices

Activity type	Consultancy or WP1 support
Contributors	E. Agullo (WP1), L. Giraud (WP1), M. Hastaran (WP1), M. Kuhn (WP1), G. Marait (WP1), H. Buesing (WP4)

This section deals with the usage `Pastix` [3] and `Maphys` [2] Hiepac sparse solvers for linear algebra to solve matrices coming from the SHEMAT-Suite. The matrices and their characteristics used for this performance test are given in Table 28.

The following parallel experiments are all performed on the academic platform PlaFRIM (Federative Platform for Research in Computer Science and Mathematics). The part of the cluster in use is composed of 2 Dodeca-core Haswell Intel Xeon E5-2680 @ 2.5 GHz nodes with 128 GB RAM per node.

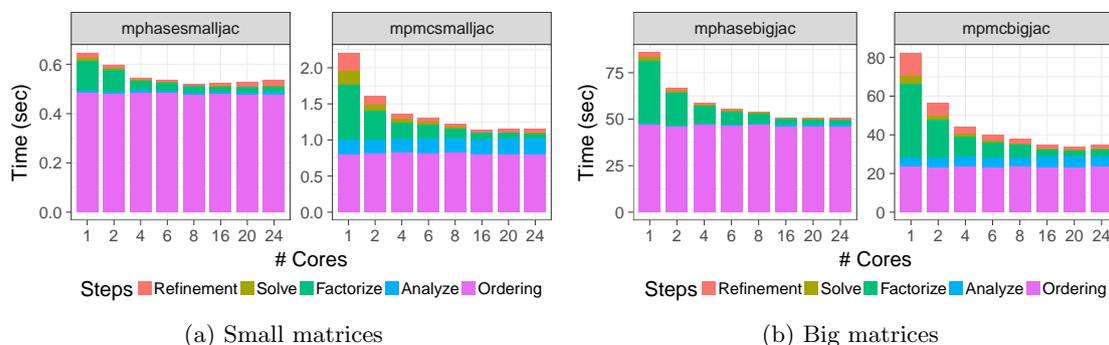


Figure 39: `Pastix` multi-threaded performances on one computational node

Figure 39 shows `Pastix` solver strong scaling on one node using multi-threading and Fig-

ure 40 shows **Maphys** solver strong scaling on several nodes with multi-threading. Globally, these preliminary results show that both **Pastix** and **Maphys** solvers perform well into solving the four matrices. This study could serve as a basis to discuss the opportunity of integrating one of the two solvers into **SHEMAT** to perform further tests.

MUMPS solver for SHEMAT-Suite

Activity type	WP1 support
Contributors	I. Duff (CERFACS, WP1), P. Leleux (CERFACS, WP1), D. Ruiz (IRIT, WP1), F. S. Torun (IRIT-CNRS, WP1), H. Büsing (RWTH, WP4)

Overview of SHEMAT-Suite

The target of this support activity was the optimization of the linear solver involved in each non-linear Picard-iteration of the code **SHEMAT-Suite**, where PDE coefficients depend on primary variables (pressure and temperature). This is a 3D problem with regular grid and classical 7 point stencil space discretization (7 diagonals in every Newton block, i.e. max 14 entries per row).

The goal is to obtain new insights into the problem and how to construct new appropriate preconditioners.

Each Picard-iteration implies the solution of a sparse linear system with single right hand side. The systems are unsymmetric, as there is advection in the physics/heterogeneity in the coefficients, and they change (structure and values) for each iteration. Target size of the systems is 10^8 and target timing of the order of the minute.

The current solution uses BiCGStab with ilu0 preconditionner launched through PetSc. The code has 2 development branches:

- single-phase flow with a pure OpenMP parallelism (8-16 cores),

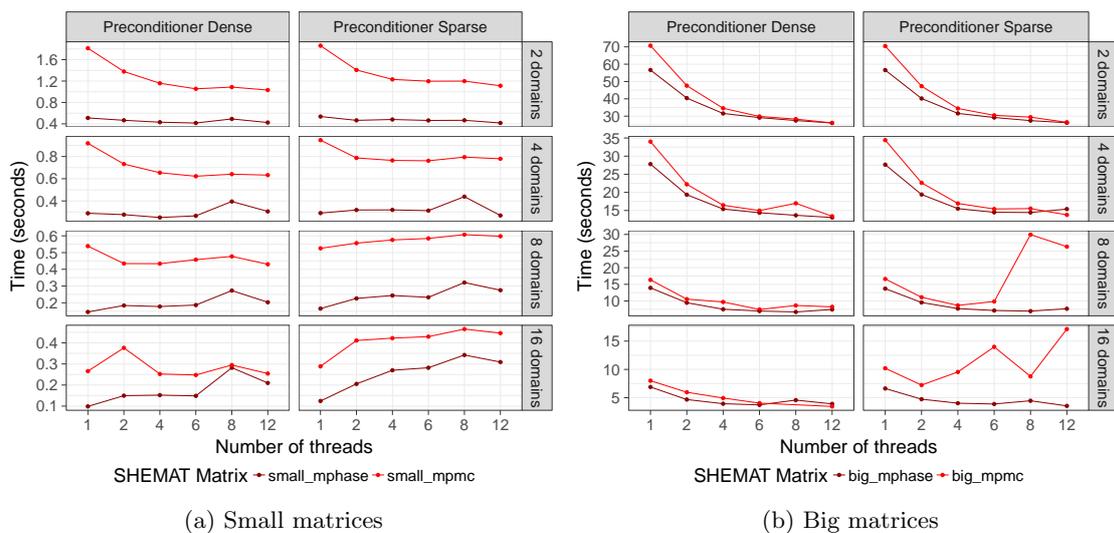


Figure 40: **Maphys** multi-threaded performances on 2 to 16 computational nodes

Table 29: Characteristics of matrices extracted from SHEMAT-Suite code, as test-cases on the EoCoE data server. More complex configurations (from the linear solver point of view) could be generated with varying permeability or variable density and viscosity.

Dev-branch	Matrix	unknowns	non-zeros per line	conditioning
Single-phase	mphase_big	$3.15 \times 10^{+06}$	6.99	$2.23 \times 10^{+07}$
	mpmc_big	$4.32 \times 10^{+06}$	9.96	$1.84 \times 10^{+05}$
	fine8	$3.15 \times 10^{+06}$	6.99	$2.37 \times 10^{+07}$
Multi-phase	head_big	$8.31 \times 10^{+06}$	6.91	$1.07 \times 10^{+03}$
	temp_big	$8.31 \times 10^{+06}$	6.89	$7.31 \times 10^{+04}$

- multi-phase flow with MPI parallelism (run on JUQUEEN up to 1024 cores).

As an example on matrix *head_big* (see Table 29) with 8 OpenMP threads, BiCGStab+ILU0 converges in 60.8s with 429 iterations and a residual of 2-norm 1×10^{-12} .

Method and Preliminary Results

We will not give extensive details about the use of MUMPS in this section but will focus on the use of this solver to tackle SHEMAT-Suite linear systems. For more details on MUMPS principle and particularly on its latest feature: Block Low Rank Approximation (BLR), see MUMPS Section from deliverable 1.7 Software technology improvement.

Our tests were run mainly on CERFACS cluster Nemo: 1872 nodes with 128GB of memory and 2 sockets of 12 Intel Xeon E5-2680 v3 Haswell CPUs at 2.5GHz. In the following "P x N cores" stands for P processes with N threads each. The test cases used for preliminary results were those of Table 29.

As new approach to solving the linear systems in SHEMAT-Suite, we decided to make use of MUMPS with BLR as a preconditioner for a simple iterative scheme like GMRES.

The relevance of this approach comes from several observations made after preliminary runs with MUMPS on SHEMAT-Suite extracted matrices:

1. MUMPS is capable of scaling on SHEMAT-Suite matrices as long as there is enough granularity (see Figure 41),
2. For most applications, there is no need to get a solution to machine accuracy: BLR feature approximates the LU factorisation,
3. On a theoretical point of view, BLR has an asymptotic complexity of $O(n^{(4/3)})$ with n being the first dimension of the 3D problem. Geometric multigrid will always be a better choice on purely elliptic problems, however on different problems (ex: Helmholtz or structural mechanics) the gains compared to using an iterative scheme could be greater. For more results, see [1],
4. BLR applied to SHEMAT-Suite data gives particularly good results as a slight compression is enough to already decrease flops and timing by a good factor with no loss (see Figure 42),
5. However, the memory consumption and timings stay too high compared to pure

Table 30: Tests on the multiphase system with refinement level 8 on 4 cores: comparison of MUMPS and CPR-AMG (Constrained Pressure Residual Algebraic Multigrid) timings for the full simulation.

Refinement level	MUMPS (No BLR)	MUMPS (BLR $\epsilon = 10^{-16}$)	CPR-AMG
8	7:54.41 min	6:44.31 min	3:57.58 min

iterative schemes (see Figure 43 and Table 30).

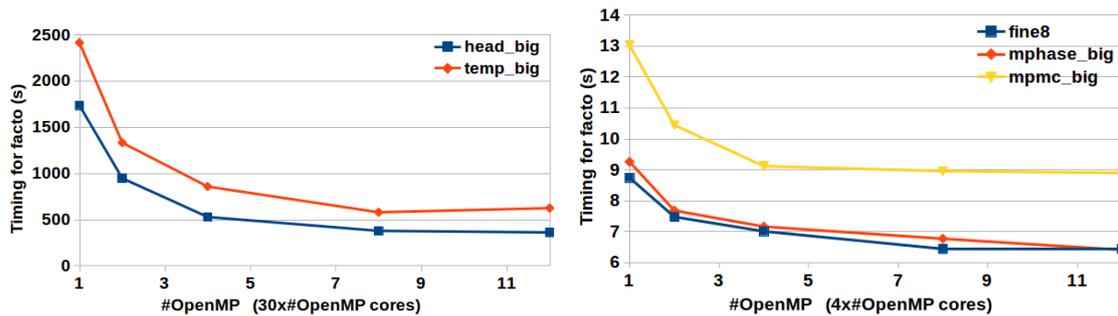


Figure 41: MUMPS factorisation phase depending on #OpenMP (**Left**) for single-phase with 30 MPI and (**Right**) for multi-phase with 4 MPI.

N.B.: Through the runs, we noticed that multi-phase matrices are faster to solve and thus look smaller from the direct solver point of view. We are still investigating this point as only the geological structure is more intricate for single-phase while physics and structure (2x2 block compared to 1x1) are harder in multi-phase.

Future tests

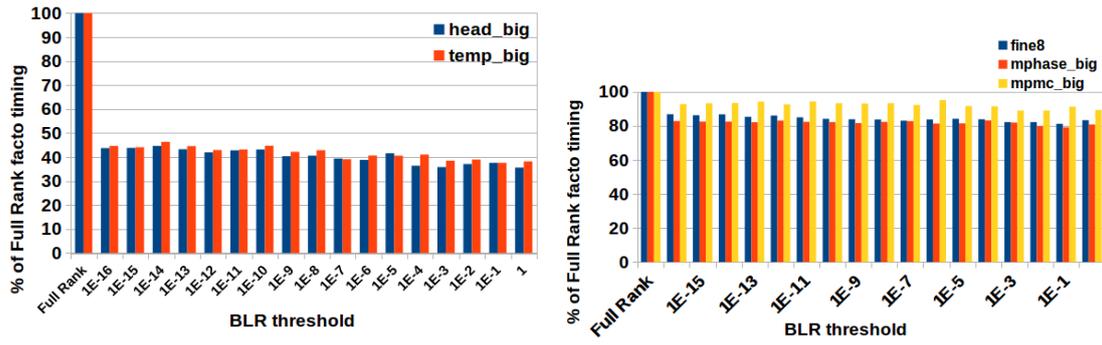
The method can be tested directly through PETSc using command-line options. We are planning to test several configurations in full simulations:

1. MUMPS+BLR as preconditioner on complete system for GMRES:
`-ksp_type gmres -pc_type lu -sub_pc_factor_package mumps`
`-sub_mat_mumps_icntl_35 1 -sub_mat_mumps_cntl_7 1 x 10-1,`
2. MUMPS+BLR as preconditioner on Block-Jacobi subsystems for GMRES:
`-ksp_type gmres -pc_type bjacobi -sub_pc_type lu -sub_pc_factor_package mumps`
`-sub_mat_mumps_icntl_35 1 -sub_mat_mumps_cntl_7 1 x 10-1,`

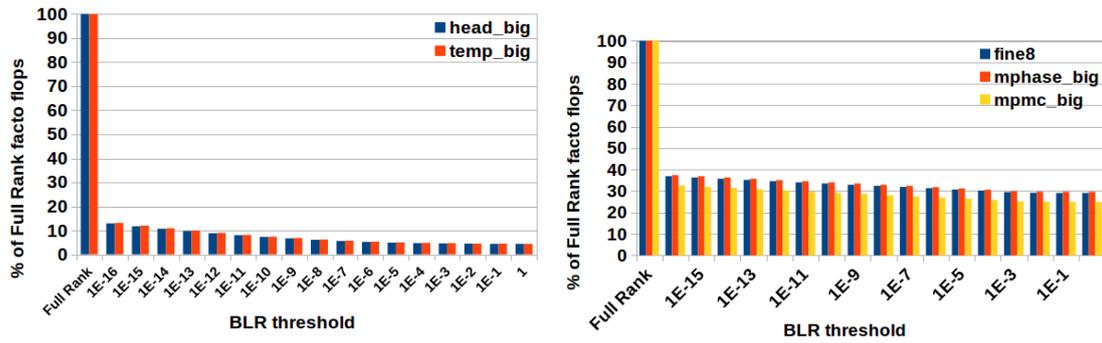
Depending on the results, further tests can be designed. The goal is to handle more precisely the sub-domains from the Block-Jacobi preconditioner with MUMPS to decrease the number of #iterations of GMRES. Relaxing the direct solver with BLR will then decrease MUMPS timing while increasing the #iterations and we are looking for the right trade-off.

References

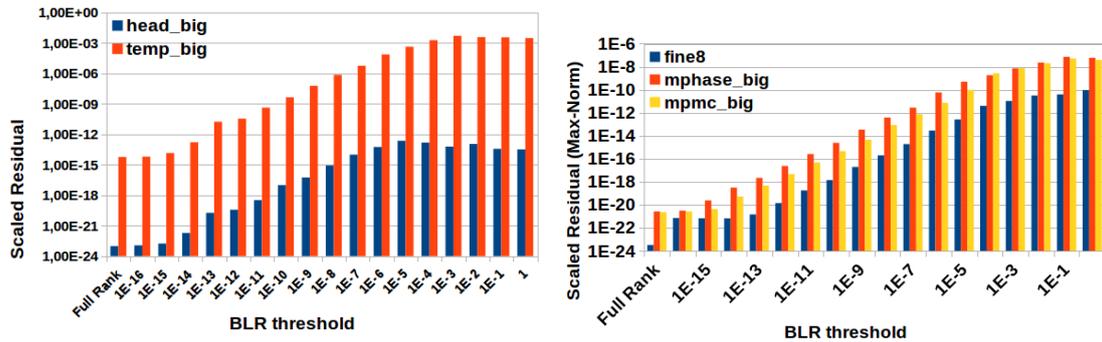
- [1] Théo Mary. “Block Low-Rank multifrontal solvers: complexity, performance, and scalability”. PhD thesis. UT3, 2017.



(a) Factorisation timing



(b) Factorisation flops



(c) Accuracy of solution

Figure 42: MUMPS used with Block Low Rank Approximation on SHEMAT-Suite (**Left**) single-phase with 30x12 cores and (**Right**) multi-phase with 4x4 cores.

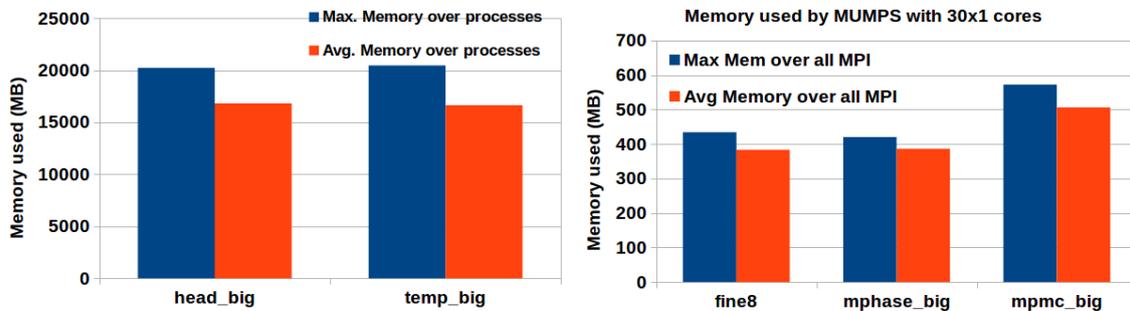


Figure 43: Memory needed by MUMPS with 30x1 cores (**Left**) for single-phase and (**Right**) for multi-phase.

- [2] *Massively Parallel Hybrid Solver (Maphys)*. URL: <https://gitlab.inria.fr/solverstack/maphys>.
- [3] *Parallel Sparse direct Solver (PaStiX)*. URL: <https://gitlab.inria.fr/solverstack/pastix>.

11. SolarNowcast

Nowcasting is a short term solar irradiation forecast code based on data acquired by a fisheye webcam. It has applications in photovoltaic centrals short term production prediction.

Nowcasting is composed of 2 codes:

- **MotionEstimation** estimates the dynamics from a set of successive acquired images with an iterative minimization of an energy function with the BFGS solver. It uses a second-order semi-Lagrangian scheme SETTLS and backward integration of the adjoint model. It is a serial code.
- **Forecast** consists of a simulation of future images, based on the result of Motion-Estimation. It uses a second-order semi-Lagrangian scheme SETTLS. It is pure OpenMP.

Objective:

The performance objectives of Nowcasting are of real time order: to return prediction results for a given period (10 minutes) in the lapse of time between two images acquisitions (10 seconds in the targeted production benchmark).

11.1 Performance metrics

Code team:

- Isabelle Herlin (Inria), WP2
- Dominique Béréziat (LIP6), WP2
- Yacine Ould Rouis (MdlS), WP1

Benchmark characteristics:

Domain size	501*501
Number of time steps	3600
Compile options	-O3 -xHost
Resources	1 node on JURECA
IO details	serial, every 10 timesteps
Type of run	the size of benchmark aims to be faithful to the target use of the program

11.2 Forecast - Application support activities

Activity type	WP1 support
Contributors	Y. Ould-Rouis (WP1), D. Bereziat (WP2), I. Herlin (WP2)

The optimization process was primarily based on measurements performed by 2 JUBE scripts, reproducing a scalability test, on 1 to 24 cores, and a VTune profile collection. Other tools were occasionally used, such as Intel vectorization reports. The “EoCoE JUBE integrated perf evaluation” was used to monitor the evolution, only at notable steps.

We could describe the optimization work as follows:

Table 31: Performance metrics for Nowcasting Forecast module on the JURECA HPC system.

	Metric name	July 2016 (1/8/24 threads)	October 2016 (1/8/24 threads)
Global	Total Time (s)	169 / 34 / 26	76.5 / 11.5 / 4.8
	Time IO (s)	0.4 / 0.5 / 0.4	0.5 / 0.4 / 0.4
	Time MPI (s)	N.A.	N.A.
	Memory vs Compute Bound	N.A.	N.A.
IO	IO Volume (MB)	10529.8	1050.2
	Calls (nb)	80107	80107
	Throughput (MB/s)	2631.1 / 2613.6 / 3159.6	2316.0 / 2576.3 / 2475.2
	Individual IO Access (kB)	1016.4	1016.4
Node	Ratio OpenMP	-0.0	N.A.
	Load Imbalance OpenMP	N.A.	N.A.
	Ratio Synchro / Wait OpenMP	0.0	N.A.
	OpenMP Scalability Efficiency	ref / 62% / 27%	ref / 83% / 66%
Mem	Memory Footprint (KB)	33272 / 34656 / 43696	33780 / 39092 / 38116
	Cache Usage Intensity	N.A.	N.A.
	RAM Avg Throughput (GB/s)	N.A.	N.A.
Core	IPC	N.A.	N.A.
	Runtime without vectorisation (s)	169 / 33 / 27	86.9 / 13.3 / 5.6
	Vectorisation efficiency	1.0 / 1.0 / 1.0	1.13 / 1.16 / 1.16
	Runtime without FMA (s)	163 / 33 / 27	80.2 / 12.1 / 5.1
	FMA efficiency	0.96 / 1.0 / 1.0	1.05 / 1.05 / 1.06

- Code understanding
- Exploring the major hot-spots through the VTune profile
- Checking the nested loops order, to avoid data access indirections. No notable problems found at this level.
- Checking for redundant operations. When spotted, factorize the operations. This translates, for example, in factorizing divisions in IntegreAll loops. In any case, a division is more expensive than a multiplication, so any constant divisor in an iteration should be replaced with a multiplication by its inverse. Looking at the bigger picture, the time loop, some costly operations present in the code, were redundant, or even useless. This was the case with “SetAll” calls (memsets) in IntegreAll, on arrays that were entirely rewritten in the next step. These operations were simply removed.
- Vectorization: Based on Intel compiler’s opt-reports, the semi-Lagrangian calculation (IntegreAll) innermost loop, among others, was entirely rewritten in a shape easily vectorizable by the compiler, removing any ambiguity regarding instructions inter-dependance, and favouring data alignment when possible.
- OpenMP:
 - The OpenMP distribution was improved by dividing the main IntegreAll loop into bigger independent chunks, reducing the number of threads initializations, and improving the data locality and SIMD possibilities within each thread.
 - Thread binding, using `kmp_affinity` for Intel, `OMP_PROC_BIND` on GCC,

improves the cache usage and reduces threads initiation time

- **Memory Copy Optimization:** Saving the state vector at the 2 previous time steps, necessary for the calculation of the next state, was using data copy. The code was adapted in order to use pointer copies. In addition to saving a precious `mem_copy` time, this step allowed to unveil and fix an algorithmic bug.
- **Porting on GNU compilers:** All along the optimization process, the code performed much better on Intel compiler. However, the main bottleneck on GNU was spotted as being the use of the floor function in the projection. The standard library floor function is costly, as it performs a series of conditional statements in order to deal with overflow cases. In some cases it even had a problematic behavior, multiplying the execution time 4-fold (`-O3 -march native`, on `eider`, with GCC 4.6.3). In a bound problem like ours, we can replace it with a much lighter, vectorizable function. This modification made a significant difference, bringing the GNU compiled code very close to the Intel compile performance, while not modifying the performance of the latter. Another necessary modification on GCC was to remove a costly file reading part when not needed. This part reads a list of output times from the input file, using a search routine with a key word for each of these times. It is not needed when determining a constant output interval, thus it could be conditioned out. We strongly recommend to replace this routine with a more performant one, parsing the list of output time steps straight in one step.
- **A word on MotionEstimation:** After completing this work on Forecast, it was decided that the code owners will handle the optimization of MotionEstimation and try to apply the best practises described above alone, with the WP1 contact only providing performance analysis and advise, as a way of knowledge transmission.

Results

Table 32: Results and scalability on a JURECA node (Two Intel Xeon E5-2680 v3 Haswell CPUs 30 MB cache 2.5 GHz), Intel compiler, with best opt. flags “`-O2 -xHost -ipo`”.

Threads	MotionEst W1	Forecast W1	MotionEst W2	Forecast W2	Forecast improvement	Scaling efficiency
1	38.6	76.9	3.7	77.1	54 %	
2	38.9	39.9	3.7	39.8	58 %	97 %
4	38.4	22.0	4.0	22.0	62 %	88 %
8	38.3	11.5	3.8	11.6	71 %	83 %
12	38.3	8.5	3.8	8.2	73 %	78 %
24	38.1	4.8	3.8	4.8	81 %	67 %

Table 33: Results and scalability on a JURECA node, GNU 5.3 compiler, with best opt. flags “`-O3 -march=native`”.

Threads	MotionEst W1	Forecast W1	MotionEst W2	Forecast W2	Forecast improvement	Scaling efficiency
1	74.209	80.48	9.977	78.594		
2	73.642	41.021	9.988	40.69		97 %
4	73.581	23.322	10.108	23.279		85 %
8	74.228	12.098	10.242	12.052		81 %
12	73.564	8.481	10.282	8.431		78 %
24	73.652	5.1	10.45	5.077		65 %

As described above, a full performance evaluation on the Forecast code allowed to identify a big optimization potential, both on serial and parallel levels. Optimization efforts

Table 34: Results and scalability on Eider node (2x Intel Xeon CPU E5-2650 20 MB cache 2.00 GHz), GCC 4.6.3.

Threads	MotionEst W1	Forecast W1	MotionEst W2	Forecast W2 (IntegreAll)	Forecast improvement	Scaling efficiency
1	161.305	117.892	11.423	116.500 (114.082)	53 %	
8	152.748	18.295	11.425	17.863 (16.4179)		81 %
16	153.043	10.448	11.421	10.494 (9.07102)		70 %

On Jureca node (2* Xeon E5-2685v2 12C 2.5GHz, 30M L3 Cache), Intel compiler, 501*501 model, w output every 10 timesteps

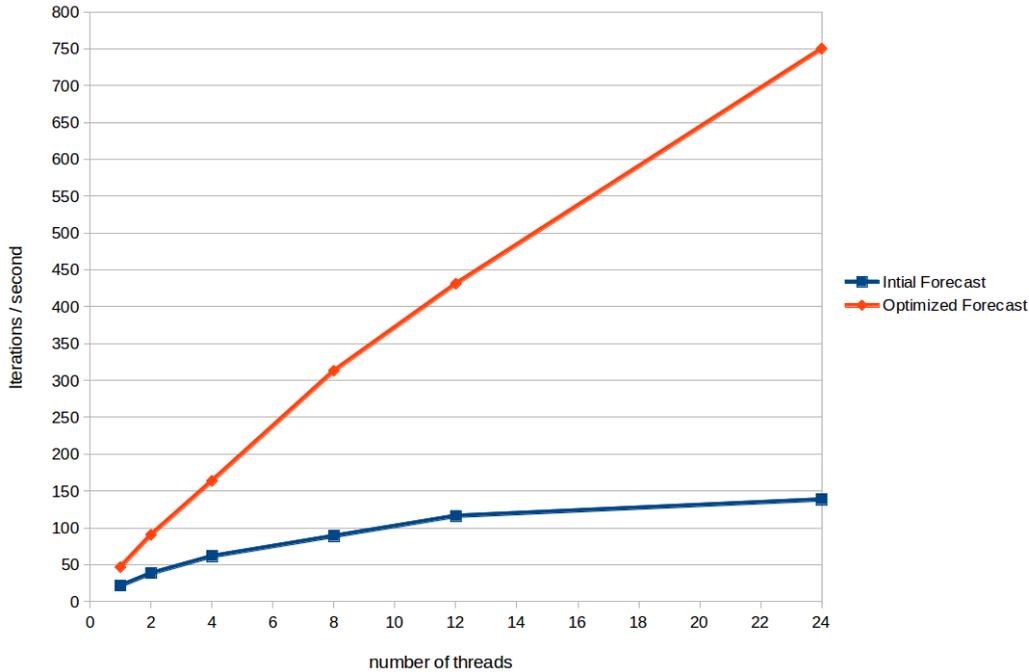


Figure 44: Performance and scalability of Forecast, before and after optimization.

improved the run time, on the targeted production benchmark, by more than 2 times on the serial run, 4 times on 8 threads, and more than 5 times on 24 threads, and raised the scalability efficiency to 70% on 16 threads and 66% on 24 threads, with both compilers, and on several machines.

11.3 MotionEstimation - Knowledge transfer

Activity type	WP1 knowledge transfer
Contributors	D. Bereziat (WP2), supported by Y. Ould-Rouis (WP1)

This part of this study addresses the optimization of the Motion Estimation (ME) module and has been done by the code owners following the best practises learned during the optimisation stage of Forecast module.

The optimization process was primarily based on measurements performed by 2 JUBE scripts, reproducing a scalability test, on 1 to 24 cores, and a VTune profiling. The “EoCoE JUBE integrated perf evaluation” was not used for this part.

Motion is computed by minimising a cost function with an steepest descent method. Each iteration has three steps: forward integration, backward integration and call of the solver

to perform the steepest descent.

The forward integration is similar to the Forecast module: the model is integrated in time. In addition, cost function and departures are also computed. Cost function value is mandatory by the solver and departures are required for the computation of the cost function gradient. However the complexity of these calculations remains negligible in comparison of the integration of the model. Moreover they can be easily distributed using Open MP directives. The model optimisation has already been investigated in the Forecast module.

Optimisation of adjoint model code

The backward integration requires to integrate backward in time the adjoint model. Adjoint model code is obtained by the automatic differentiation of the model code. This is performed by Tapenade⁷.

In a first step, we reported the optimised model from Forecast module into ME one (the two models are identical). A first run on one thread of Eider node showed a time of 153 seconds against 132 before optimisation of model code (on the first window). A quick investigation with VTune indicated the bad performances were caused by the adjoint code (automatically obtained from Tapenade) and function `IntegreAll_b()`. Indeed, the adjoint code needs to store data in a stack with the inconvenience to break vectorization. After a discussion with Tapenade Authors, it appeared that the stack operations were due to a limitation of Tapenade to identify independent iterations in a loop. However, it is possible to reduce the number of stack operations if we explicitly declare, using a Tapenade directive in the code, independent iterations. After several tries, we inserted two directives of independent iterations with the result to totally eliminate stack operations. A run on one thread of Eider node gave 86 seconds (so an improvement of 36% compared to the non optimised code).

The second step was to study the scalability of ME module with OpenMP. It is important to notice the elimination of Tapenade stack operations allows now to distribute the independent iterations on several threads. The stack operation functions make use global arrays and make impossible to use OpenMP directives. We inserted an OpenMP directive for the main loop of `IntegreAll_b()`, at the same level than in `IntegreAll()`. As showed by Tables 35, 36 and 37, the scaling efficiency is not good for more than 4 threads. We introduced timers for the 3 main stages of the ME module: forward integration, backward integration, and solver call. We report these results in Tables 38, 39 and 40. As it can be seen, scaling efficiency is very good for forward and backward step. The solver remains mono-thread, the global scaling efficiency is not good in conformity with Amdahl's law.

Table 35: Scalability on Eider node (GNU Compiler with option "-O3").

Threads	MotionEst W1	Forecast W1	MotionEst W2	Forecast W2	Scaling efficiency (W1)
1	86.213	118.475	11.025	118.515	
8	37.261	17.899	4.535	17.900	29%
16	33.728	10.446	4.103	10.419	16%

⁷<http://www-sop.inria.fr/tropics/tapenade.html>

Table 36: Scalability on JURECA node (GNU Compiler with option "-O3 -march=native").

Threads	MotionEst W1	Forecast W1	MotionEst W2	Forecast W2	Scaling efficiency (W1)
1	44.745	79.312	6.268	85.565	
2	29.472	41.197	4.364	41.771	77%
4	22.85	23.229	3.488	23.187	49%
8	18.475	12.345	3.068	12.084	31%
12	17.238	8.643	2.864	8.475	22%
24	16.195	5.136	2.88	4.986	12%

Table 37: Scalability on JURECA node (Intel Compiler with option "-O3 -xHost -ipo").

Threads	MotionEst W1	Forecast W1	MotionEst W2	Forecast W2	Scaling efficiency (W1)
1	49.363	68.033	5.499	68.672	
2	33.261	34.864	3.729	34.744	74%
4	26.509	19.605	2.908	19.722	47%
8	21.918	10.441	2.261	10.384	29%
12	20.679	7.765	1.969	7.288	19%
24	19.444	4.656	1.819	4.59	11%

Optimisation of the solver

The last step is to work on solver scalability. We use L-BFGS solver version 3.0, written in Fortran. Using Vtune, we have identified 4 costly loops in the main part of the solver. Iterations inside these loops being independent, we have introduced Open MP directives to distribute them among available cores. Scaling performances are presented in Table 41 and 42. As it can be seen, performance and scalability of Motion Estimation have been improved, but efficiency remains poor.

The solver makes call of BLAS functions `daxpy`, `dcopy` and `ddot`. We tried to link with OpenBLAS (a multithreaded implementation of BLAS), without notice some improvement (see tables 38, 39 and 40). We are not sure OpenBLAS calls are effective, this is currently under investigation.

Another way is to change the solver. For instance, HLBFGS⁸ is an C++ implementation of L-BFGS with OpenMP directives that could be interesting. The objective to obtain a time computation close to 5 seconds for the ME stage appears realist if we obtain a good scalability on solver.

⁸<http://research.microsoft.com/en-us/UM/people/yanliu/software/HLBFGS/>

Table 38: Scalability on Eider node (GNU Compiler with option "-O3") and OpenBLAS.

Threads	MotionEst W1			
	Total	Forward	Backward	Solver
1	89.090	24.9864	44.3159	17.6397
4	43.054	8.3472	12.1346	21.2606
8	34.532	5.13174	7.0714	21.0328
12	31.344	4.62574	5.22171	20.136
16	28.864	4.55259	5.04882	17.8837

Table 39: Scalability on JURECA node (GNU Compiler with option "-O3 -march=native") and OpenBLAS.

Threads	MotionEst W1				Scaling efficiency	
	Total	Forward	Backward	Solver	Total	Forward+Backward
1	44.862	12.7	21.8	9.1		
2	28.03	6.7	11.3	9.0	80%	96%
4	20.686	4	6.7	9.1	53%	81%
8	16.083	2.7	3.2	9.2	35%	73%
12	14.457	2.1	2.2	9.2	27%	67%
24	13.438	1.4	1.6	9.4	14%	48%

Table 40: Scalability on JURECA node (Intel Compiler with option "-O3 -xHost -ipo") and OpenBLAS.

Threads	MotionEst W1				Scaling efficiency	
	Total	Forward	Backward	Solver	Total	Forward+Backward
1	49.889	15.8	18.1	14.4		
2	32.023	8.1	9.5	13.1	78%	96%
4	24.445	4.6	5.3	13.5	52%	86%
8	19.029	2.6	2.8	12.7	33%	78%
12	17.798	2.0	2.0	12.7	23%	70%
24	16.284	1.3	1.4	12.6	13%	52%

Table 41: Scalability on eider node (best optimiser flags), after optimisation of LBFGS.

Threads	MotionEst W1				Scaling efficiency
	Total	Forward	Backward	Solver	Total
1	80.2	20.8	39.5	17.8	-
4	27.4	6.4	10.2	9.6	73%
8	21.4	4.4	7.1	8.6	46%
12	19.9	3.7	5.1	9.9	33.6%
16	21.4	3.3	4.2	9.6	23.4%

Table 42: Scalability on Jureca node with Intel compiler (best optimiser flags), after optimisation of LBFGS.

Threads	MotionEst W1				Scaling efficiency
	Total	Forward	Backward	Solver	Total
1	63.8	17.4	25.0	19.3	
2	35.7	8.4	12.3	13.7	89%
4	25.0	4.8	6.9	12.1	64%
8	17.8	2.8	3.6	10.5	44%
12	15.9	2.16833	2.5	10.2	33%
24	13.9	1.5	1.8	9.7	19%

12. Telemac

TELEMAC-MASCARET is an integrated suite of solvers for use in the field of free-surface flow.

The application submitted to EoCoE performance evaluation is a 3D multi-physics coupling for coastal simulation. It consists of a 2D free surface fluid dynamics model coupled with wave propagation and sediment transport. The code is pure MPI.

12.1 Performance metrics

Code team:

- Yacine Ould-Rouis (MdlS) for WP1
- Antoine Joly (EDF) for external partners

Case 1 characteristics:

Resources	2 nodes on JURECA (48 cores)
Domain size	Non structured multi-layer mesh (about 1800 points per process, 36 plans, 25 frequencies)
IO details	
Type of run	development run / production run

12.2 Application support

Activity type	WP1 support
Contributors	Y. OULD ROUIS (WP1)

The application support on Telemac focuses on the memory-bound behavior of the code, and finding a way to unlock the vectorization potential on the core level when possible. The work has been conducted based on the conclusions of the performance evaluation.

In the following, I describe point-by-point the different actions and steps taken in this work, and expose the results at the end.

First, it is important to note that the simple compiler upgrade from Intel 2017 to Intel 2018 changed the behavior of the code, improving the execution time by 10%, while reducing some MPI latencies and slightly modifying the execution profile as shown in Figure 46. This execution time will be taken as a reference for the following improvements.

QNLIN1 is the costliest routine (28% of the execution time). The main hot-spot here is made of 3 nested loops enclosing a series of 6 loops on the same dimension, separated by conditional (but non exclusive) statements. These inner loops, while very well vectorizable, had a bad cache usage that made them run at almost scalar speed, as the data had to be reloaded in the cache at each successive loop. Moreover, The calculations involve memory accesses of neighbours of each node on the different dimensions. Therefore the cache blocking appeared to be a good technique to try in order to improve the data locality.

Cache blocking or **loop blocking** is the transformation of the memory domain of a given problem into smaller chunks, rather than sequentially traversing through the entire memory domain. Each chunk should be small enough to fit all the data for a given computation into the cache, thereby maximizing data reuse.

Table 43: Performance metrics for telemac2d-tomawac-sysphe coupling on the JURECA HPC system.

	Metric name	original	after IO fix	after App Support
Global	Total Time (s)	857	701	519
	Time IO (s)	107	1.99	4.2
	Time MPI (s)	178	173	105
	Memory vs Compute Bound	1.26	1.44	1.36
	Load Imbalance (%)	20	23	19
IO	IO Volume (MB)	9972	9932	9912
	Calls (nb)	584 M	422 K	422 K
	Throughput (MB/s)	93	4997	2361
	Individual IO Access (kB)	0.02	74.15	74.32
MPI	P2P Calls (nb)	1390838	1390838	1390996
	P2P Calls (s)	14	13	7
	P2P Calls Message Size (kB)	1	1	1
	Collective Calls (nb)	306873	306873	306843
	Collective Calls (s)	163	159	97
	Coll. Calls Message Size (kB)	59	59	59
	Synchro / Wait MPI (s)	148	143	86
	Ratio Synchro / Wait MPI (%)	82.73	82.20	80.21
Mem	Memory Footprint	369MB	365MB	375MB
	L3 Cache Usage Intensity (%)	78	78	73
Core	IPC	0.97	0.96	0.94
	Runtime without vectorisation (s)	850	727	582
	Vectorisation efficiency	1	1.04	1.12
	Runtime without FMA (s)	815	702	584
	FMA efficiency	0.95	1.00	1.13

The first tries were successful beyond expectation, resulting in QNLIN1 running 4 to 5 times faster, saving 15% of the total execution time on full nodes. With a tuning benchmark displayed in Figure 45, this gain was maximized to 18%, reducing the execution time from 624 to 519 seconds, with a block size of 16 to 64 iterations.

The new time distribution in the code is as displayed in the new profiling in Figure 47.

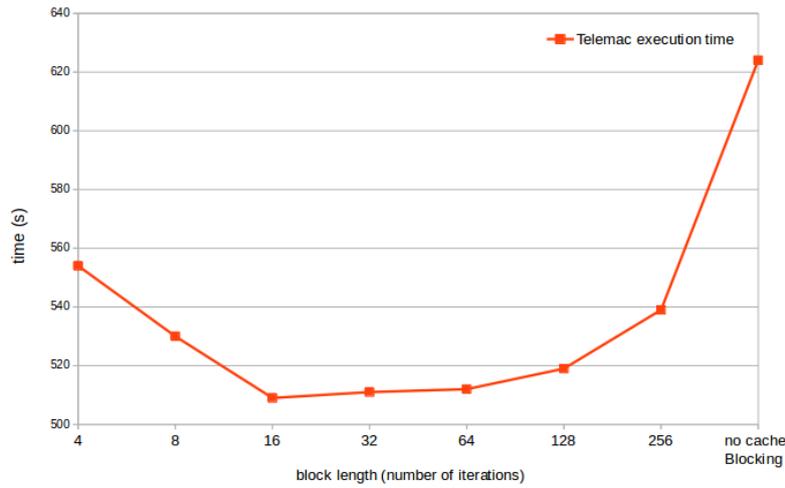


Figure 45: Result of the cache blocking introduced in QNLIN1 on the total run time, benchmark for different block sizes.

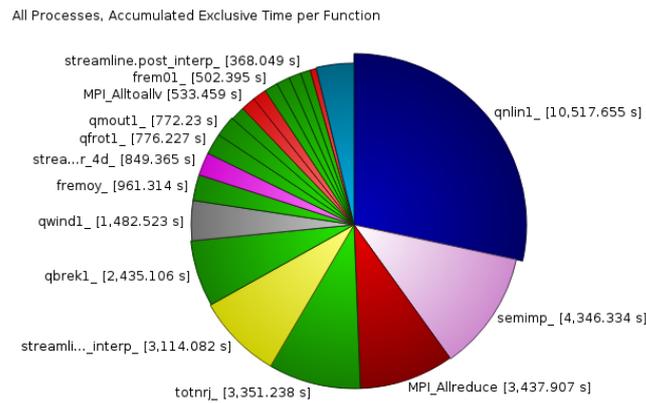


Figure 46: Telemac - Initial time profiling using Scalasca and Vampir visualization - Compiler: Intel 2018.

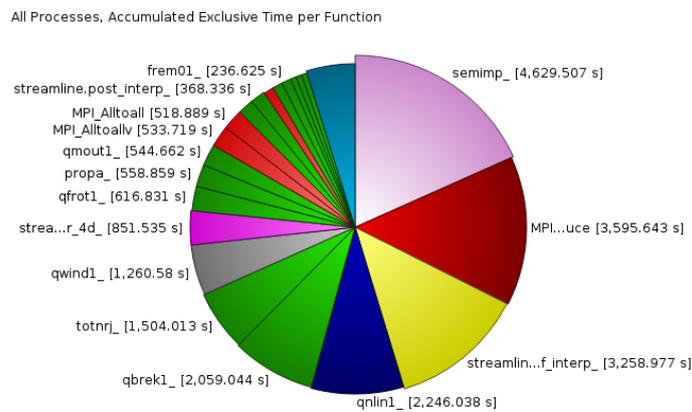


Figure 47: Telemac - time profiling after QNLIN1 optimization - Compiler: Intel 2018.